

Traffic Modeling Using Queueing Theory

"Prince Shaker Street Case"

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ABSTRACT

In this thesis, the problem of sequencing and setting interconnected traffic signals is addressed. Both analytical and numerical models exist for the single intersection problem. The objective is to improve the performance, that is measured in terms of total delay, by incorporating the inter-dependence of the successive signals. Hence, a method was developed for sequencing and timing of the interconnected signals to enable the use of an existing computer package, TRANSYT-7F, designed for finding the time setting of interconnected signals given the required sequence. The method developed in this thesis lead to improving the performance on a selected case study as well as decreasing the required computer time while providing good solution.

بسم الله الرحمن الرحيم

الخلاصة

في هذه الرسالة نناقش مسألة جدولة وتوقيت اشارات المرور المتعاقبة المرتبطة ببعضها البعض ، حيث يتوفر نماذج رياضية وعددية لحل مسألة جدولة وتوقيت الاشارة الواحدة . وتهدف هذه الدراسة الى تحسين مستوى الاداء على الاشارات المرتبطة مقاسا بتوقيت الانتظار الكلي على مجموع الاشارات على التقاطعات .

لقد تم تطوير طريقة لجدولة وتوقيت الاشارات المتعاقبة بحيث يمكن الاستفادة من حزمة برمجيات جاهرة (TRANSYT-7F) والمصممة لاجاد التوقيت الامثل على الاشارات لنظام جدولة محدد لهذه الاشارات ونتيجة لاستخدام هذه الطريقة فقد تم تحسين الاداء على الاشارات في حالة دراسية طبقت عليها هذه الدراسة بالاضافة الى انه امكن تقليل الوقت اللازم لاستخدام الحاسوب والمحافظة على جودة الحل الناتج .

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CHAPTER ONE

Introduction

1.1 Background:

Queueing theory is one of the most important fields of applied sciences that is widely used in a variety of areas such as computer systems, telecommunications, traffic and transportation engineering. The importance of Queueing Theory comes from its applicability and capability to solve real-life problems.

In this research, queueing models have been used to solve traffic problems, especially delay problem. The aspect of minimization of delay is important since it is directly proportional to fuel consumption and pollution of environment. When delay is minimized, more vehicles are allowed to pass a certain point of the road in a given period of time.

1.2 Study Area:

The area under study is Prince Shaker Street. A map of the area is shown in Fig 1.1. The principal reason for choosing this street is the existence on it of five inter-connected traffic signals. Because the goal of this study is to apply operations research methods, especially, the queueing theory and simulation, in order to schedule these traffic signals to have a smooth traffic flow, this street is considered suitable for case study. Other factors that affect the selection of this corridor are:

- 1) This area is one of the fast developing sections in Amman. This can be seen clearly from the large population that moved

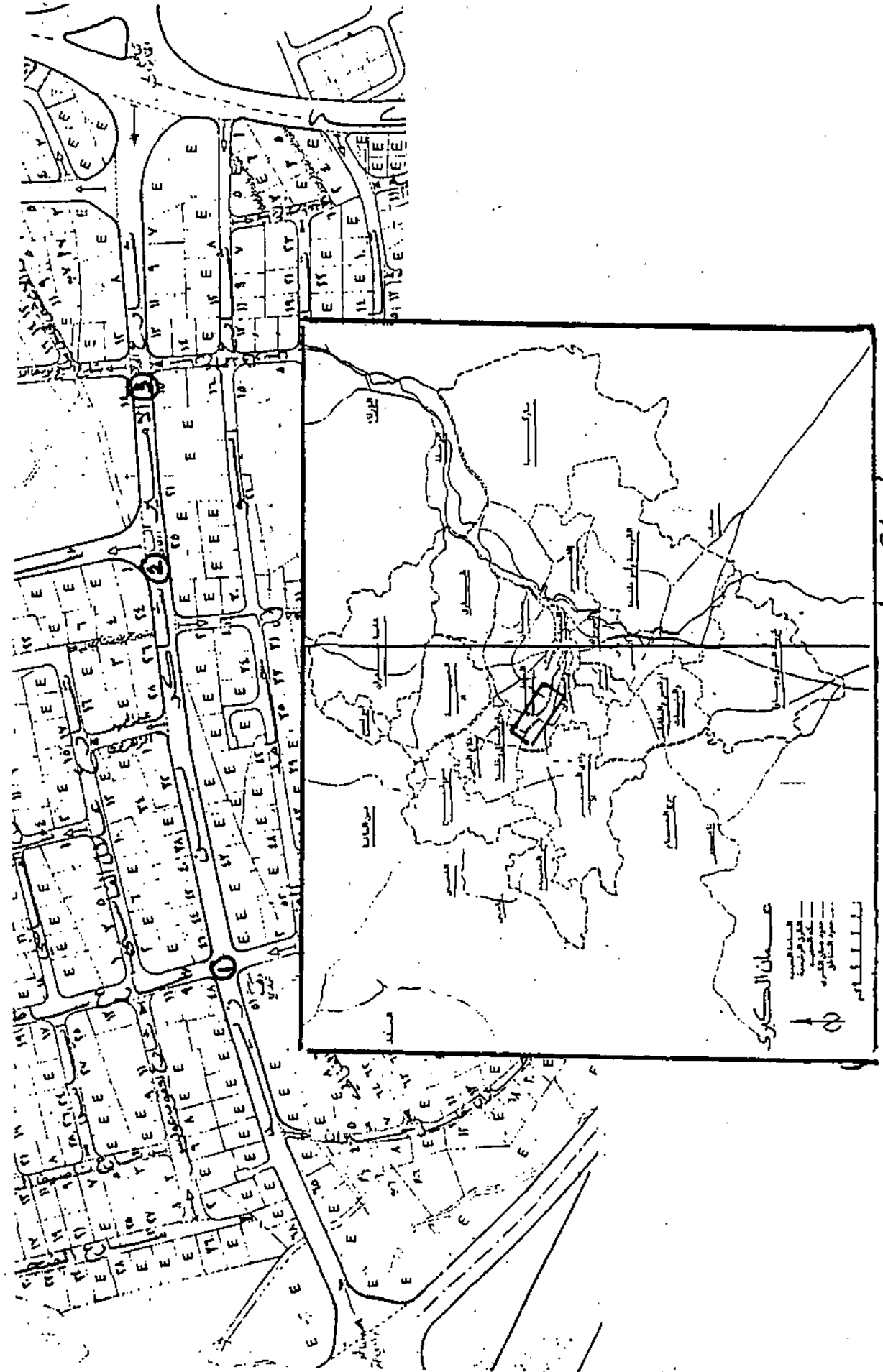


Fig.1.1 Map of area under study

from other parts of Amman to this area.

- 2) Because of the traffic congestion in the center of Amman, which was a result of the increase in the number of vehicles, it was natural for many of the businesses to move outside the center.
- 3) Another characteristic of this area is the existence in it of some centers of attraction, such as restaurants, banks, and governmental departments. These centers attract traffic.
- 4) This area is considered as a major link between several areas in Amman.

Because of all the factors listed, it is not unusual to find that this area has a high traffic volume. For this reason, traffic authorities, including Municipality of Greater Amman, found it necessary to change the geometry of several intersections in that area. An intersection is defined as the general area where two or more highways or streets join or cross each other. Within an intersection are included the roadway and roadside facilities for traffic movements in that area. One of the intersections in this area was previously an at-grade intersection, at which traffic intersects at the same level, was changed later to a multi level intersection -the Mukhabarat interchange-. Another intersection was up-graded from a circle to a signalized intersection, namely, Wadi Sakra intersection.

1.3 Objective:

The objective of the selected case is to study the

traffic flow at Prince Shaker Street between Mukhabarat and Wadi Sakra Intersections, to determine how to get the traffic flow as smooth as possible. To achieve this objective, it is important not to have bottleneck points where traffic congestion occurs. Accordingly, taking into consideration all what has been discussed above, the problem on hand is to "SET SIGNAL SEQUENCE AND TIMING FOR INTERCONNECTED TRAFFIC SIGNALS". Stated differently, the problem is to schedule the separate intersections signal timing so as to eliminate the problem of congestion and delays in traffic flows.

Mathematical analysis and modeling, techniques of systems and control engineering, and computer simulation, are some of the methods that can be used in this problem. When it becomes evident that an intersection has become a bottleneck detrimental to the satisfactory operation of the adjacent highway system, a detailed study of its physical and operational capabilities and limitations must be carried out. Based upon the study, appropriate decisions can be made as to the nature and degree of improvement possible and justifiable.

Signal sequencing can be achieved by modeling the system as queues with service interruptions, which is one kind of queueing systems. Interruption at a given intersection means that traffic signal changes to RED, and a queue starts to build-up at the specified intersection.

Simulation is a powerful analysis and design tool. Once a simulation model is constructed, it acts as an experimentation laboratory in which the impacts of various design alternatives can be carefully evaluated.

The simulation technique has been used in the case this research is dealing with, and Queueing Models, which is the heart of simulation has been applied through a computer package known as TRANSYT-7F, which has a built-in traffic models that uses simulation. This research attempts to use anew algorithm to improve utilization of TRANSYT-7f procedure.

1.4 Overview of the Thesis:

In chapter two, a review of related literature is presented. Chapter three which is titled Research Methodology, included three main parts, the collected data that is needed in this research, the mathematical model that was tested in order to minimize delay, and the simulation technique used in order to find an optimal or near-optimal solution using a computer package named TRANSYT-7F. In chapter four, TRANSYT-7f was implemented and a new algorithm was developed in order to reach the solution in a very short time. Chapter five concluded the research and suggests some ideas for future research topics.

CHAPTER TWO

Literature Review

2.1 General

A number of researchers had investigated problems associated with intersections such as delay of vehicles, and queue at the up-stream of the intersection (the in-coming traffic). Some of those researchers used conventional methods to solve intersection problems like Webster and Pignataro. Others tried to find some new measures that could be used and give global solutions as Shanteau and Taylor. In the following sections, the methods used to solve the problem of congestion and minimizing delay.

2.2 Webster's Formula^(1,2,3)

Webster has developed the following approximate formula for determining the optimum cycle length in terms of minimum delay:

$$C_o = (1.5L + 5)/(1 - \sum y_i) \dots\dots\dots(2.1)$$

where, C_o = optimum cycle length, seconds

L = lost time, seconds

y_i = design flow/saturation flow

The above formula is a simple approximation of a more complicated relationship. In this method, all, or nearly all, of the amber time is assumed to be usable for vehicle movement. To start with, the conflicts between streams are prevented by a separation in time for the different traffic

movements. The procedure by which the streams are separated is known as Phasing the Traffic. Each phase should not have any intersecting (conflicting) traffic. The number of phases employed at any intersection should be kept to a minimum. In Jordan, left-turns on red are prohibited. So, the left-turners could not turn between gaps of the opposing traffic. Therefore, a special phase for left-turn movements is to be introduced.

The capacity of approach, which is the leg of intersection having traffic movement, is affected by two factors, geometric and traffic factors. These two factors are discussed below.

2.2.1 The Geometric Factor

This factor includes lane width, gradient, and radius of turning movements. The saturation flow, which is the flow in vehicles per hour which would be obtained if there was an infinite queue of vehicles and given a 100 per cent green time, is an important factor in designing the intersection, since it is dependent on geometric parameters. For the unopposed traffic streams, the saturation flow is given by:

$$S_1 = (S_0 - 140d_n)/(1 + 1.5 f/r) \dots\dots\dots(2.2)$$

where,

S_1 = saturation flow for unopposed streams, pcu

$$S_0 = 2080 - 42d_g * G + 100 (w - 3.25)$$

d_n = is 1 for nearside lanes and 0 for non-nearside lanes

d_g = is 1 for uphill entries and 0 for

downhill entries.

f = is the proportion of turning vehicles in the moving traffic lane

r = is the radius of curvature of vehicle paths, meters

G = is the percentage gradient for the entry lane

w = is the lane width at entry, meters

For opposing traffic streams (which is not considered in Jordan), saturation flow S_2 is given by

$$S_2 = S_g + S_c \dots\dots\dots(2.3)$$

where, S_2 = saturation flow for opposing streams

S_g = is the saturation flow in lanes of opposing mixed turning traffic during the effective green period (pcu/hr)

S_c = saturation flow in lanes of opposed mixed turning traffic after the effective green period (pcu/hr).

2.2.2 The Traffic Factor

This is the second factor that affects the approach. This is mainly introduced by the use of weighting factors, referred to as passenger car units ,pcu's, which is a representation of larger vehicles, such as trucks and buses, as equivalent to a number of passenger cars to be used in Level of Service and capacity analysis. The magnitude of the equivalency is

dependent upon vehicle size and weight, vehicle operating characteristics, vehicle speeds, and roadway characteristics, such as gradient. Important traffic factors that affect capacity of the approach are:

1) Determination of effective green time. This factor indicates the number of vehicles that could cross a stop line over the whole cycle, comprising red, green, and yellow (or amber) intervals.

2) Lost time occurs due to starting delays, while some vehicles cross the stop line during the amber interval either before or after the actual green phase. This measure, lost time, is considered in design of capacity. It can be calculated as shown in the following formula:

$$\text{Effective green time} = \text{actual green interval} + \text{amber interval} \\ - \text{lost time} \dots \dots \dots (2.4)$$

3) Cycle length. In order to find the optimum cycle length, a new measure is defined. The y -value, which is the flow on the approach divided by the saturation flow, is a measure that gives an indication about how green time should be split. Then, the sum of the maximum y -values for all approaches, Y , is considered in finding the optimum cycle length, C_0 . This is found experimentally by simulation of flow at different traffic signals as shown in equation:

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$$C_0 = (1.5 L + 5)/(1 - Y) \dots \dots \dots (2.5)$$

This optimum cycle length would result in minimum overall delay when employed with fixed time signals and should result in waiting vehicles clearing the intersection. Then, the effective green time is divided by the phases in the ratio of the y_{max} of each phase.

The effective green period could not be taken simply as measured. It depends also, as stated earlier, on the geometric factors of the approach. For example, when the width of approach is wide, the effective green for that approach could be recalculated taking into consideration the saturation flow, actual flow, and approach width.

The length of queue at any approach at the beginning of the green period could then be found easily. Two cases are possible:

a. Unsaturated green period: where the queue disappears during the green period before the green signal-phase changes to amber. The following equation finds the number of vehicles in the queue:

$$N_u = q r \dots\dots\dots(2.6)$$

where, N_u = initial queue at the beginning of
the unsaturated green period, pcu

q = flow (pcu/sec)

r = effective red (sec)

b. Saturated green period: where, the queue builds up and does not disappear before the start of the amber interval. In this case, the delay is a major element in order to find the

length of queue that should be considered, as in the following equation:

$$N_s = \max \left\{ q \left(\frac{r}{2} + d \right) \left(1 + \frac{qj}{av} \right) , qr \left(1 + \frac{qj}{av} \right) \right\} \quad (2.7)$$

where,

N_s = initial queue at the beginning of
a saturated green period, pcu

q and r = as defined previously

d = average delay per vehicle (sec)

a = number of lanes in queue

j = average spacing of vehicles in
queue

v = free running speed, m/sec

As mentioned before, this method was developed mainly under the assumption of getting minimum delay. The average delay per vehicle on a particular intersection could be calculated as follows:

$$d = cA + (B/q) - C \quad \dots\dots\dots(2.8)$$

where, d = minimum delay, sec

c = cycle length, sec

$A = (1-\lambda)^2 / 2(1-\lambda x)$

$B = x^2 / 2(1-x)$

$C = 0.65(c/q^2)^{1/3} x^{(2+5\lambda)}$, correction
factor

λ = proportion of cycle that is

effectively green

$x =$ degree of saturation " $q/s\lambda$ "

$q =$ flow, pcu/sec

This average delay per vehicle is used to find the total delay (D) for the intersection as follows:

$$D = \sum (\text{average delay per veh.}) * \text{flow} \dots\dots(2.9)$$

By differentiating this total delay with respect to cycle time C, and setting the derivative to zero, the optimum cycle length, C_o , is then as follows:

$$C_o = 2LF/1-Y \dots\dots\dots(2.10)$$

where, L = total lost time per cycle

$$F = 1 + \frac{\sqrt{[Y^2 - Y + 1/E] - Y}}{2}$$

$$E = \frac{L(1+Y)^2}{16 n Y^5} \sum_{i=1}^n \frac{y_x S_x}{1-y_x} [4(Y-y_x)^2 - Y^2(1-Y)^2]$$

$Y = y_{\max}$ over all phases, which is the ratio of design flow to the saturation flow

2.3 Pignataro's Method (1,3)

Pignataro has suggested a method that is used widely nowadays in the signalization of intersections. In this method, the first step is the phasing of traffic.

Intersections of more than four approaches may require a division of the cycle time into more than two phases, which, in general, should be avoided, since each additional phase lengthens the overall cycle. This may result in increasing delay.

In this method, for the timing of traffic signals it is extremely desirable to consider the variation in traffic flow during the peak hour. A peak 15-minute period is considered to be the shortest practical time to express this variation. The peak hour factor (PHF) is defined as the ratio of vehicles entering the intersection during the peak hour to four times the number of vehicles entering during the peak 15-minute period. Left turning vehicles and commercial vehicles require more green time than do straight or through passenger cars. One method of addressing this problem is treated in the following paragraph.

The procedure used in this method to account for the determination of commercial vehicles, and turning movements on the time of start up, or average headway, in the determination of cycle time, is to convert the demand volume, given in mixed vehicles per hour with percentage of commercial vehicles and left-turns (which is not considered here in Jordan), to an equivalent volume in straight passenger cars. This procedure develops passenger car equivalent (pce) for all demand volume.

Under this procedure, each non-left turning passenger car is equal to 1 pce each. Buses and trucks are assumed to be each equal to 1.5 pce. This is based on the finding that each left-turn movement consumes 1.3 seconds of additional time.

Since the minimum departure headway is 2.1 seconds, it can be shown that:

$$1 \text{ left-turn} = (2.1 + 1.3)/2.1 = 1.6 \text{ pce}$$

Vehicle clearance interval, which is the required sufficient time for vehicles to clear the intersection before cross traffic starts to move, is a very important measure that is considered in the sense it incorporates a safe stopping distance. The Traffic Engineering Handbook⁽⁹⁾ recommends the following formula:

$$Y = t + \frac{V}{2a} + \frac{(w + l)}{V} \dots\dots\dots(2.11)$$

where, Y= clearance interval, in sec

t= perception-reaction time, in sec,

suggested value = 1.0

V= approach speed of clearing vehicle,
in ft/sec

a= deceleration rate of clearing
vehicle, in ft/sec², suggested value
= 15

w= intersection width in ft

l= length of vehicles in ft, suggested =
20

This formula is based on a coefficient of anti-skid friction of about 0.5.

The goal of Pignataro's method is finding the appropriate

cycle length. In general, the calculated minimum cycle length will be checked against the following requirements:

$$C_{min} = \frac{Y_1}{1 - [N_1 S_1 / 3600 (PHF)]} \dots (2.12)$$

where, C_{min} = minimum cycle length, seconds

N_1 = critical lane volume, the number of vehicles in a single lane entering the intersection during the peak hour, pce.

S_1 = approximat average headway between vehicles entering the intersection

Y_1 = vehicle clearance interval in sec

PHF = peak hour factor

This minimum length is split between the different phases in proportion to the relative critical lane volumes. The green time for each approach is checked. Cycle failure is addressed indirectly by requiring that the peak 15-minute volume for each leg be accomodated in the green time available to that leg in the peak 15-minutes; that is, it is required that, for all approaches,

$$\frac{N_1 S_1}{4 (PHF)} < \frac{900}{C} G_1 \dots (2.13)$$

where, N_1 and S_1 = as defined previously

PHF = peak hour factor

C = cycle length, seconds

G_i = available green time for phase i

constant 900 = number of seconds in
15 minutes.

2.4 Shanteau's Method⁽⁴⁾

Shanteau developed a new method for measuring the saturation flow and lost time. This method depends mainly on constructing some curves. The importance of the saturation flow comes from the fact that the number of vehicles that cross the intersection in the green phase is dependent upon green interval. Previously, the number of vehicles were calculated using the following equation:

$$N(t) = s (t - L_s) \dots\dots\dots(2.14)$$

where, s = saturation flow, vph

t = time that allows vehicles cross
the intersection, seconds

L_s = starting lost time, seconds

The new method presented by Shanteau assumes that the number of vehicles to enter the intersection in one phase is not simply $N(G)$, where G is the green time, because vehicles continue to enter for some time after light turns yellow. The amount of yellow time (Y) that is effectively unused is the ending lost time L_e , so the number of vehicles to enter in one saturated phase of length $G+Y$ is:

$$N(G+Y) = s (G + Y - L_s - L_e) \dots\dots(2.15)$$

and, if the total lost time is $L_s+L_e = L$, then

$$N(G+Y) = s (G + Y - L) \dots\dots\dots(2.16)$$

By calculating the number of vehicles which have cleared the intersection, the number of vehicles that are still in the queue at the signalised intersection can be determined.

2.5 Taylor, et al Approach ⁽⁵⁾

In their paper titled "Queue volume: a measure of congestion", Taylor, et al used a new approach for identifying the traffic performance. This approach mainly uses the traffic detector data to identify the congested situations. The new measure is named the "degree of congestion". In some previous work, the queue length was considered. It seeks to minimize the sum of the queue lengths on each arm of an intersection or over a network. In another work, the "free capacity" on the link, which is the difference between the link length and the queue length, was considered as a measure of traffic congestion. The new measure of congestion developed by Taylor is the "Queue Volume". This measure is based on the level of queueing, and on the length of time a queue persists. The advantage of this measure is that it provides a time dimension reflecting the proportion of the cycle for which a given queue was at or close to the maximum. This means that when the maximum queue is equal to the link

length, queue volume continues to increase. However, queue volume is a better estimator than maximum queue length, particularly at periods of high delay. This measure was tested against traffic density and vehicle time-of-occupancy, and high a correlation was found. As a result of this study, and because this measure gives a time dimension to the queue length, it represents the true behaviour of traffic flow more accurately than the existing methods using queue length. Finally, queue volume should be considered in improving the operation of vehicle-responsive signal control.

2.6 Lin's et al Findings⁽⁶⁾

Lin et al pointed out the three basic requirements that should be satisfied by a queue dissipation model developed for simulation analysis of signal operations. First, the model should provide a realistic representation of the probabilistic characteristics of queue discharge times or headways. Second, after the green onset, queued vehicles will enter and occupy a specified space in the approach lane for different lengths of time. The model should provide a realistic representation of the probabilistic characteristics of such dwell times. And, finally, the model should be sufficiently flexible that it can be conveniently calibrated for varying conditions.

In his study, Lin used a simple car-following model to reproduce queue dissipation characteristics. In this model, the following assumptions are made:

(1) A driver would assume that at any instant the vehicle immediately ahead has the possibility of decelerating at a

rate E and coming to a stop.

(2) a driver would adjust the vehicle speed continuously so that an acceptable deceleration rate KE can be applied to achieve a safe stop if the vehicle ahead decelerates at the expected rate E and comes to a stop.

Based on these assumptions, the driver behaviour can be represented as:

$$B = \frac{-(2V_2 - hKE) + Q}{2h} \dots\dots\dots(2.17)$$

where, B= constant rate of speed change of following vehicle

V_2 = speed of the following vehicle E = deceleration rate of vehicle 1, < 0

K = a positive constant representing the degree of risk a driver is willing to take

h = a small time interval

The inputs to the simulation model include the following traffic characteristics: vehicle length, vehicle type, driver reaction time in response to the green onset, speed, and spacing between stopped vehicles. This study concluded that the driver reaction time can assume a constant value. The length of each vehicle does not have to be treated separately.

Instead, the average length of each vehicle type (passenger cars, trucks, busses, etc) could be taken to represent the lengths of individual vehicles. The spacing between stopped

vehicles can be represented by a constant value. The probabilistic nature of steady state speeds and the variations of the K factor due to behavioral differences among drivers should be considered well.

2.7 Srikar and Vinod's Method⁽⁷⁾

Srikar and Vinod constructed a closed queueing network performance model at American Airlines to evaluate the performance of large complex flow shops. This model, which was named QNET, estimated the performance and capacity of job shops using a network of queues models. The reason of using these queues models is three-fold: (1) extensive data for simulation is needed, (2) violation of theoretical assumptions, though queueing networks proved to be good tools to deal with such situations, (3) simulation models are time consuming, so, queueing models proved to be ideal.

QNET model, although it is built mainly to find the capacity and performance of a landing gear shop, it can be applied in the traffic modeling for the following reasons:

1. the model consists of a closed queueing network with a finite number M of work stations (traffic signals are considered as work stations)
2. first-come-first-served (FCFS) or infinite-server (INFS) queue disciplines can be simulated (FCFS, could simulate the queue before the traffic signal if the signal is red. INFS, could simulate the transit time on the road between two traffic signals)
3. each work station i may have one or more identical

machines, c_i , with a service time distribution that is exponentially distributed (each intersection has four legs -approaches-, and each approach has three movements, through, left, and right turn. Each movement could be considered as a machine c_i)

4. jobs that have distinct process plan are classified as a distinct job class. R job classes with distinct work-in-process (WIP) levels are considered in this model (each vehicle type -bus, car, truck ...etc- could be considered as a job class. Clearance time of the vehicle -time to cross the intersection while the signal is green- could be considered as the WIP time)
5. the needed data to process each job is σ_i and μ_i (variance and mean)
6. concerning memory requirements, QNET was tested and found accurate for large problems, $M=50$ and $R=200$ (maximum of 50 traffic signals and 200 of vehicle types)
7. breakdown and repair of unreliable work stations are allowed in this model (breakdown represents a red signal, and service represents a green signal)

The output of QNET model is very important in so many ways. It echoes the input data: the work station summary, the process plans and work load summary by part type. The performance characteristics about the system are provided also. These performance characteristics are:

1. average queue length. This measure could point the minimum total delay concerning the intersection

2. average waiting time (including service)
3. utilization, which can give a clear idea about the usage of green signals
4. identify bottleneck stations, where this can point the intersections that are considered as a bottlenecks.

CHAPTER THREE

Research Methodology

The mathematical model which is represented by Webster's equation has been investigated in order to figure out if it can be applied on the case of Prince Shaker street. Then, a simulation and optimization tool has been used to describe the flow of traffic as a function of signal phasing and then find an optimal or near-optimal solution to the case we are dealing with. Data for the current flow in Prince Shaker Street has been collected.

The following reasearch stages have been done:

3.1) Data Collection:

Traffic data were collected at the different intersections considered in this research as shown in Fig 1.1. Data consisted of the traffic counts for each direction an for each movement, i.e. left and right turns and through traffic. Data collected consist also of the existing signal phasing for the different periods. The distance between each intersection, and the average running speed of vehicles are known (see Fig 3.1).

Traffic data were taken from the Municipality of Greater Amman. It includes the traffic counts at each single intersection. These data were taken each 15-minute period. Counts were taken for the morning peak from 7:30 until 9:30 a.m. Data were also taken for the off-peak period where the traffic was counted from 12:00 until 2:30 in the afternoon. For a third period, which is the evening peak, traffic was

counted from 4:00 until 6:00 p.m.

The collected data were not considered sufficient. So, further counts were made in order to find the turning movements, which are of great importance, since they affect the phasing and timing of each signal, and also, they affect delay, which is an important issue in finding the optimal cycle length. All data are shown in Appendix C.

3.2) Mathematical Model:^(1,2)

As can be seen from the literature review, many researchers discussed the issue of traffic flow under certain conditions such as vehicle delay, formation of queues, non-smoothness of flow, and congestion.

The delay model that was developed by Webster has been tested in order to find delay, which is the major factor that affects the cycle length. In Webster's model, the optimum cycle length C_0 would result in minimum overall delay when employed with fixed time signals, such as in the case we are dealing with. The average delay per vehicle on a particular arm is given by:

$$d = \frac{c(1 - \lambda)^2}{2(1 - \lambda x)} + \frac{x^2}{2q(1 - x)} - 0.65 \left(\frac{c}{q^2} \right)^{1/3} x (2 + 5\lambda)$$

where, d = average delay per vehicle, sec

c = cycle time, sec

λ = proportion of the cycle that is

effectively green for the phase under consideration, g/c

q = flow, veh/sec

s = saturation flow, veh/sec

x = degree of saturation, which is the ratio of actual flow to the possible flow "effeciency" it equals to $q/s\lambda$

3.2.1 Calcualtion of Delay:*

Using the above equation, and using the signals phasing of Prince Shaker Street that is introduced from the Municipality of Greater Amman, delay was found. The following tables present the results achieved.

Table 3.1 Tabulation of data taken from Municipality of Amman for Prince Shaker Street, seconds.

SIGNAL	ACTUAL GREEN	AMBER RED	AMBER	ALL RED	EFFECTIVE GREEN	RED
1	12	1	3	1	16	83
2	33	1	3	1	37	62
3	13	1	3	1	27	72
4	22	1	3	1	26	73
5	56	1	3	1	60	39
6	23	1	3	1	27	72
7	34	1	3	1	38	61
8	28	1	3	1	32	67
9	43	1	3	1	52	47
10	19	1	3	1	23	76
11	43	1	3	1	52	47
12	23	1	3	1	27	72

* Appendix B contains a program that calculates delay using Webster's method

Table 3.2 Calculations of the different variables of delay equation

Signal	Width (m)	S Veh/H	s Veh/S	Flow Veh/H	q Veh/S	g sec	λ g/c	λs	x
1	3.6	1900	0.528	340	0.094	16	0.16	0.084	1.118
2	4	1950	0.542	1193	0.331	37	0.37	0.200	1.653
3	3.4	1880	0.522	321	0.089	27	0.27	0.141	0.632
4	4.6	2250	0.625	637	0.177	26	0.26	0.163	1.089
5	4.3	2075	0.576	854	0.237	60	0.6	0.346	0.686
6	2	1100	0.306	360	0.100	27	0.27	0.083	1.212
7	4.8	2420	0.672	819	0.228	38	0.38	0.255	0.891
8	4.5	2215	0.615	475	0.132	32	0.32	0.197	0.670
9	4.4	2150	0.597	1402	0.389	52	0.52	0.311	1.254
10	2	1100	0.306	307	0.085	23	0.23	0.070	1.213
11	4.4	2150	0.597	877	0.244	52	0.52	0.311	0.784
12	4	1950	0.542	517	0.144	27	0.27	0.146	0.982

Table 3.3 Delay for each approach using Webster's equation, seconds

Signal	Uniform	Random	Empirical	Delay
1	42.96	-56.34	19.940	-33.32
2	51.009	-6.32	43.650	1.039
3	32.13	6.09	3.230	34.99
4	38.19	-37.64	12.670	-12.12
5	13.59	3.16	1.190	15.56
6	39.61	-34.64	26.650	-21.68
7	29.05	15.97	5.150	39.87
8	29.42	5.15	2.750	31.82
9	33.11	-7.95	16.030	9.13
10	41.12	-40.63	28.660	-28.17
11	19.45	5.83	2.520	22.76
12	36.26	186.02	10.330	211.95

3.2.2 Total Delay of the Intersection:

In this section, total delay will be calculated using the method described in Road Research Technical Paper 39. The total delay for the intersection is given by:

$$D = \sum (\text{average delay/vehicle}) * \text{flow}$$

So, using this equation, and using the aforementioned data, total delay for each intersection is found to be as follows:

$$D_{\text{Wahbi}} = -1.79$$

$$D_{\text{Flying}} = 14.81$$

$$D_{\text{Gardens}} = 36.17$$

From the previous tables, it can be seen that there are some delay values that have negative signs. In order to understand this situation, Webster's equation will be analyzed.

As it was stated before, delay "d" depends mainly on the effective green and saturation flow, considering constant cycle time and flow. Saturation flow, s , of the approach, is the uniform departure of traffic in a specific lane depending mainly on many factors. Some of these factors are: lane width, grade of the approach, existence of a parking lane, a bus stop, and pedestrian crossings. On the other hand, effective green time of an approach depends mainly on the traffic flow on that approach. Also, it depends on the y -value, i.e. the ratio between design flow and saturation flow, which in turn depends on saturation flow. The term "degree of saturation", which is dependent on flow, saturation flow, effective green, and cycle length, should not exceed unity. This is because it represents efficiency. In our case, it was found that some approaches have a degree of saturation, x , greater than unity. This can be explained in many ways. First, since as stated before, saturation flow depends on lane width, more than one vehicle occupy that

width. This means that this lane releases more vehicles than it was designed for. Second, the green of the signal at such an approach is not phased adequately. In other words, green time is not enough to clear that specific approach. Finally, the traffic behaviour which the equation considered is not the same in Jordan. So, a new equation, or a correction factor needs to be added in order to suit existing traffic behaviour.

Another way of tackling the case is the Simulation technique. This has been used. A full description is presented in the next section.

3.3) Simulation Technique: (8,9,10)

As it can be seen from the mathematical model that had been tested, calculations of delay using Webster's model showed unreasonable values since there were some negative values. Webster's model is plotted in Fig 3.2.

It can be seen that, as the degree of saturation approaches and then, exceeds 100%, the model is not applicable. In common uses, the model is only considered valid for a degree of saturation up to about 95%.

There are many factors that affect delay; among them are:

- 1) Physical factors, such as the number of lanes, grades, approach width, access control, channelization and transit (bus) stops.
- 2) Traffic factors, such as volume on each approach, turning movements, vehicle classification, driver characteristics, approach speed, parking and number of pedestrians.
- 3) Traffic controls, such as types and timing of signals,

stop or yield signs, and turn and parking controls.

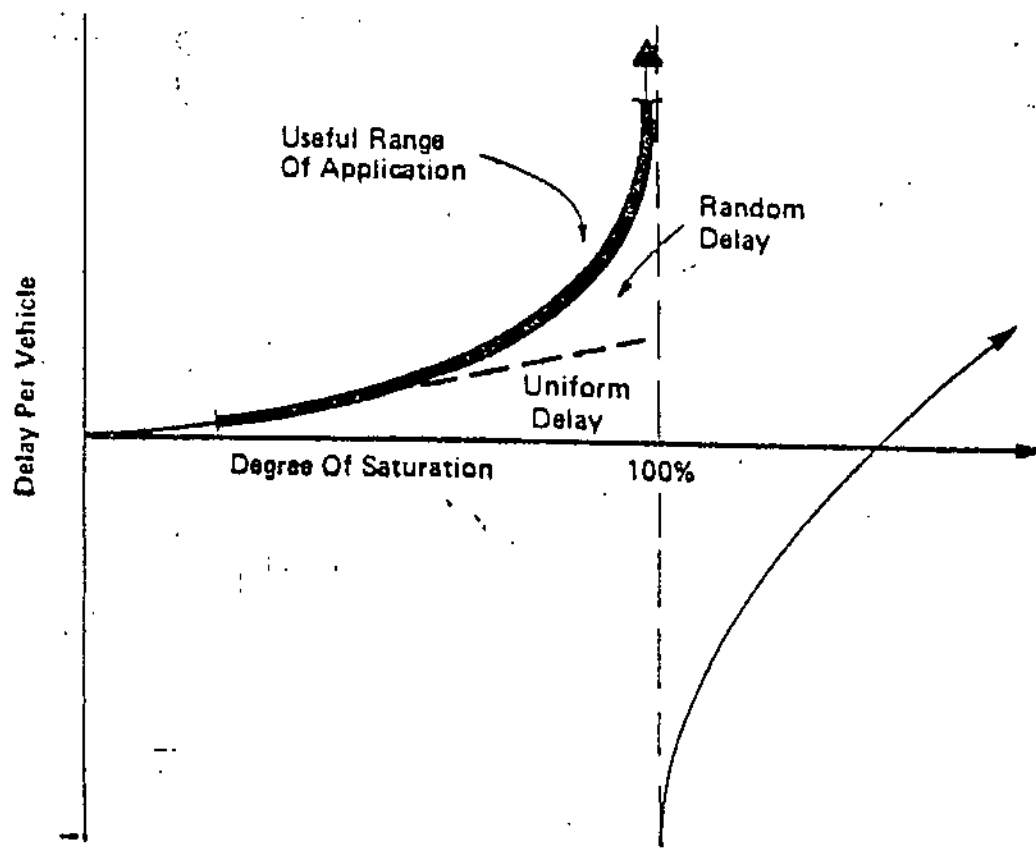


Fig 3.2 Webster's delay model

(Source: TRANSYT-7F, User's Manual, Rel. 6, 1988)

As it was stated before, the objective of this research is to "Set Signal Sequence and Timing for Interconnected Traffic Signals". This means that there should be a cycle length that gives a good performance to the system, and though, minimum delay, which is the most important factor that affects driver behaviour in terms of respecting traffic control, and in terms of comfort of driver. This can be achieved in different ways. Among these, vehicle can travel and cross different intersections with either no or minimum stops. So, a perfect progression, which allows no stops, is the case which provides largely non stop operation, with flow rates approaching 2000 passenger cars per hour of green per

lane. This type of operation can be attained where there are relatively few turning movements, with all signal cycles being very close to fully loaded, and with no mid-block frictional elements. It is susceptible to abrupt breakdown whenever any abnormality in the traffic flow develops.

In order to reach a smooth traffic flow in the system, and because delay is a major issue that affects the smoothness of flow, and because the factors that affect delay are too complicated, especially when the saturation flow exceeds 95%, where Webster's Model cannot handle the problem, it can be seen that the most appropriate method to deal with the existing situation we are studying (Prince Shaker Case) by the use of SIMULATION.

Two existing computer packages have been tested in order to find the most suitable one that can handle the case. These packages are GPSS-PC, and TRANSYT-7F. A brief description of each of these packages would be of great importance in the selection of the most suitable package.

3.3.1 GPSS-PC^(11,15)

GPSS is a simulation programming language, used to build computer models for discrete-event simulations. GPSS contains special features for reproducing the dynamic behaviour of systems which operate in time, and in which changes of state occur at discrete points in time. GPSS needs the analyst to build his/her own model using the blocks and statements built-in this language. This package had been tested on a small case. When it was compared with TRANSYT-7F (will be

discussed later), it was found that TRANSYT-7F would be much more useful since it has the option of simulation and optimization, and was tested in many places and found sufficient.

3.3.2 TRANSYT-7F^(8,12)

TRANSYT-7F is one of the most popular traffic flow analysis and signal timing programs. This program optimizes the signal settings to reduce fuel consumption, delay and vehicle stops. This program, TRANSYT-7F, has two major functions, Simulation of traffic flow and Optimization of traffic signal timing plans.

1) The first major function, simulation of flow of traffic in a signalized network, is an analytical process that attempts to represent real world events. The traffic flow model in TRANSYT is among the most realistic models in many ways. This model considers platoons of vehicles rather than individual vehicles. Also, its representation of traffic is more detailed than other models because it simulates traffic in small time increments. This model utilizes a platoon dispersion algorithm that simulates the normal dispersion of platoons as they travel downstream. Another important consideration is that it considers traffic delay, stops, fuel consumption, travel time and traffic signal timing plans.

2) The second major function of TRANSYT-7F, is the development of an optimized traffic signal timing plan. TRANSYT optimizes phase length. To determine the best cycle length, an evaluation of a specified range of cycle lengths

may also be made. When optimizing, TRANSYT-7F minimizes an objective function called Performance Index (PI). The PI is either a linear combination of delay (where TRANSYT-7F bypasses the problem of degree of saturation when it exceeds 100% as shown in Fig 3.3), stops, and (optionally) excessive maximum back of queue, or excess operating cost.

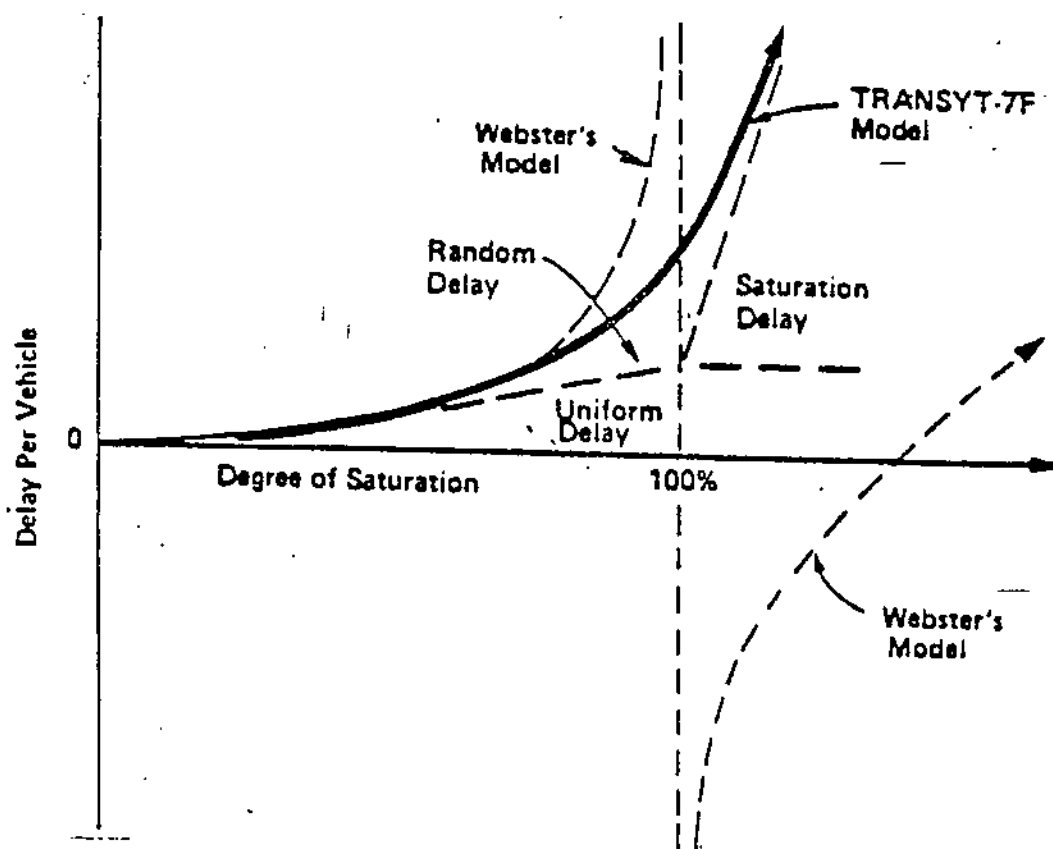


Fig 3.3 TRANSYT-7F estimate of delay

(Source: TRANSYT-7F, User's Manual, Rel. 6, 1988)

The delay/stops PI is defined as follows:

$$PI = \sum \{ (w_{d1} d_1 + K w_{s1} S_1) + u_1 (w_{d1-1} d_{1-1} + K w_{s1-1} S_{1-1}) + B_1 (W_q [q_1 - c_1]_2) \}$$

where, d_1 = delay on link i in vehicle-hour (and

$i-1)$

K = a user input coefficient to express the importance of stops relative to delay

S_i = stops on link i (and $i-1$) in stops/sec

$w_{x,i}$ = link specified weighting factors for delay (d) and stops (S) for link i (and $i-1$)

B_i, u_i = binary variable associated with card type 34 (used by TRANSYT)

w_q = network-wide penalty applied to the excess queue "spillover"

C_i = maximum back of queue "capacity" for link i

From the previous discussion, it was concluded that TRANSYT-7F program is the most suitable package to use for this study.

3.4 Methodology of TRANSYT-7F: (8)

As it can be seen from the previous section, TRANSYT-7F appears to be a good tool that could be used to analyze the case we are dealing with. In this case, three intersections are located apart, in an area that shows some sort of congestion as shown in Fig 1.1. In the peak times, and in many cases, the signal timing plan cannot clear the intersection.

In order to analyze the case and to find an optimum solution, the following requirements are of great importance

- 1) General requirements before starting the analysis
- 2) Data collection requirements
- 3) Optimization requirements

3.4.1) General Requirements: (18, 20)

As it was stated in the main objective, the goal of this study is to set a signal timing plan and a phase sequence. This implies two-fold criteria, first is to find the plan that gives a minimum system-wide operational delay and fixed delay.

Operational delay can be defined as that delay caused by interference between components of traffic, that is, delay due to influences of other traffic. One type of operational delay is caused by other traffic movements that interfere with the stream of flow (side frictions). This includes parking or unparking vehicles, pedestrians, stalled vehicles, double parking, and cross traffic. A second type of operational delay is caused by interferences within the traffic stream (internal friction). This includes congestion due to high volumes, lack of roadway capacity, and merging or weaving maneuvers.

Fixed delay, which is the second type of delay that affects the system, is the delay caused by traffic control devices. It is the delay to which a vehicle is subjected regardless of the amount of traffic volume and interference present, and it occurs primarily at intersections. It may be caused by traffic signals, stop signs, yield signs, and any other control device.

The second point of the criteria is the cycle length

constraints. These constraints are very important since they are very much related to the signal plan. The following are some of these constraints:

- a) the cycle length must be long enough to provide sufficient minimum times for all phases considering both vehicle and pedestrian requirements.
- b) the cycle length should be sufficiently long to ensure that no movement is saturated, if possible. That is, the degree of saturation should be less than 100% for all approaches, at all intersections. This constraint results in a higher value for cycle length than does the previous one.
- c) the cycle length should not be so long as to cause unacceptably high delays. In some studies, the maximum cycle length at which the user starts not to respect the signal was shown to be 120 seconds.
- d) in a progressive system, the cycle length should be chosen to facilitate traffic progression.

3.4.2) Data Requirements:

The data required for running TRANSYT-7F is shown in Table(3.4).

Traffic data which concern the volumes and timing plan are taken from the records of the Municipality of Greater Amman. Turning movements, on the other hand, were not included. Therefore, 15-min counts were conducted in order to figure the different movements on each approach.

Table 3.4 Summary of input data requirements to run model

Major Category	Data Types
Network Data	<ul style="list-style-type: none"> - Nodes (intersections) - Links (streets) - Link distances (stopline to stopline) - Turning restrictions
Timing Data	<ul style="list-style-type: none"> - Existing cycle lengths - Existing offsets - Existing interval durations and phase lengths
Saturation Flow	<ul style="list-style-type: none"> - Saturation flow
Speed Data	<ul style="list-style-type: none"> - Cruise speed on links
Volume Data	<ul style="list-style-type: none"> - Total volume counts - Turning movement counts - Link-to-link movements

(Source: TRANSYT-7F, User's Manual, Rel. 6, 1988)

This short count is justified as Pignataro states: "in many cases, manpower, time, and financial limitations may rule out the feasibility of taking long counts. Manual counts have an advantage over machine counts in that the manual counts give classification and turning movements. The short count method involves counting for periods of 5,6,10, or 12 minutes at each location or intersection."

Input Data: (e)

Data required to run TRANSYT-7F can be summarized in the following steps:

- 1) Each intersection is represented as a node, and each movement at this node is considered as a link as shown in Fig 3.4. Each node in the network is given a number, and the same thing is done with links.

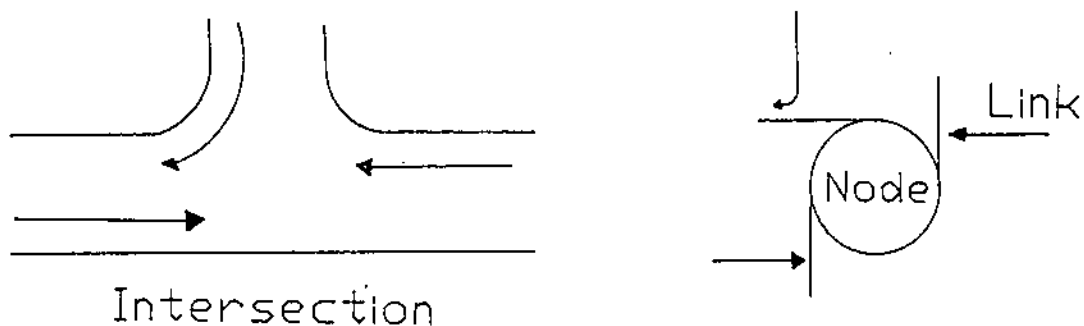


Fig 3.4 Representation of a node

- 2) Saturation flow for each link is figured out. The following table shows the effect of approach width on saturation flow

w (ft)	10	11	12	13	14	15	16	17
s(pcu/h)	1850	1875	1900	1950	2075	2250	2475	2700

Values in this table are given by the following equation:

$$s = 160 w \text{ pcu/hr}$$

There are some correction factors that affect saturation flow, but we are not interested in them because none of them applies to the case we are dealing with.

- 3) The link length, which is the length between stop lines of two following intersections is measured.
- 4) Timing plan and sequence for each intersection is figured out. These data are referred to the existing (installed) plan. The timing plan should add-up to the cycle length that is installed.
- 5) Average speed could be found by spot speed studies. In the case we are dealing with, the average speed is considered to be 35 Km/hr, since the design of the progression system that is installed assumes this value of speed.

- 6) Traffic counts for each intersection were taken each 15 minutes. The period that we are interested in for the study is the morning peak hour, between 7:30 a.m. and 8:30 a.m.

Because the turning movements are an important issue in the analysis, and since the available counts do not include all the movements, additional counts were made to find out the percentages of turning movements to the total volume. Approach volumes are split into their components: through, right turn, and left turn movements.

- 7) Design hourly volume is found by figuring out the maximum half-hour volume of each approach multiplied by two.
- 8) Components of volume of each link are found -i.e., the link volumes of the preceding intersection that compose a link in the intersection being considered are found. An example is shown in Fig 3.5

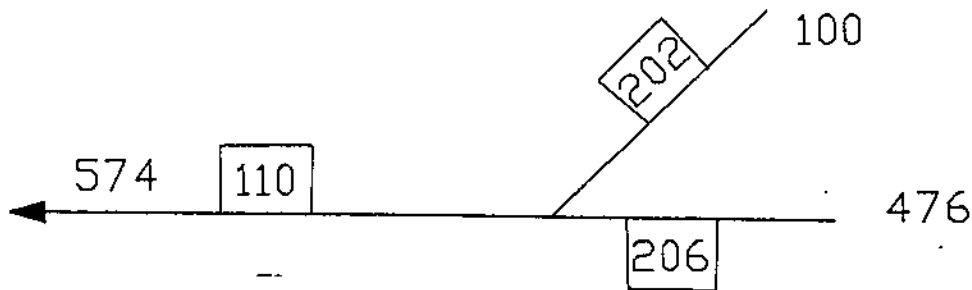


Fig 3.5 Representation of componenets of link volumes

In this example, link 110 is composed of traffic coming from links 202 and 206. Of course, the volume of these links might not add-up to the volume of the link considered, because these links are coming from different phases.

- 9) All of the previous points are combined together to form a schematic node/link diagram on which every single point of data is represented. This diagram is shown in Fig 3.6. Full details of the required data are presented in Appendix E.

3.4.3) Optimization in TRANSYT-7F:

TRANSYT-7F is used in this research to help in finding the optimal solution that minimizes delay. In order to reach an optimal solution for a particular case, the procedure presented in Table 3.5 is used.

Table 3.5 Recommended procedure for applying TRANSYT-7F

Step	Description	Run
1	Run TRANSYT-7F with the existing timing plan.	Sim.
2	Run TRANSYT-7F with a nominal cycle length number of times to determine the best phase sequence	Opt.
3	Run TRANSYT-7F with the phase sequence determined to evaluate a range of cycle lengths	Opt.
4	Get the cycle length that gives minimum PI and run the model	Opt.

(Source: TRANSYT-7F, User's Manual, Rel. 6, 1988)

In the following subsections, the method of optimization will be discussed.

A) Input to the Model:

The cycle length selection, which is an important issue

Prince Shaker Street

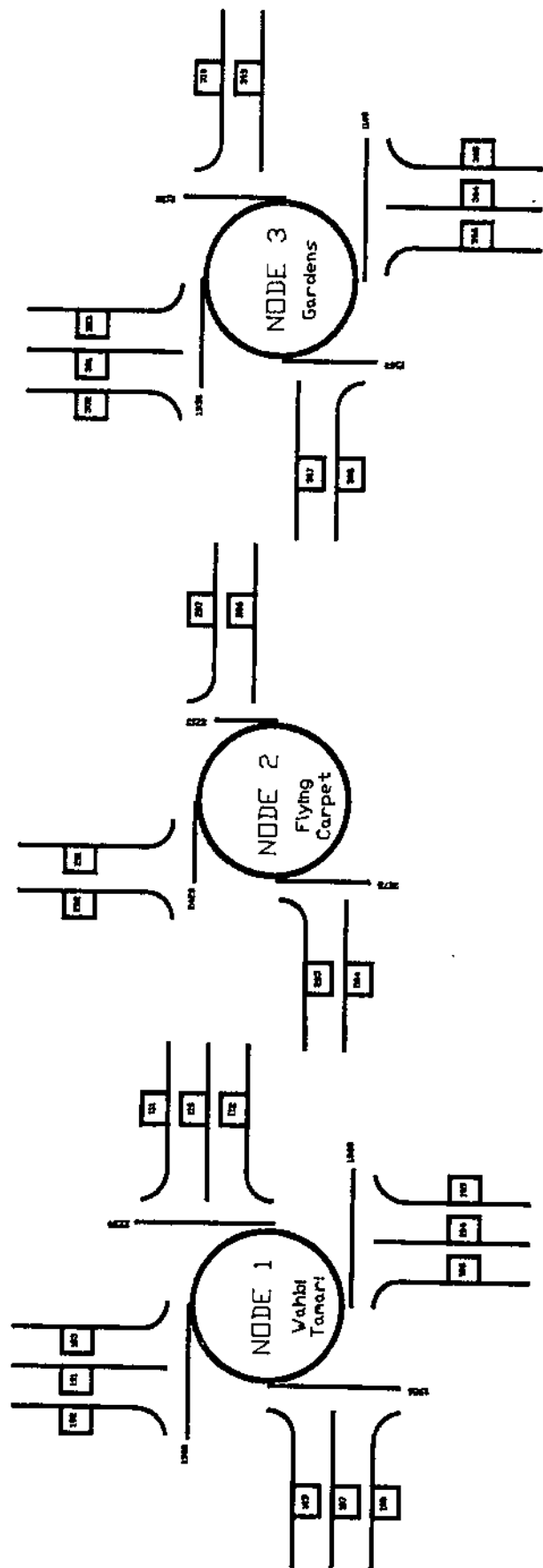


Fig 3.6 Schematic Node/Link Diagram

since it affects delay in the system, can be accomplished automatically in TRANSYT-7F. The user inputs a minimum and a maximum cycle lengths, and a cycle length increment. TRANSYT-7F optimizes phase length for every cycle length between the minimum and the maximum at the input increment. The best cycle length is the one that results in the lowest performance index (P.I.) after phase lengths have been optimized. This process accounts for not only the effects of volume and capacity at individual intersections, but also for the effects of traffic flow patterns in the network and spacing between signals. Other methods such as Webster's formula, only account for volume relationships at individual intersections.

B) Optimization Technique:

The optimization technique used in TRANSYT-7F is based on the gradient search technique⁽¹⁶⁾, which requires extensive numerical computations by the computer. The following steps explain the procedure

Step 1 The initial signal timing plan is simulated by the traffic model, and an initial PI (performance index) is calculated. Simply, the PI is a linear combination of delay and stops.

Step 2 The offset, which is the time difference in seconds between the system time base and the start of a specified interval, is increased. Then Step 1 is repeated.

Step 3 Comparison between the new PI and the previous one is carried out. If the new value of PI is less, then the program continues to increase the offset, otherwise when

the PI starts to increase, the program will decrease the offset till PI becomes the minimum. Then the model goes to the next signal in the system. This procedure is shown in Fig 3.7

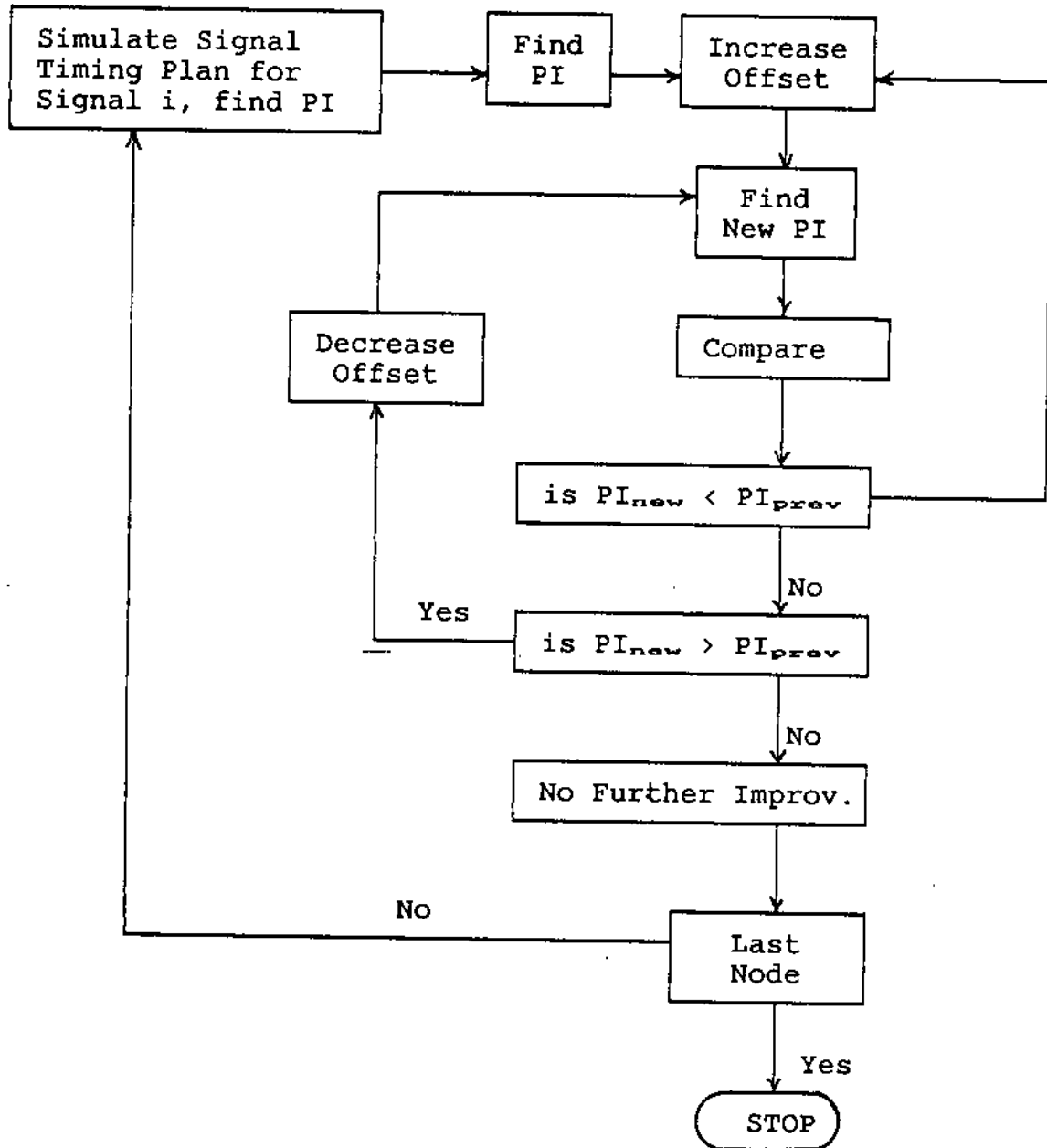


Fig 3.7 Optimization procedure used in TRANSYT-7F

On the other hand, and in order to find the optimal solution (minimum PI) for the system, this could be done by altering the phase sequence along an arterial route. The procedure is shown in Fig 3.8

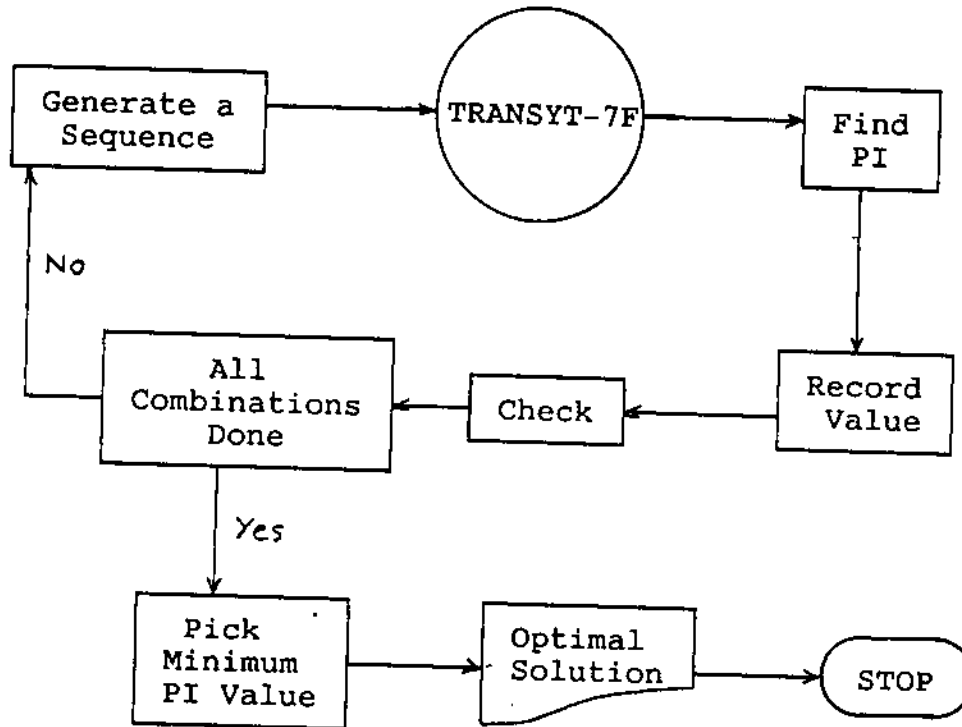


Fig 3.8 Procedure for determination of system optimal solution

C) Optimization Methodology :

The methodology of finding optimal solution is by generating all the possible sequences for all nodes, then running all these combinations in order to find the optimal solution.

In the case of Prince Shaker Street, the possible combinations are 864 cases. This can be illustrated by the following steps :

- a) 24 sequences for node 1 (C_4) since there are four approaches

- b) 6 sequences for node 2 (C_2)
 c) 6 sequences for node 3 (C_3)
 d) total combinations = $C_4 * C_2 * C_3$
 $= (4*3*2)*(3*2)*(3*2) = 864$ cases.

In order to run all the combinations (phase sequences) to find the one that results in minimum PI, it will require huge computer time. The Central Processing Unit (CPU) time needed to run one combination, and to make a cycle evaluation over a range of cycle lengths is approximated in Table 3.6

Table 3.6 CPU time (in the average) required to optimize

Processor	PC-XT	PC-AT
Time/Run* (sec)	1726.1	962.5
Time/Run** (sec)	21200	9594.6
Total Time* (hrs)	414.3	231

* Corresponds to One Cycle Length

** Corresponds to Cycle Evaluation Over a Range 90-130 sec

From Table 3.6, it can be shown the amount of time and work needed to find an optimal sequence that develops a minimum performance index. A claim is set in order to minimize the work needed.

Heuristic: The combination of minimum delay sequence for each node results in the sequence of minimum delay for the system.

It is difficult to prove this heuristic analytically, however, the procedure claimed in the heuristic is to be tested on a smaller problem to check its correctness. If the procedure works on the problem, one can have higher confidence that it will result in a minimum or near minimum delay for the

system.

Test Problem: Choose node 2 and node 3 of Fig 3.6. The possible sequences are 36. By comparing the combination that is claimed previously to other combinations, it was not possible to decrease delay.

When Nodes 2 and 3 of the network are chosen, and all the possible combinations were solved (36 phase sequences), the resulting PI's are shown in Table 3.7

These PI values shown in Table 3.7 are plotted versus the phase sequence in Fig 3.9. The sequence corresponding to minimum PI for each node is selected.

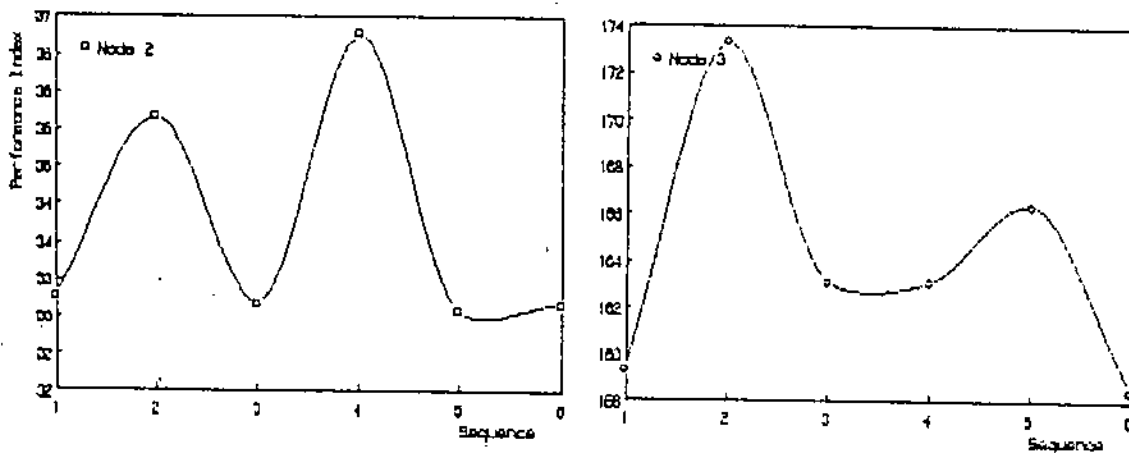


Fig 3.9 PI values plotted against phase sequence

Table 3.7 Resulting PI's for all possible phase sequences of Nodes 2 and 3

Phase Sequence	Node		System Wide	Phase Sequence	Node		System Wide
	2	3			2	3	
1 , 1	33.5	160.1	193.64	4 , 1	37.1	159.6	196.75
1 , 2	33.6	174	207.56	4 , 2	36.8	173.7	210.55
1 , 3	33.9	163.5	197.37	4 , 3	37	164.2	201.28
1 , 4	33.3	169.2	202.49	4 , 4	36.8	163.2	199.99
1 , 5	33.3	167	200.24	4 , 5	36.8	167	203.78
1 , 6	33.7	158.7	192.46	4 , 6	37	159.6	196.6
2 , 1	36	159.9	195.88	5 , 1	33.5	159.4	192.9
2 , 2	35.9	174.8	210.72	5 , 2	33.1	173.4	206.49
2 , 3	36.5	163.2	199.69	5 , 3	33.5	164.2	197.69
2 , 4	40	168.3	208.32	5 , 4	33.3	163.4	196.68
2 , 5	35.7	166.6	202.32	5 , 5	33.4	166.8	200.25
2 , 6	36.4	158.6	194.99	5 , 6	33.4	159.6	192.9
3 , 1	33.5	159.6	193.12	6 , 1	33.5	160.1	193.64
3 , 2	33.2	173.7	206.92	6 , 2	33.2	175.2	208.4
3 , 3	36.1	164.3	200.35	6 , 3	34.4	163.3	197.71
3 , 4	35.7	163.6	199.26	6 , 4	33.3	169.2	202.49
3 , 5	35.8	167	202.78	6 , 5	33.3	166.6	200.12
3 , 6	36.1	159.8	195.89	6 , 6	33.7	159.4	193.13

Another run has been carried out using the timing plan of the selected sequences as shown in Table 3.8. The system wide PI value of this run is compared to values which resulted from all the combinations under study. It was found that this value is the minimum among all other values corresponding to the different combinations. Hence, as expected, the procedure can result in the optimal solution for the system. Consequently, the procedure will be used in solving the case under study in this research.

Table 3.8 PI values for the best sequence combination

Sequence	Node		System Wide
	2	3	
5 , 6	33.4	159.6	192.9

CHAPTER FOUR

Implementation and Results

4.1 Introduction:

The major objectives of signal timing are the minimization of delay and congestion at intersections and within block lengths and series of block lengths between intersections, and the increase in safety for all road users. Full utilization of traffic control signals is realized only when they are operated so as to satisfy, as nearly as possible, actual traffic requirements.

In this chapter, and in order to have a feeling about the difference between solving the problem using the conventional methods such as Webster's, Pignataro's and others, and the other advanced methods using queuing models as TRANSYT-7F, the case of Prince Shaker Street was solved using the two approaches. In the next section, British method has been used to solve the first intersection (Wahbi Tamari) in order to find the signal timing plan.

4.2 Using the Webster's Method to Solve Wahbi Tamari: (1, 2, 3)

In the case of this intersection, Wahbi Tamari, because the traffic volumes are heavy, and it has four approaches, it requires a longer cycle length than those intersections of lighter traffic volumes and fewer approaches. In general, cycle lengths range from a minimum of 30 sec to a maximum of 120 sec., depending on traffic volumes, approaches, and movements.









In this section, the intersection will be designed using

one of the conventional methods, The British Method, in order to have a feeling of how the design will be done. The design is concerned with the morning peak hour from 7:30 to 8:30 a.m.

As mentioned before, this method is mainly concerned with minimizing delay of the intersection. Also, peak-hour-factor (PHF) and saturation flow are the major factors that affect cycle time splitting.

4.2.1 Traffic Flow Data: *

Table 4.1 Traffic flow data for each approach in the a.m. peak hour

TIME	N B		S B		E B		W B		TOTAL
									
7:30 - 7:45	22	78	23	62	40	120	60	235	640
7:45 - 8:00	26	71	28	64	46	116	125	206	682
8:00 - 8:15	22	56	30	68	38	171	84	197	666
8:15 - 8:30	18	47	15	31	7	99	75	211	503
TOTAL	88	252	96	225	131	506	344	849	2491

$$\text{PHF} = \frac{\text{Total flow in 1 Hr}}{4 (\text{Max flow of 15 min})} = \frac{2491}{4 \times 682} = 0.913$$

4.2.2 Splitting Effective Green Times:

The effective green times are splitted in proportion of the y_1 to Y . A complete computation is found in Appendix D.

* A complete solution using Webster's Method is found in Appendix D

$$y_N = 0.199$$

$$y_S = 0.189$$

$$y_E = 0.330$$

$$y_W = 0.713$$

$$Y = \sum y_i = 1.431$$

Since the summation $y_i > 1$, then set the equation to the maximum cycle length that can be used, $C_o = 120$ seconds. (20)

$$g_i = \frac{y_i}{Y} (C_o - L)$$

$$g_N = \frac{0.199}{1.431} (120 - 12) = 15.0$$

$$g_S = 0.189 * 75.472 = 14.3$$

$$g_E = 0.330 * 75.472 = 24.9$$

$$g_W = 0.713 * 75.472 = 53.8$$

Then, actual green times, using cycle length $C_o=120$ seconds, are as follows (Fig 4.1):

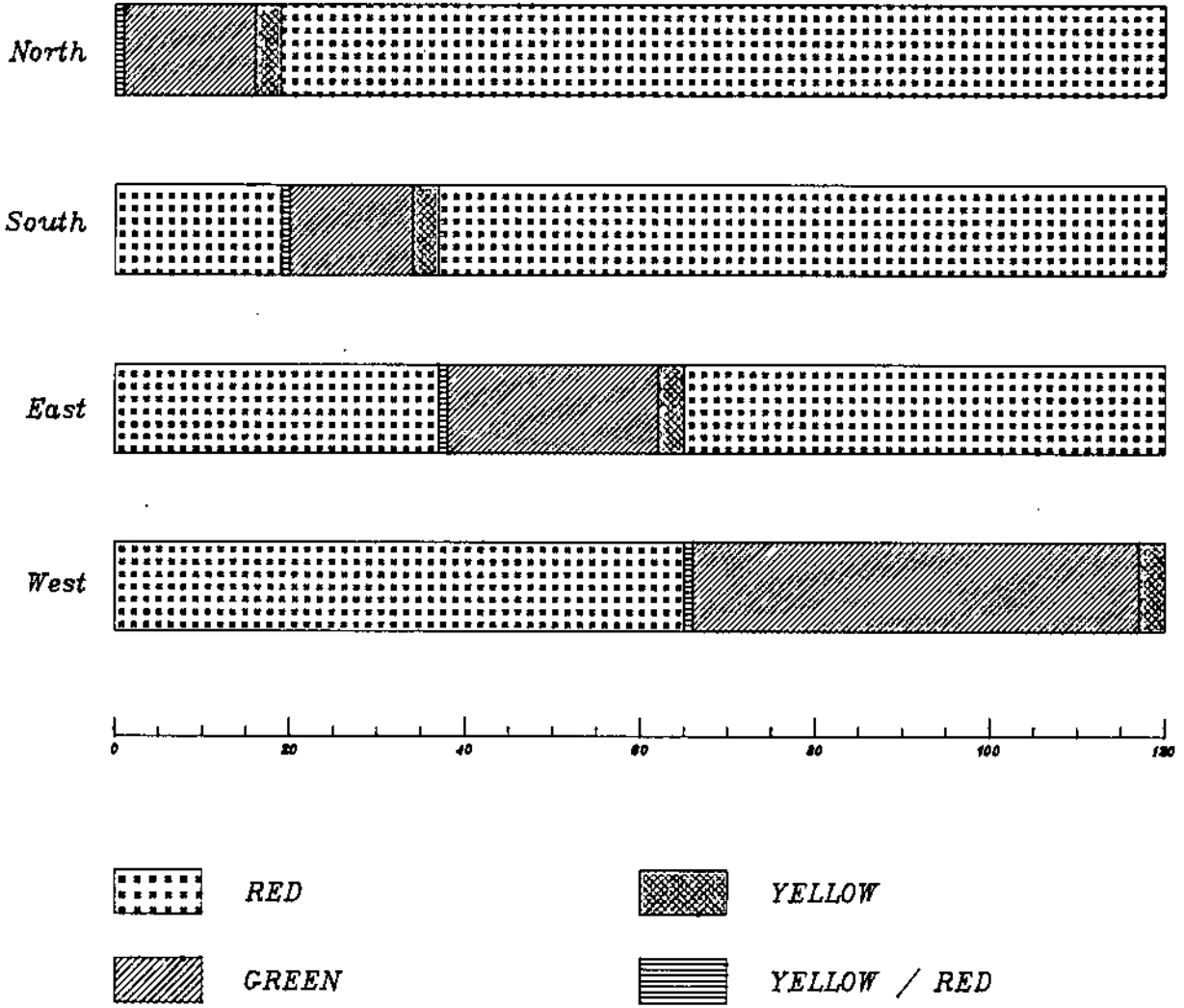
$$g_N = 15 \text{ sec.}$$

$$g_S = 14 \text{ sec}$$

$$g_E = 24 \text{ sec}$$

$$g_W = 51 \text{ sec.}$$

Phase Diagram (Wahbi Tamari Intersection)



*Fig 4.1 Phase diagram of Wahbi Tamari Intersection
in the a.m. peak hour*

4.3 Analysis Using TRANSYT-7F:

4.3.1) Statistical Analysis of Traffic Data^(13,14)

The most important aspect of the simulation of traffic travelling along signalized streets is the manner in which the traffic flow is distributed and modeled. Although TRANSYT models the dispersion of the platoons of vehicles as they progress along a link, determining the distribution of traffic flow in the area of study gives some feeling about the behaviour of traffic in that area. The hypothesis testing technique will be used to test the flow, and what distribution does the traffic data follow. The data used are those of the flow at Wahbi Tamari Intersection as an example. It has four legs, and the traffic data is collected. The data of the south bound leg is shown in the following table:

Table 4.2 Statistical results to test distribution of traffic

TIME PERIOD	INTERVAL (sec)	OBSERVED (Veh/15 min)	EXPECTED (Veh/15 min)	(O - E) ²
7:30 - 7:45	900	85	54	961
7:45 - 8:00	900	92	54	1444
8:00 - 8:15	900	98	54	1936
8:15 - 8:30	900	46	54	64
8:30 - 8:45	900	29	54	625
8:45 - 9:00	900	29	54	625
9:00 - 9:15	900	19	54	1225
9:15 - 9:30	900	36	54	324
TOTAL		434		7204

- O means Observed, E means Expected.

In this test, in order to verify if the distribution is Poisson, arrival rate, which is the total traffic in a given

time calculated in Veh/Sec., is to be calculated. The other thing to do is to test the "goodness" of fit using the Chi-Square test, according to the following hypothesis:

H_0 : Traffic flow follows Poisson distribution

H_1 : Traffic flow does not follow Poisson Dist.

$$q = \frac{434}{2 * 3600} = 0.06 \text{ Veh/Sec.}$$

$$E = q * \text{time interval} = 0.06 * 900 = 54 \text{ veh/15-min}$$

$$X_{\text{comp}}^2 = \sum \frac{(E - O)^2}{E} = \frac{7204}{434} = 16.676$$

$$X_{0.05, 6}^2 = 12.592$$

$$\text{Hence, } X_{\text{comp}}^2 > X_{0.05, 6}^2$$

— where, q = arrival rate in veh/sec

E = expected flow rate in
veh/15-min

O = observed flow rate in
veh/15-min

Thus, there is no significant difference between observed and theoretical distribution, so the distribution is considered as POISSON DISTRIBUTION.

4.3.2) Calculations of the Case

As presented in Table 3.2, the first step is to run the model using the existing signal timing plan. This plan is shown in Fig 4.2. As it can be seen from the summary of this run, the PI value is 387.70 (Fig 4.3).

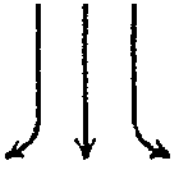
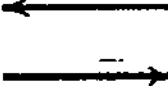

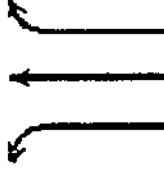

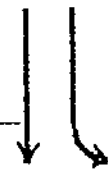
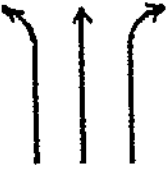


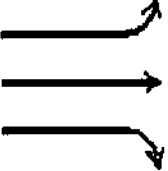
Node 1			Node 2			Node 3		
Phases			Phases			Phases		
Diagram	No	Min	Diagram	No	Min	Diagram	No	Min
	1	17		1	33		1	48
	2	27		2	28		2	28
	3	18		3	39		3	24
	4	38						

Fig 4.2 Installed signal timing plan and phase sequence

SIMULATION OF EXISTING (INSTALLED) PHASE SEQUENCE AND CYCLE LENGTH (100 SECONDS).

PERFORMANCE WITH INITIAL SETTINGS									
NO.	LINK NO.	FLOW (VEH/H)	SAT FLOW OF SAT (VEH/H)	TOTAL TRAVEL TIME (SEC)	UNIFORM DELAY (SEC/VEH)	RANDOM DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	START TIME OF RUN	PHASE LINK NO.
1	101	10	1000	2.00	0.13	0.13	0.13	13:16:54	101
1	102	196	1015	15.20	1.31	1.31	1.31	13:16:54	102
1	103	60	1030	13.20	1.04	1.04	1.04	13:16:54	103
1	104	55	1045	12.50	0.94	0.94	0.94	13:16:54	104
1	105	264	1045	10.00	0.71	0.71	0.71	13:16:54	105
1	106	878	1045	52.80	13.76	13.76	13.76	13:16:54	106
1	107	1015	1045	114.20	10.12	10.12	10.12	13:16:54	107
1	108	270	1045	108.00	5.55	5.55	5.55	13:16:54	108
1	109	540	2250	230.00	10.51	10.51	10.51	13:16:54	109
1	110	121	1105	14.48	1.15	1.15	1.15	13:16:54	110
1	111	180	1105	17.57	1.29	1.29	1.29	13:16:54	111
1	112	3570	1644	942.00	43.29	43.29	43.29	13:16:54	112
2	201	450	2420	340.00	7.07	7.07	7.07	14:47:46	201
2	202	884	2070	326.50	11.60	11.60	11.60	14:47:46	202
2	203	376	1100	151.14	1.51	1.51	1.51	14:47:46	203
2	204	558	2215	39.77	7.49	7.49	7.49	14:47:46	204
2	205	256	1200	45.51	1.29	1.29	1.29	14:47:46	205
2	206	3024	1634	1060.84	42.78	42.78	42.78	14:47:46	206
3	301	160	1950	123.14	1.92	1.92	1.92	15:34:46	301
3	302	250	1200	15.00	1.14	1.14	1.14	15:34:46	302
3	303	224	1700	123.20	2.96	2.96	2.96	15:34:46	303
3	304	112	3045	18.20	1.56	1.56	1.56	15:34:46	304
3	305	158	3045	33.60	1.26	1.26	1.26	15:34:46	305
3	306	1358	2150	240.57	12.59	12.59	12.59	15:34:46	306
3	307	428	1800	72.12	1.00	1.00	1.00	15:34:46	307
3	308	836	3045	238.80	6.97	6.97	6.97	15:34:46	308
3	310	3684	1634	1045.08	256.22	256.22	256.22	15:34:46	310

SYSTEM WIDE TOTALS INCLUDING ALL LINKS									
TOTAL	DISTANCE TRAVELED (VEH-H)	TOTAL FLOW (VEH/H)	TOTAL SAT FLOW OF SAT (VEH/H)	TOTAL TRAVEL TIME (SEC)	TOTAL UNIFORM DELAY (SEC/VEH)	TOTAL RANDOM DELAY (SEC/VEH)	TOTAL AVERAGE DELAY (SEC/VEH)	START TIME OF RUN	PHASE LINK NO.
2016.01	530.06	39.67	405.20	504.67	135.30	5375.84	1805.42	13:16:54	2016.01
GENIE SUMMARY REPORT									
NO.	LINK NO.	FLOW (VEH/H)	SAT FLOW OF SAT (VEH/H)	TOTAL TRAVEL TIME (SEC)	UNIFORM DELAY (SEC/VEH)	RANDOM DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	START TIME OF RUN	PHASE LINK NO.
1	107	841	1950	337.60	10.11	10.11	10.11	13:16:54	107
2	204	884	2070	326.50	11.60	11.60	11.60	14:47:46	204
3	307	1358	2150	240.57	12.59	12.59	12.59	15:34:46	307
DOWN :	3096	MAX = 1644	954.55	251.83	31.17	194.11	225.28	15:34:46	3096
1	110	540	2250	230.00	10.51	10.51	10.51	13:16:54	110
2	206	558	2215	39.77	7.49	7.49	7.49	14:47:46	206
3	309	851	2150	256.20	16.93	6.00	9.61	15:34:46	309
UP :	1952	MAX = 1324	505.01	76.56	37.45	60.12	110.9	15:34:46	1952
GRUPE TOTALS									
TOTAL	TOTAL DISTANCE TRAVELED (VEH-H)	TOTAL FLOW (VEH/H)	TOTAL SAT FLOW OF SAT (VEH/H)	TOTAL TRAVEL TIME (SEC)	TOTAL UNIFORM DELAY (SEC/VEH)	TOTAL RANDOM DELAY (SEC/VEH)	TOTAL AVERAGE DELAY (SEC/VEH)	START TIME OF RUN	PHASE LINK NO.
1933.66	328.40	53.62	231.77	295.39	213.93	3172.94	989.86	13:16:54	1933.66

NOTE: PERFORMANCE INDEX IS DEFINED AS:
 PI = DELAY * STOPS
 NO. OF SIMULATIONS = 1 NO. OF LINKS = 28 ELAPSED TIME = 70.5 SEC.

Fig. 4.3 Simulation of installed signal timing plan

Another run was carried out using the existing signal timing plan and phase sequence, but in the optimization mode. A summary of this run is shown in Fig 4.4. The PI value is 348.83.

It can be seen clearly that changing the phase lengths for the different movements, i.e. the portion of the cycle length given to a certain movement, even by keeping the same phase sequences may result in better performance. Fig 4.5 shows some comparison.

In order to have a feeling about the best cycle length that produces a minimum performance index, while keeping the same phase sequence, an optimization run has been done over a range of cycle lengths from 90-130 seconds. It has been determined that by using the existing phase sequences for the three intersections we deal with, the best cycle length was found to be 125 seconds, which gives a PI value of 341.07. This result is shown in Fig 4.6.

In order to reach a good solution (optimal or near-optimal), an algorithm has been developed. In the next section, the algorithm and its implementation are presented.

SEQUENCE 1.1.1

DATE OF RUN: 11/16/90 START TIME OF RUN: 31:06:100

<PERFORMANCE WITH OPTIMAL SETTINGS>

CYCLE: 100 SECONDS

MODE LINK NO.	FLOW Q (VEH/H)	SAT FLOW Q (VEH/H)	GEAREE TOTAL TRAVEL TIME (MIN)	TOTAL TIME (MIN)	UNIFORM DELAY (SEC/VEH)	RANDOM DELAY (SEC/VEH)	DELAY (SEC/VEH)	TOTAL DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	UNIFORM STORES (VEH)	MAX BACK Q (VEH)	QUEUE CAPACITY (VEH)	FUEL CONSUM (LITR)	PHASE LINK NO.
1	101	1900P	120M	2:00	65	1.14	0.45	1.53	213.0	8.5K (82)	11	25	37.19	15
1	102	101S	120M	38.00	12.23	2.67	0.58	31.24	213.0	156.5K (82)	101	1015	20.04	15
1	103	101S	120M	13.20	6.23	1.35	4.33	5.64	213.0	80.1K (82)	101	1015	20.04	15
1	104	100P	144M	13.20	5.23	1.04	5.17	6.51	255.1	45.7K (82)	20	25	20.04	16
1	105	104S	144M	10.00	5.23	1.04	5.17	6.51	255.1	121.5K (82)	104	1045	15.18	16
1	106	264	154M	52.80	37.55	5.36	20.66	92.73	322.1	132.3K (82)	104	1045	60.75	16
1	107	044	1950P	337.60	106.37	14.02	62.71	262.71	412.6	51.3K (61)	104	1045	14.04	28
1	108	28	107S	15.20	4.73	3.72	4.35	4.35	412.6	23.2K (61)	107	1075	14.04	28
1	109	270	107S	154M	34.03	4.40	26.46	30.94	412.6	164.5K (82)	107	1075	59.74	28
1	110	540	2250P	114M	29.04	4.72	17.49	22.21	148.1	448.7K (82)	23	56	5.77	31
1	111	34	110S	14.40	1.60	1.20	1.10	1.33	148.1	27.0K (79)	110	1105	92.41	31
1	112	168	110S	114M	71.57	1.45	5.44	6.81	147.3	136.1K (81)	110	1105	29.61	31
1	113	3570	MAX = 164M	313.09	2:15.58	37.46	190.03	217.50	304.7	1924.0K (712)	725.60	PI = 164.6		
2	201	650	2420	100M	34.00	7.67	7.43	15.10	64.0	809.5K (82)	41	53	63.03	27
2	202	100	1200	8	40.00	1.00	0.00	1.00	0.0	0.0K (0)	0	53	4.50	100
2	203	894	207S	70	376.58	1.33	1.40	1.73	7.0	172.1K (82)	5	58	49.06	63
2	204	376	1100	107M	160.19	13.96	8.46	9.58	99.8	113.8K (80)	4	56	45.29	24
2	205	256	221S	92	98.77	6.84	2.51	6.02	30.8	489.2K (88)	14	23	33.18	29
2	207	256	120S	21	45.31	1.83	0.00	1.00	0.0	0.0K (0)	0	23	5.10	100
2	208	1024	MAX = 107M	1060.84	62.54	13.43	18.80	32.23	39.4	1591.8K (52)	226.16	PI = 28.2		
3	301	160	1950P	160M	48.00	13.13	2.85	15.11	17.75	399.6	35	39	55.73	22
3	302	250	1200	21	75.00	2.14	0.00	1.00	0.0	0.0K (0)	0	39	56.43	102
3	303	464	201S	160M	359.20	55.43	7.69	43.81	51.50	399.6	301	3015	161.62	22
3	304	226	1100P	193M	135.50	37.65	5.23	28.25	33.79	290.0K (82)	22	79	110.16	22
3	305	142	204S	133M	67.20	18.66	2.74	14.00	16.74	539.1	304	3045	54.59	20
3	306	1358	2150S	132M	235.97	9.33	1.37	7.00	53.1	56.3K (50)	304	3045	27.30	20
3	307	108	207S	122M	19.12	75.91	4.25	61.61	65.26	28.1K (50)	28	230	219.21	58
3	308	654	2150P	79	256.20	12.02	4.06	17.08	178.9	58.6K (52)	307	3075	17.76	58
3	309	96	309S	79	28.60	1.35	0.46	4.20	13.9	70.1K (35)	309	3095	48.13	58
3	310	3684	MAX = 139M	1043.08	234.81	23.50	175.51	205.01	200.3	2026.1K (55)	708.01	PI = 156.0		

<SYSTEM WIDE TOTALS INCLUDING ALL LINKS>

TOTAL DELAY TRAVEL TIME (MIN)	TOTAL FUEL CONSUM (LITR)	TOTAL UNIFORM STORES (VEH)	TOTAL AVERAGE DELAY (SEC/VEH)	TOTAL UNIFORM STOPS (VEH/H)	TOTAL DELAY (MIN)	OPERATING COST	PERFORMANCE INDEX	SPEED (KM/H)
454.73	176.44	5434.9K (59)	1659.97	2452.56	348.83	5.58	<TOTALS>	

NOTE: PERFORMANCE INDEX IS DEFINED AS:

PI = DELAY * STOPS

NO. OF SIMULATIONS = 21 NO. OF LINKS = 310 ELAPSED TIME = 1909.8 SEC.

Fig 4.4 Optimization of installed signal timing plan and phase sequence

*** Comparison between the performance with INITIAL and OPTIMUM settings for the installed phase sequence and signal timing plan.

DATE OF RUN: 12/14/90 START TIME OF RUN: 13:16:54
 <PERFORMANCE WITH INITIAL SETTINGS> CYCLE: 100 SECONDS <PERFORMANCE WITH OPTIMAL SETTINGS> CYCLE: 100 SECONDS.

MODE LINK NO.	TOTAL TIME (VEH-H/H)	AVERAGE (SEC/VEH)	UNIFORM (VEH/H ²)	FUEL CONSUM (CL/H)	PHASE LENGTH (SEC)	LINK NO.	MODE LINK NO.	TOTAL TIME (VEH-H/H)	AVERAGE (SEC/VEH)	UNIFORM (VEH/H ²)	FUEL CONSUM (CL/H)	PHASE LENGTH (SEC)	LINK NO.
1	101	114.2	9.5C 9522	1.34	17	101	1	101	213.0	8.2C 8222	2.09	15	101
1	102	114.2	161.2C 9522	22.39	17	102	1	102	213.0	158.5C 8222	37.19	15	102
1	103	147.2	23.2C 9522	14.62	18	103	1	103	213.0	80.1C 8222	18.79	15	103
1	104	247.2	59.6C 9522	11.62	18	104	1	104	213.0	74.7C 8222	15.18	16	104
1	105	247.2	209.0C 9522	11.08	18	105	1	105	355.1	162.9C 8222	60.18	16	105
1	106	19.64	514.2C 6122	23.22	38	106	1	106	412.6	54.2C 6122	311.79	38	106
1	107	110.49	430.1	14.35	38	107	1	107	412.6	23.2C 6122	14.04	38	107
1	108	35.35	430.1	14.35	38	108	1	108	412.6	16.5C 6122	9.74	38	108
1	109	50.15	291.5	15.46	27	109	1	109	148.6	27.0C 6122	5.77	31	109
1	110	15.60	289.5	9.50	27	110	1	110	148.6	27.0C 6122	5.77	31	110
1	111	15.60	290.5	47.13	27	111	1	111	147.5	156.1C 8122	28.61	31	111
1	112	259.06	326.6	1847.8C 7222	769.40	PI = 176.2	1	112	304.7	1824.0C 7122	725.90	PI = 164.6	112
2	201	20.11	44.0	779.8C 9222	75.66	39	201	24.82	64.0	809.6C 9522	89.03	37	201
2	202	11.14	4.5	109.5C 1222	46.26	61	202	12.49	7.0	172.1C 1322	43.06	63	202
2	203	23.13	235.2	211.5C 5622	89.44	28	203	13.96	89.8	113.8C 3022	45.29	34	203
2	204	1.23	-0	434.0C 0222	5.10	100	204	0.94	58.8	489.2C 8622	52.18	23	204
2	205	72.78	51.0	1534.6C 5122	254.89	PI = 36.0	2	205	39.4	1584.8C 5222	226.16	PI = 28.2	205
2	206	217.9	130.0C 9122	32.69	28	206	2	206	393.6	100.0C 6222	55.73	22	206
2	207	32.06	217.9	377.0C 9122	92.67	28	207	35.14	293.0	280.0C 9222	18.44	100	207
2	208	30.93	138.8C 6122	91.35	24	208	2	208	353.1	419.0C 8222	160.92	22	208
2	209	15.36	431.3	68.8C 6122	45.57	24	209	18.66	538.1	156.2C 5022	157.59	20	209
2	210	17.68	431.3	94.7C 6122	38.78	24	210	9.33	538.1	28.1C 5022	218.21	58	210
2	211	10.57	329.5	94.7C 4022	38.97	48	211	73.12	175.7	677.4C 5022	218.21	58	211
2	212	16.93	329.5	769.1C 9022	63.97	48	212	12.01	118.8	68.8C 5222	17.76	58	212
2	213	1.90	40.5	86.5C 9022	7.15	48	213	11.55	13.8	670.1C 7322	45.48	58	213
3	301	258.22	223.7	2593.5C 7022	781.13	PI = 175.6	3	301	235.82	2026.1C 5522	708.01	PI = 156.0	301

<SYSTEM WIDE TOTALS INCLUDING ALL LINKS>

PERFORMANCE WITH INITIAL SETTINGS	PERFORMANCE WITH OPTIMAL SETTINGS
TOTAL DISTANCE TRAVELED (VEH-KM/H)	TOTAL DISTANCE TRAVELED (VEH-KM/H)
5016.01	5016.01
590.06	590.06
99.67	99.67
405.20	405.20
504.07	504.07
195.90	195.90
5375.8C 6422	5375.8C 6422
1805.42	1805.42
OPERATING PERFORMANCE INDEX	OPERATING PERFORMANCE INDEX
5.11	5.11
587.70	587.70
2335.82	2335.82
5.11	5.11
<TOTALS>	<TOTALS>

NOTE: PERFORMANCE INDEX IS DEFINED AS:

PI = DELAY + STOPS

NO. OF SIMULATIONS = 1 NO. OF LINKS = 28 ELAPSED TIME = 51.4 SEC.

<PERFORMANCE WITH OPTIMAL SETTINGS>

PERFORMANCE WITH INITIAL SETTINGS	PERFORMANCE WITH OPTIMAL SETTINGS
TOTAL DISTANCE TRAVELED (VEH-KM/H)	TOTAL DISTANCE TRAVELED (VEH-KM/H)
5016.01	5016.01
540.90	540.90
80.40	80.40
374.23	374.23
454.73	454.73
176.44	176.44
5434.9C 5922	5434.9C 5922
1659.97	1659.97
OPERATING PERFORMANCE INDEX	OPERATING PERFORMANCE INDEX
5.56	5.56
348.93	348.93
2152.56	2152.56
5.56	5.56
<TOTALS>	<TOTALS>

NOTE: PERFORMANCE INDEX IS DEFINED AS:

PI = DELAY + STOPS

NO. OF SIMULATIONS = 21 NO. OF LINKS = 318 ELAPSED TIME = 1308.8 SEC.

Fig 4.5 Comparison between initial and optimal setting of installed phase sequence

CYCLE EVALUATION SUMMARY PERFORMANCE

CYCLE LENGTH (SEC)	AVERAGE BELOW (SEC/VEH)	PERCENT STOPS	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	NUMBER SAT LINKS
110	173.86	57	1640.0	344.0	21
115	173.99	55	1637.0	333.4	22
120	174.30	52	1632.4	342.0	22
130	173.58	56	1635.4	342.6	22

BEST CYCLE LENGTH = 125 SEC. CYCLE SENSITIVITY = 2.2

PERFORMANCE WITH OPTIMAL SETTINGS

CYCLE: 125 SECONDS

LINK NO.	LINK NO.	FLOW (VEH/HR)	SET FLOW OF SAT (VEH/HR)	TOTAL FLOW (VEH/HR)	TOTAL DELAY (SEC/VEH)	UNIFORM DELAY (SEC/VEH)	TOTAL DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	UNIFORM STOPS (VEH/HR)	MAX STOPS (VEH/HR)	QUEUE CAPACITY (VEH/HR)	FUEL CONSUMPTION (GAL/HR)	PHASE LENGTH (SEC)	LINK NO.
1	101	180	180	360	98	29	17.82	332.1	37.2	101	26	2.99	15	101
1	102	98	101	199	16.61	1.91	13.70	322.1	39.0	101	101	51.37	16	102
1	103	98	101	199	9.40	1.91	7.49	322.1	6.96	101	101	27.47	16	103
1	104	66	180	246	19.20	1.93	17.27	322.1	6.96	101	101	27.47	17	104
1	105	28	104	132	16.52	1.93	14.59	322.1	10.4	104	104	28.10	17	105
1	106	28	104	132	52.60	1.93	50.67	322.1	10.4	104	104	104.73	17	106
1	107	644	185.00	829.00	37.60	15.16	22.44	322.1	78.01	702	162	260.90	54	107
1	108	36	107	143	2.95	2.95	5.90	322.1	16.9	107	107	11.74	18	108
1	109	36	107	143	15.20	2.95	12.25	322.1	16.9	107	107	11.74	18	109
1	110	540	230.0	770.0	20.04	4.34	15.70	322.1	42.40	622	156	93.54	38	110
1	111	34	115	149	11.61	1.23	10.38	322.1	11.99	115	115	15.60	38	111
1	112	168	1105	1273	71.57	1.23	70.34	322.1	6.91	932	110	1105	58	112
1	2570	MAX = 1604	912.03	240.99	43.04	43.04	171.24	215.08	301.3	1073.6	732	719.62	PI = 163.0	
2	201	450	2420	95	240.00	4.76	235.24	52.3	20	20	20	81.75	48	201
2	204	894	2175	73	376.58	1.66	374.92	52.3	4	4	4	46.22	17	204
2	205	376	1100	104	160.18	1.12	159.06	52.3	7	7	7	42.24	43	205
2	206	588	2215	98	99.77	5.17	94.60	52.3	16	16	16	44.12	254	206
2	207	288	1200	21	45.31	1.00	44.31	52.3	0	0	0	5.10	123	207
2	302	MAX = 1044	1060.04	61.45	15.01	15.01	31.52	37.5	1596.2	532	224.24	PI = 27.9		
3	301	150	1260	154	48.00	3.17	44.83	386.9	30	30	30	54.46	28	301
3	302	250	1200	151	75.00	2.14	72.86	386.9	14.00	14	14	61.44	12	302
3	303	464	3015	1514	139.20	64.10	75.10	386.9	40.34	50.13	301	151.95	20	303
3	304	286	1800	235	135.60	43.33	92.27	386.9	35.3	42.23	27	7.9	21	304
3	305	182	3045	235	110.80	11.84	98.96	386.9	18.2	22.23	204	31.56	21	305
3	307	1350	2150	1154	240.31	5.96	234.35	386.9	50.19	50.19	304	173.39	76	307
3	308	108	3075	115	19.12	4.71	14.41	386.9	4.16	18.9	307	14.49	76	308
3	310	36	3095	75	28.60	1.06	27.54	386.9	4.55	30.5	308	15.48	76	310
3	3	3684	MAX = 2364	1043.09	226.26	24.65	192.01	192.5	192.3	522	685.03	PI = 150.2		

GRATE SUMMARY REPORTS THE 1SD ORIENTATION DOWNWARD ON THE PHASE IS WESTBOUND

LINK NO.	LINK NO.	FLOW (VEH/HR)	SET FLOW OF SAT (VEH/HR)	TOTAL FLOW (VEH/HR)	TOTAL DELAY (SEC/VEH)	UNIFORM DELAY (SEC/VEH)	TOTAL DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	UNIFORM STOPS (VEH/HR)	MAX STOPS (VEH/HR)	QUEUE CAPACITY (VEH/HR)	FUEL CONSUMPTION (GAL/HR)	PHASE LENGTH (SEC)	LINK NO.
1	107	844	1850	1424	37.65	15.16	22.49	322.7	78.01	702	162	260.90	54	107
2	204	894	2175	73	376.58	1.66	374.92	52.3	4	4	4	46.22	17	204
3	307	1356	2150	1154	240.37	5.96	234.41	386.9	50.19	50.19	304	173.39	76	307
3	308	MAX = 1424	954.55	158.12	29.07	109.49	129.56	181.1	1334.0	432	481.11	PI = 99.0		
1	110	540	230.0	770.0	20.04	4.34	15.70	322.7	42.40	622	156	93.54	38	110
2	204	894	2175	73	376.58	1.66	374.92	52.3	4	4	4	46.22	17	204
3	307	1356	2150	1154	240.37	5.96	234.41	386.9	50.19	50.19	304	173.39	76	307
3	308	MAX = 1154	505.01	53.73	13.91	37.28	51.19	156.1	1561.2	802	186.65	PI = 32.0		

PERFORMANCE WITH OPTIMAL SETTINGS

LINK NO.	LINK NO.	FLOW (VEH/HR)	SET FLOW OF SAT (VEH/HR)	TOTAL FLOW (VEH/HR)	TOTAL DELAY (SEC/VEH)	UNIFORM DELAY (SEC/VEH)	TOTAL DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	UNIFORM STOPS (VEH/HR)	MAX STOPS (VEH/HR)	QUEUE CAPACITY (VEH/HR)	FUEL CONSUMPTION (GAL/HR)	PHASE LENGTH (SEC)	LINK NO.
1	107	844	1850	1424	37.65	15.16	22.49	322.7	78.01	702	162	260.90	54	107
2	204	894	2175	73	376.58	1.66	374.92	52.3	4	4	4	46.22	17	204
3	307	1356	2150	1154	240.37	5.96	234.41	386.9	50.19	50.19	304	173.39	76	307
3	308	MAX = 1154	505.01	53.73	13.91	37.28	51.19	156.1	1561.2	802	186.65	PI = 32.0		

Fig 4.6, Optimization over a range of cycle lengths assuming installed phase sequence

4.4 Developed Algorithm:

There are three parameters that affect the solution in TRANSYT. These are cycle length C , sequence S , and timing plan T . The logical way that leads to a good solution is presented in Fig4.7. Using the Hierarchical Decomposition will lead to understand better how to reach the solution.

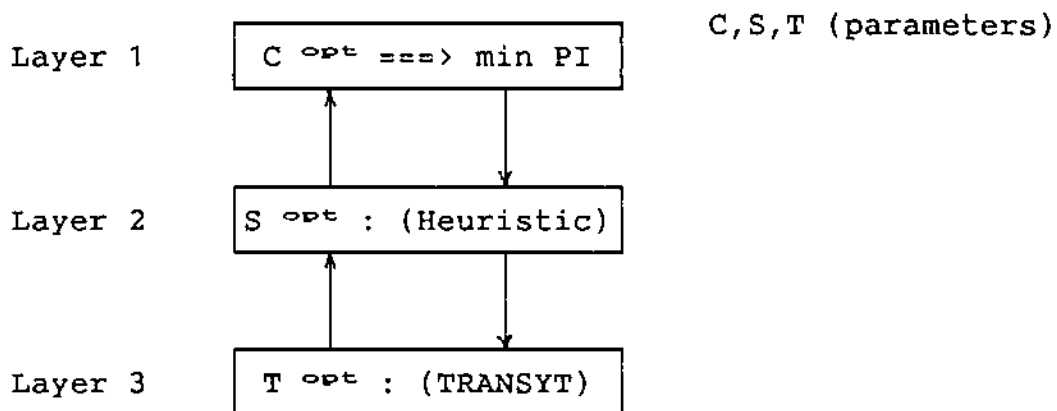


Fig 4.7 Hierarchical decomposition

The procedure of each layer is described below.

Layer 1: the user starts by inserting a nominal cycle length, and preferably, the installed one.

Layer 2: using the Heuristic described before (p. 41), we find the best sequence for each node.

Layer 3: then, the sequence found in layer 2 is used to find the best timing plan and cycle length for that specific sequence.

The iterations continue between Layer 2 and Layer 3 (regenerate new sequence using the resulting cycle length by applying Heuristic) until we reach a steady-state. This means that, the resulting sequence and timing plan and cycle length

are optimal or near-optimal. The resulting cycle length from Layers 2 and 3 is the best that can be obtained.

Taking into consideration the way that the decomposition works, the new algorithm has been developed. The procedure for this algorithm is shown in Fig 4.8. Also, the flow chart of the procedure is shown in Fig 4.9.

STEP 1

Find sequence for each node such that:

$$PI_{min} = \min_l \min_k \min_m (PI)_{lkm}$$

STEP 2

Find optimal cycle length for system with combination of sequence found in STEP 1.

STEP 3

If cycle length is the same as used in STEP 1, STOP.

Otherwise, Go to STEP 4.

STEP 4

Repeat STEP 1 with cycle length found in STEP 2.

GO TO STEP 2.

Fig 4.8 Algorithm to find an optimal or near optimal solution

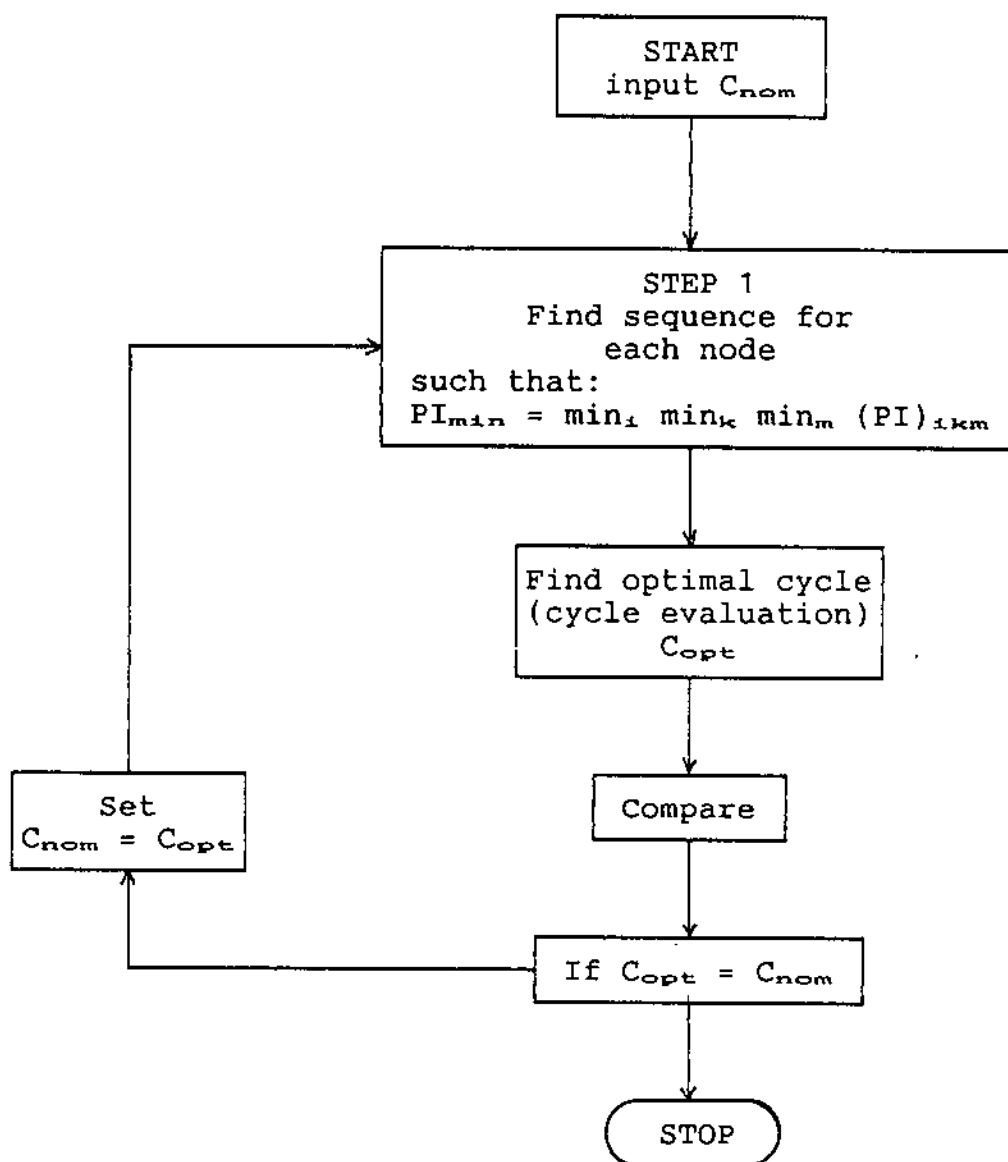


Fig 4.9 Flow chart presenting the procedure of algorithm 4.4.1) Implementation of Algorithm:

The algorithm shown in Fig 4.8 has been implemented. TRANSYT has been run with several iterations as it can be seen in the following pages. These iterations cover all the possible phase sequences for each node. In other words, 24 sequences for node 1, 6 sequences for node 2, and 6 sequences for node 3.

ITERATION : 1

Input Cycle Length: 100 seconds

Resulting Sequence: 19,5,1

Resulting PI Value: 346.93

Best Cycle Length Over Range: 120 seconds

Resulting PI Value: 349.14

Reference: Table 4.3, Fig 4.10, Fig 4.11

Table 4.3 Resulting PI's for cycle length of 100 sec.

Phase Sequence	Node			System Wide
	1	2	3	
1,1,1	165	28.2	155.5	348.65
2,2,2	163.9	29.8	166.7	360.38
3,3,3	164.3	30.4	153.2	347.97
4,4,4	163.5	31.1	161.5	356.16
5,5,5	167.4	27.3	157.3	352.02
6,6,6	164.5	28.7	158.1	351.21
7,6,1	166.1	30	154	350.03
8,1,2	165.3	28.6	168.5	362.38
9,2,3	166.2	30.1	151.7	348.05
10,3,4	163.3	30.6	161.7	355.6
11,4,5	164.2	31.1	159.9	355.23
12,5,6	164.8	28.9	154.7	348.43
13,6,1	167.5	28.6	151.4	347.55
14,5,2	163.3	29.3	166.6	349.25
15,4,3	166.1	30.9	153.9	350.91
16,3,4	164.5	30.5	163.5	358.52
17,2,5	167.3	29.8	159.3	356.44
18,6,1	164.7	28.2	151.4	344.24
19,5,2	162.8	30.4	166.7	359.95
20,1,6	164.4	29.4	152.7	346.53
21,2,1	164.3	30.4	152.9	347.65
22,3,2	164.1	31.3	166.6	361.97
23,4,3	165.8	32.3	154.2	352.31
24,5,4	164.6	28.4	161.4	354.37

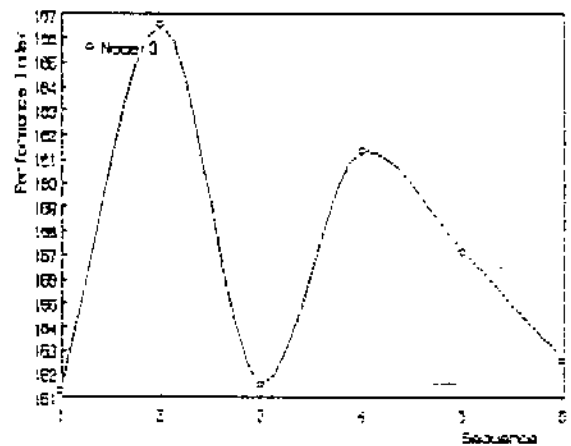
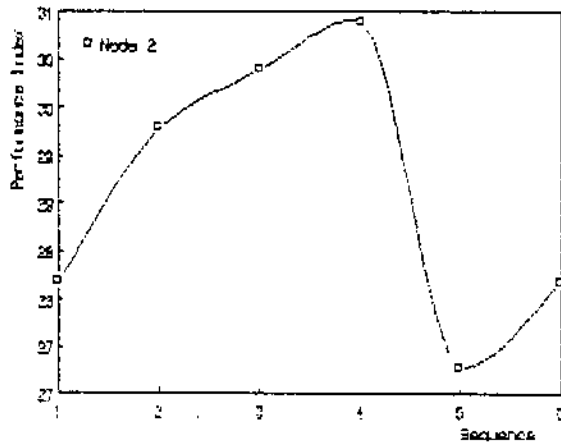
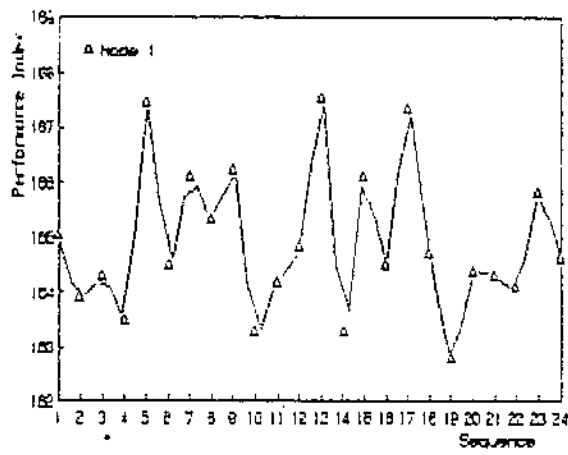


Fig 4.1Q PI values versus phase sequences for each node (100 sec)

Phase Sequence	System Wide PI
19,5,1	346.93

DATE OF RUN: 12/26/90 START TIME OF RUN: 14:17:11

BEST CYCLE LENGTH = 120 SEC.

MAX Cycle Evaluation Using Phase Sequence 19,5,1

CYCLE EVALUATION SUMMARY PERFORMANCE									
CYCLE NO.	START (SEC)	STOP (SEC)	AVERAGE FLOW (L/HR)	PERCENT STOP	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	NUMBER SATURATED LINKS		
90	192.86	65	1775.4	2.2	352.9	2.2	2		
91	175.25	66	1681.6	2.2	351.3	2.2	2		
105	175.69	63	1645.4	2.2	343.4	2.2	2		
110	173.15	64	1652.3	2.2	347.2	2.2	2		
115	172.25	63	1634.0	2.2	342.6	2.2	2		
120	172.99	64	1642.9	2.2	344.9	2.2	2		
130	174.51	64	1652.8	2.2	347.4	2.2	2		

PERFORMANCE WITH OPTIMAL SETTINGS									
MODE LINK NO.	LINK NO.	FLOW (GPM)	SAT DEGREE (%)	TOTAL FLOW (GPM)	UNIFORM DELAY (SEC)	RANDOM DELAY (SEC)	TOTAL DELAY (SEC)	UNIFORM STOP (SEC)	RANDOM STOP (SEC)
1	101	1500P	134M	2.00	1.89	1.75	3.64	1.75	1.89
1	102	180	1012	39.00	16.92	12.29	29.21	12.29	16.92
1	103	66	1880P	135M	4.15	3.71	7.86	3.71	4.15
1	105	50	1045	132M	10.00	4.86	14.86	4.86	10.00
1	106	264	1045	132M	22.80	15.41	38.21	15.41	22.80
1	107	878	1075	165M	35.40	4.89	40.29	4.89	35.40
1	108	270	1075	165M	108.00	4.55	112.55	4.55	108.00
1	110	540	2450P	107M	230.04	21.49	251.53	21.49	230.04
1	111	136	1105	107M	71.59	6.92	78.51	6.92	71.59
1	112	180	1105	107M	71.59	1.21	72.80	1.21	71.59
1	2570	MAX = 185M	912.09	238.92	39.97	173.05	213.02	238.92	1827.46
2	201	850	1200	96M	340.00	9.53	349.53	9.53	340.00
2	202	100	1200	96M	1.14	3.75	4.89	3.75	1.14
2	204	884	2075	71	376.58	3.29	379.87	3.29	376.58
2	205	376	1100	105M	160.18	4.15	164.33	4.15	160.18
2	206	526	1200	21	45.51	1.23	46.74	1.23	45.51
2	207	256	1200	21	45.51	4.00	50.51	4.00	45.51
2	3024	MAX = 105M	1060.84	67.62	21.91	15.78	37.59	15.78	37.59
3	301	160	1950P	154M	48.00	3.34	51.34	3.34	48.00
3	302	250	1200	21	75.00	3.00	78.00	3.00	75.00
3	303	464	2015	154M	135.20	9.59	144.79	9.59	135.20
3	304	226	100P	215M	125.60	41.59	167.19	41.59	125.60
3	305	112	2045	115M	51.20	7.23	58.43	7.23	51.20
3	306	358	250P	119M	240.37	10.23	250.60	10.23	240.37
3	307	158	250P	119M	43.12	3.32	46.44	3.32	43.12
3	309	854	250P	77	256.20	5.19	261.39	5.19	256.20
3	310	96	250P	77	256.80	12.45	269.25	12.45	256.80
3	3684	MAX = 215M	1043.08	231.08	34.58	187.15	201.73	187.15	231.08

TOTAL DISTANCE TRAVELLED									
MODE LINK NO.	LINK NO.	TRAVEL TIME (SEC)	UNIFORM DELAY (SEC)	RANDOM DELAY (SEC)	TOTAL DELAY (SEC)	UNIFORM STOP (SEC)	RANDOM STOP (SEC)	TOTAL STOP (SEC)	PERFORMANCE INDEX
3016.01	537.62	96.46	355.97	452.44	175.55	5908.00	642	1859.46	5.61

ROUTE SUMMARY REPORT									
MODE LINK NO.	LINK NO.	FLOW (GPM)	SAT DEGREE (%)	TOTAL FLOW (GPM)	UNIFORM DELAY (SEC)	RANDOM DELAY (SEC)	TOTAL DELAY (SEC)	UNIFORM STOP (SEC)	RANDOM STOP (SEC)
1	107	844	1050P	165M	327.60	108.43	436.03	108.43	327.60
2	307	1356	250P	119M	240.37	64.16	304.53	64.16	240.37
3	3066	MAX = 165M	954.55	188.70	22.00	138.14	160.14	160.14	188.70
4	110	540	250P	107M	230.04	21.48	251.52	21.48	230.04
5	309	854	2150P	77	256.20	12.41	268.61	12.41	256.20
UP	1352	MAX = 107M	505.01	47.28	15.38	15.55	30.93	15.55	30.93

TOTAL PERFORMANCE									
MODE LINK NO.	LINK NO.	TRAVEL TIME (SEC)	UNIFORM DELAY (SEC)	RANDOM DELAY (SEC)	TOTAL DELAY (SEC)	UNIFORM STOP (SEC)	RANDOM STOP (SEC)	TOTAL STOP (SEC)	PERFORMANCE INDEX
1535.56	234.08	37.38	153.69	191.08	136.54	3331.60	642	1041.20	6.58

Fig 4.11 Optimal solution using phase sequence 19,5,1

ITERATION : 2

Input Cycle Length: 120 seconds

Resulting Sequence: 6,4,3

Resulting PI Value: 341.53

Best Cycle Length Over Range: 125 seconds

Resulting PI Value: 342.84

Reference: Table 4.4, Fig 4.12, Fig 4.13

Table 4.4 Resulting PI's for cycle length of 120 sec

Phase Sequence	Node			System Wide
	1	2	3	
1,1,1	164.2	30.4	176.8	371.49
2,2,2	161.4	32.4	161.9	355.7
3,3,3	164.7	36.6	149.2	350.57
4,4,4	163.1	29.1	149.8	341.99
5,5,5	162.4	33.2	146.4	342.07
6,6,6	161.2	33.1	147.6	341.91
7,6,1	167.6	34.1	174	375.65
8,1,2	169.5	29.3	162.3	361.05
9,2,3	175.9	32.7	150	358.58
10,3,4	177.8	36.3	149	363.1
11,4,5	165.6	28.9	150.1	344.63
12,5,6	167.8	34.7	151	353.51
13,6,1	179.2	33	168.6	380.75
14,5,2	164.4	32	161.2	357.5
15,4,3	171	28.3	145.9	345.27
16,3,4	165.1	37.1	152.9	355.14
17,2,5	163.7	36.3	148.1	348.03
18,6,1	163.6	32.5	168.8	364.96
19,5,2	161.4	33.1	161.8	356.21
20,1,6	171.6	29.5	148.3	349.47
21,2,1	163	35.8	171	369.8
22,3,2	162.2	33.4	162.1	357.65
23,4,3	167.9	28.6	147.3	343.72
24,5,4	177	33.2	148.4	358.67

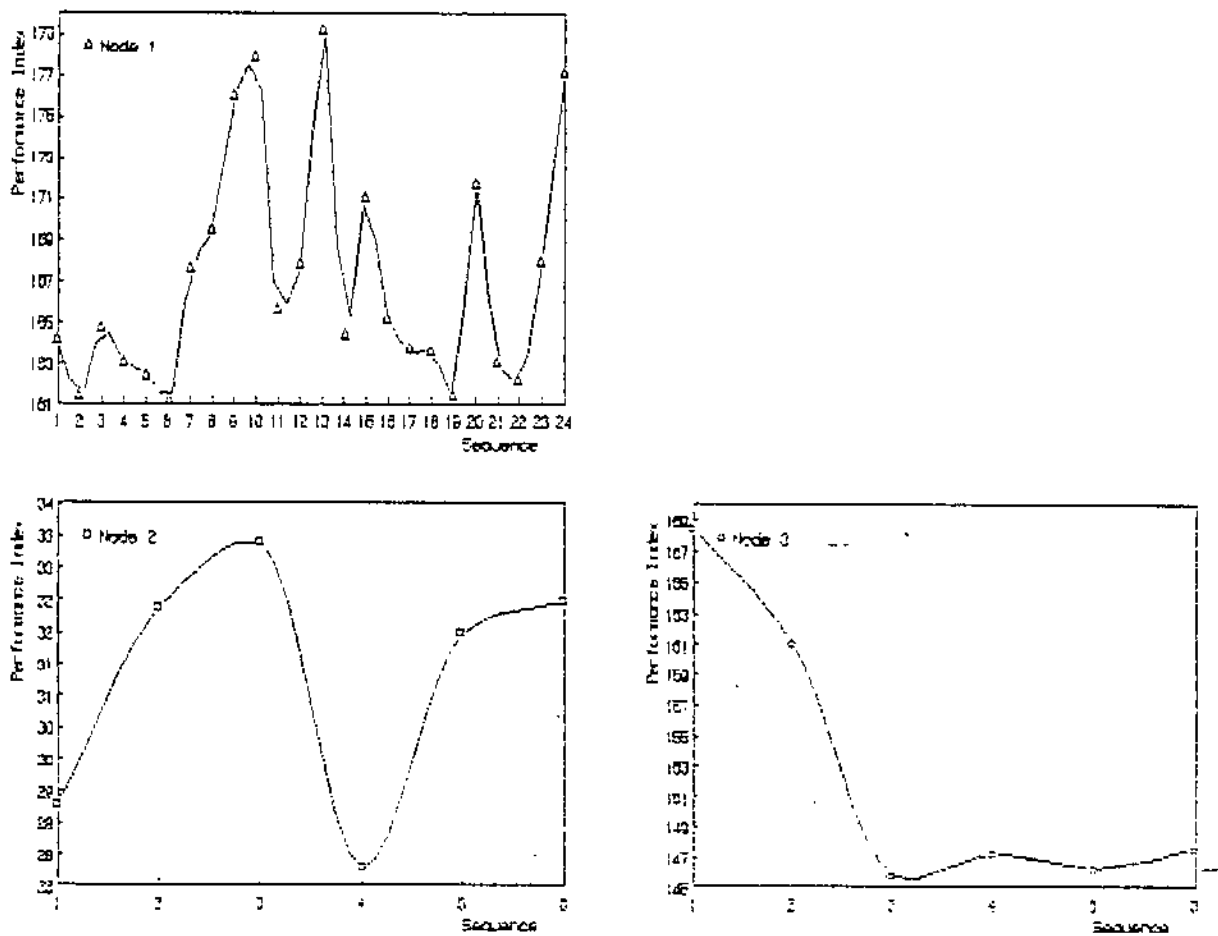


Fig 4.12 PI values versus phase sequences for each node (120 sec)

Phase Sequence	System Wide PI
6, 4, 3	341.53

DATE OF RUN: 12/26/90 START TIME OF RUN: 14: 3: 1

BEST CYCLE LENGTH = 125 SEC.

*** Cycle Evaluation Using Phase Sequence 6.4.3

CYCLE EVALUATION SUMMARY PERFORMANCE			
CYCLE LENGTH (SECS)	AVERAGE DELAY (SECS)	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX SATURATED LINKS
90	190.16	1591.9	357.7
95	181.06	1700.0	355.9
100	177.88	1822.6	352.7
105	174.73	1967.8	349.2
110	171.62	2136.0	345.6
115	168.54	2328.0	342.1
120	165.50	2545.0	338.5
125	162.54	2787.0	335.0
130	159.66	3055.0	331.5

PERFORMANCE WITH OPTIMAL SETTINGS			
NO. LINK	FLOW (VEH/H)	DEGREE (C)	PERFORMANCE INDEX
1	101	1900P	122M
1	102	1810P	122M
1	103	1770P	122M
1	104	1740P	122M
1	105	1710P	122M
1	106	1680P	122M
1	107	1650P	122M
1	108	1620P	122M
1	109	1590P	122M
1	110	1560P	122M
1	111	1530P	122M
1	112	1500P	122M

TOTAL DELAY (VEH-H)				TOTAL FUEL CONSUMPTION (GAL-H)			
NO. LINK	UNIFORM	RANDOM	TOTAL	UNIFORM	RANDOM	TOTAL	PERFORMANCE INDEX
1	1.20	1.74	2.94	1.20	1.74	2.94	357.7
2	1.99	2.96	4.95	1.99	2.96	4.95	355.9
3	1.06	1.42	2.48	1.06	1.42	2.48	352.7
4	4.80	3.25	8.05	4.80	3.25	8.05	349.2
5	15.73	10.74	26.47	15.73	10.74	26.47	345.6
6	47.71	32.80	80.51	47.71	32.80	80.51	342.1
7	5.03	3.66	8.69	5.03	3.66	8.69	338.5
8	7.11	5.00	12.11	7.11	5.00	12.11	335.0
9	2.05	1.71	3.76	2.05	1.71	3.76	331.5
10	49.09	34.02	83.11	49.09	34.02	83.11	328.0
11	0.88	0.60	1.48	0.88	0.60	1.48	324.5
12	3.45	2.48	5.93	3.45	2.48	5.93	321.0
13	8.00	5.00	13.00	8.00	5.00	13.00	317.5
14	20.02	15.53	35.55	20.02	15.53	35.55	314.0
15	32.88	23.26	56.14	32.88	23.26	56.14	310.5
16	11.24	8.00	19.24	11.24	8.00	19.24	307.0
17	6.84	4.80	11.64	6.84	4.80	11.64	303.5
18	1.44	1.00	2.44	1.44	1.00	2.44	300.0
19	2.03	1.44	3.47	2.03	1.44	3.47	296.5
20	3.47	2.48	5.95	3.47	2.48	5.95	293.0
21	11.23	8.00	19.23	11.23	8.00	19.23	289.5
22	65.46	45.11	110.57	65.46	45.11	110.57	286.0
23	22.23	15.55	37.78	22.23	15.55	37.78	282.5
24	0.00	0.00	0.00	0.00	0.00	0.00	279.0
25	11.24	8.00	19.24	11.24	8.00	19.24	275.5
26	3.45	2.48	5.93	3.45	2.48	5.93	272.0
27	8.00	5.00	13.00	8.00	5.00	13.00	268.5
28	20.02	15.53	35.55	20.02	15.53	35.55	265.0
29	32.88	23.26	56.14	32.88	23.26	56.14	261.5
30	11.24	8.00	19.24	11.24	8.00	19.24	258.0
31	6.84	4.80	11.64	6.84	4.80	11.64	254.5
32	1.44	1.00	2.44	1.44	1.00	2.44	251.0
33	2.03	1.44	3.47	2.03	1.44	3.47	247.5
34	3.47	2.48	5.95	3.47	2.48	5.95	244.0
35	11.23	8.00	19.23	11.23	8.00	19.23	240.5
36	65.46	45.11	110.57	65.46	45.11	110.57	237.0
37	22.23	15.55	37.78	22.23	15.55	37.78	233.5
38	0.00	0.00	0.00	0.00	0.00	0.00	230.0
39	11.24	8.00	19.24	11.24	8.00	19.24	226.5
40	3.45	2.48	5.93	3.45	2.48	5.93	223.0
41	8.00	5.00	13.00	8.00	5.00	13.00	219.5
42	20.02	15.53	35.55	20.02	15.53	35.55	216.0
43	32.88	23.26	56.14	32.88	23.26	56.14	212.5
44	11.24	8.00	19.24	11.24	8.00	19.24	209.0
45	6.84	4.80	11.64	6.84	4.80	11.64	205.5
46	1.44	1.00	2.44	1.44	1.00	2.44	202.0
47	2.03	1.44	3.47	2.03	1.44	3.47	198.5
48	3.47	2.48	5.95	3.47	2.48	5.95	195.0
49	11.23	8.00	19.23	11.23	8.00	19.23	191.5
50	65.46	45.11	110.57	65.46	45.11	110.57	188.0
51	22.23	15.55	37.78	22.23	15.55	37.78	184.5
52	0.00	0.00	0.00	0.00	0.00	0.00	181.0
53	11.24	8.00	19.24	11.24	8.00	19.24	177.5
54	3.45	2.48	5.93	3.45	2.48	5.93	174.0
55	8.00	5.00	13.00	8.00	5.00	13.00	170.5
56	20.02	15.53	35.55	20.02	15.53	35.55	167.0
57	32.88	23.26	56.14	32.88	23.26	56.14	163.5
58	11.24	8.00	19.24	11.24	8.00	19.24	160.0
59	6.84	4.80	11.64	6.84	4.80	11.64	156.5
60	1.44	1.00	2.44	1.44	1.00	2.44	153.0
61	2.03	1.44	3.47	2.03	1.44	3.47	149.5
62	3.47	2.48	5.95	3.47	2.48	5.95	146.0
63	11.23	8.00	19.23	11.23	8.00	19.23	142.5
64	65.46	45.11	110.57	65.46	45.11	110.57	139.0
65	22.23	15.55	37.78	22.23	15.55	37.78	135.5
66	0.00	0.00	0.00	0.00	0.00	0.00	132.0
67	11.24	8.00	19.24	11.24	8.00	19.24	128.5
68	3.45	2.48	5.93	3.45	2.48	5.93	125.0
69	8.00	5.00	13.00	8.00	5.00	13.00	121.5
70	20.02	15.53	35.55	20.02	15.53	35.55	118.0
71	32.88	23.26	56.14	32.88	23.26	56.14	114.5
72	11.24	8.00	19.24	11.24	8.00	19.24	111.0
73	6.84	4.80	11.64	6.84	4.80	11.64	107.5
74	1.44	1.00	2.44	1.44	1.00	2.44	104.0
75	2.03	1.44	3.47	2.03	1.44	3.47	100.5
76	3.47	2.48	5.95	3.47	2.48	5.95	97.0
77	11.23	8.00	19.23	11.23	8.00	19.23	93.5
78	65.46	45.11	110.57	65.46	45.11	110.57	90.0
79	22.23	15.55	37.78	22.23	15.55	37.78	86.5
80	0.00	0.00	0.00	0.00	0.00	0.00	83.0
81	11.24	8.00	19.24	11.24	8.00	19.24	79.5
82	3.45	2.48	5.93	3.45	2.48	5.93	76.0
83	8.00	5.00	13.00	8.00	5.00	13.00	72.5
84	20.02	15.53	35.55	20.02	15.53	35.55	69.0
85	32.88	23.26	56.14	32.88	23.26	56.14	65.5
86	11.24	8.00	19.24	11.24	8.00	19.24	62.0
87	6.84	4.80	11.64	6.84	4.80	11.64	58.5
88	1.44	1.00	2.44	1.44	1.00	2.44	55.0
89	2.03	1.44	3.47	2.03	1.44	3.47	51.5
90	3.47	2.48	5.95	3.47	2.48	5.95	48.0
91	11.23	8.00	19.23	11.23	8.00	19.23	44.5
92	65.46	45.11	110.57	65.46	45.11	110.57	41.0
93	22.23	15.55	37.78	22.23	15.55	37.78	37.5
94	0.00	0.00	0.00	0.00	0.00	0.00	34.0
95	11.24	8.00	19.24	11.24	8.00	19.24	30.5
96	3.45	2.48	5.93	3.45	2.48	5.93	27.0
97	8.00	5.00	13.00	8.00	5.00	13.00	23.5
98	20.02	15.53	35.55	20.02	15.53	35.55	20.0
99	32.88	23.26	56.14	32.88	23.26	56.14	16.5
100	11.24	8.00	19.24	11.24	8.00	19.24	13.0
101	6.84	4.80	11.64	6.84	4.80	11.64	9.5
102	1.44	1.00	2.44	1.44	1.00	2.44	6.0
103	2.03	1.44	3.47	2.03	1.44	3.47	2.5
104	3.47	2.48	5.95	3.47	2.48	5.95	0.0
105	11.23	8.00	19.23	11.23	8.00	19.23	0.0
106	65.46	45.11	110.57	65.46	45.11	110.57	0.0
107	22.23	15.55	37.78	22.23	15.55	37.78	0.0
108	0.00	0.00	0.00	0.00	0.00	0.00	0.0
109	11.24	8.00	19.24	11.24	8.00	19.24	0.0
110	3.45	2.48	5.93	3.45	2.48	5.93	0.0
111	8.00	5.00	13.00	8.00	5.00	13.00	0.0
112	20.02	15.53	35.55	20.02	15.53	35.55	0.0
113	32.88	23.26	56.14	32.88	23.26	56.14	0.0
114	11.24	8.00	19.24	11.24	8.00	19.24	0.0
115	6.84	4.80	11.64	6.84	4.80	11.64	0.0
116	1.44	1.00	2.44	1.44	1.00	2.44	0.0
117	2.03	1.44	3.47	2.03	1.44	3.47	0.0
118	3.47	2.48	5.95	3.47	2.48	5.95	0.0
119	11.23	8.00	19.23	11.23	8.00	19.23	0.0
120	65.46	45.11	110.57	65.46	45.11	110.57	0.0
121	22.23	15.55	37.78	22.23	15.55	37.78	0.0
122	0.00	0.00	0.00	0.00	0.00	0.00	0.0
123	11.24	8.00	19.24	11.24	8.00	19.24	0.0
124	3.45	2.48	5.93	3.45	2.48	5.93	0.0
125	8.00	5.00	13.00	8.00	5.00	13.00	0.0
126	20.02	15.53	35.55	20.02	15.53	35.55	0.0
127	32.88	23.26	56.14	32.88	23.26	56.14	0.0
128	11.24	8.00	19.24	11.24	8.00	19.24	0.0
129	6.84	4.80	11.64	6.84	4.80	11.64	0.0
130	1.44	1.00	2.44	1.44	1.00	2.44	0.0
131	2.03	1.44	3.47	2.03	1.44	3.47	0.0
132	3.47	2.48	5.95	3.47	2.48	5.95	0.0
133	11.23	8.00	19.23	11.23	8.00	19.23	0.0
134	65.46	45.11	110.57	65.46	45.11	110.57	0.0
135	22.23	15.55	37.78	22.23	15.55	37.78	0.0
136	0.00	0.00	0.00	0.00	0.00	0.00	0.0
137	11.24	8.00	19.24	11.24	8.00	19.24	0.0
138	3.45	2.48	5.93	3.45	2.48	5.93	0.0
139	8.00	5.00	13.00	8.00	5.00	13.00	0.0
140	20.02	15.53	35.55	20.02	15.53	35.55	0.0
141	32.88	23.26	56.14	32.88	23.26	56.14	0.0

ITERATION : 3

Input Cycle Length: 125 seconds

Resulting Sequence: 2,1,3

Resulting PI Value: 339.53

Best Cycle Length Over Range: 125 seconds

Resulting PI Value: 337.22

Reference: Table 4.5, Fig 4.14, Fig 4.15

Table 4.5 Resulting PI's for cycle length of 125 sec

Phase Sequence	Node			System Wide
	1	2	3	
1,1,1	165.7	28.2	176.6	370.42
2,2,2	161.4	31.6	159.9	352.88
3,3,3	170.1	38.3	149.3	357.78
4,4,4	162.6	31.4	148	342.05
5,5,5	167.6	31.8	150.5	349.78
6,6,6	163.3	31.3	147.5	342.03
7,6,1	167	36.6	177.8	381.5
8,1,2	167.5	27.6	167	362.16
9,2,3	182.2	32	148.3	362.59
10,3,4	178.3	45.1	147.2	370.64
11,4,5	164.9	30.7	147.7	343.34
12,5,6	167.6	35.6	152	355.27
13,6,1	185.1	30.9	171.2	387.22
14,5,2	170	33.7	158.3	362
15,4,3	172.7	29.5	145.5	347.8
16,3,4	164.3	38.5	152.4	355.23
17,2,5	166.3	38.3	148.4	353.04
18,6,1	163.7	34.9	173	371.61
19,5,2	162.5	34.6	160	357.17
20,1,6	177.2	29.8	147.6	354.54
21,2,1	163.9	35	174.7	373.58
22,3,2	162.1	35.1	164.3	361.55
23,4,3	171.5	29.8	145.3	346.69
24,5,4	177.9	33.6	145.7	357.24

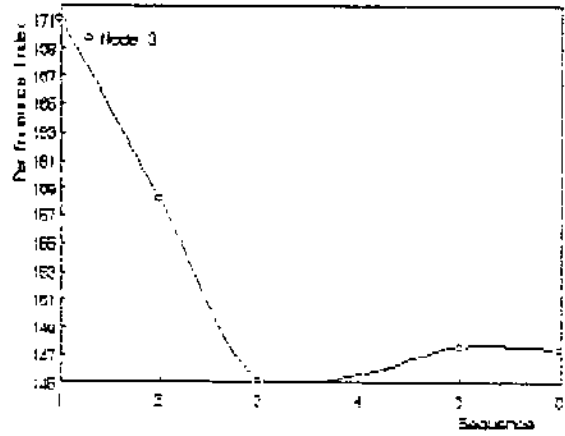
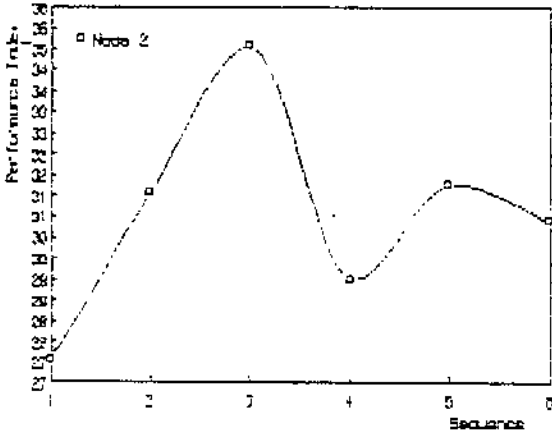
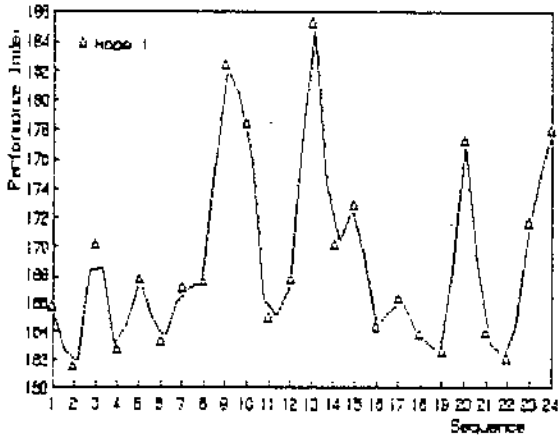


Fig 4.14 PI values versus phase sequences for each node (125 sec)

Phase Sequence	System Wide PI
2, 1, 3	339.53

*** Cycle Evaluation Using Phase Sequence 2,1,3

CYCLE EVALUATION SUMMARY PERFORMANCE DATE OF RUN: 12/26/90 STREET TIME OF RUN: 13:11:13

CYCLE LENGTH (SECS)	STEP	PERCENT	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	NUMBER LINKS
35	10	17.7	147.5	32.1	23
100	35	17.7	166.8	34.1	22
105	35	17.7	169.5	34.1	21
110	35	17.7	172.2	34.1	21
115	35	17.7	174.9	34.1	21
120	35	17.7	177.6	34.1	21
125	35	17.7	180.3	34.1	21
130	35	17.7	183.0	34.1	21

<PERFORMANCE WITH OPTIMAL SETTINGS>

LINK NO.	TRAVEL TIME (SECS)	DEGREE OF SRT (DEG)	TOTAL TRAVEL TIME (SECS)	UNIFORM DELAY (SECS)	TOTAL DELAY (SECS)	AVERAGE DELAY (SECS)	UNIFORM STOP (SECS)	MAX BRK (G)	QUEUE CAPACITY (VEH/CLK)	FUEL CONSUM (GAL/HR)	PHASE LENGTH (SECS)	LINK NO.
1	101	10	1900P	150M	2.00	1.11	1.20	1.05	378.8	1.77	6722	14
1	102	190	1015	150M	19.20	10.65	3.69	19.39	378.6	1.77	6722	14
1	103	96	1015	150M	19.20	10.65	3.69	19.39	378.6	1.77	6722	14
1	104	56	1045	150M	17.00	8.56	3.17	17.17	378.6	1.77	6722	14
1	105	56	1045	150M	17.00	8.56	3.17	17.17	378.6	1.77	6722	14
1	106	24	1045	150M	17.00	8.56	3.17	17.17	378.6	1.77	6722	14
1	107	0	1350P	151M	23.7	12.27	4.29	23.15	452.1	2.77	5322	104
1	108	24	1350P	151M	23.7	12.27	4.29	23.15	452.1	2.77	5322	104
1	109	24	1350P	151M	23.7	12.27	4.29	23.15	452.1	2.77	5322	104
1	110	24	1350P	151M	23.7	12.27	4.29	23.15	452.1	2.77	5322	104
1	111	24	1350P	151M	23.7	12.27	4.29	23.15	452.1	2.77	5322	104
1	112	169	1105	103M	71.57	5.27	1.06	71.57	159.24	9522	110	

<SYSTEM WIDE TOTALS INCLUDING ALL LINKS>

TOTAL TRAVEL TIME (SECS)	TOTAL DELAY (SECS)	TOTAL UNIFORM DELAY (SECS)	TOTAL AVERAGE DELAY (SECS)	TOTAL UNIFORM STOP (SECS)	TOTAL MAX BRK (G)	TOTAL QUEUE CAPACITY (VEH/CLK)	TOTAL FUEL CONSUM (GAL/HR)	TOTAL PHASE LENGTH (SECS)	TOTAL LINK NO.			
3024	104M	1060.84	62.55	17.11	15.51	32.63	38.6	1603.2	5322	227.41	PI = 28.7	
2	3024	104M	1040.09	222.22	33.28	159.59	192.87	189.5	1533.44	4232	668.80	PI = 145.9

<ROUTE SUMMARY REPORT>

ROUTE NO.	LINK NO.	TOTAL TRAVEL TIME (SECS)	TOTAL DELAY (SECS)	TOTAL UNIFORM DELAY (SECS)	TOTAL AVERAGE DELAY (SECS)	TOTAL UNIFORM STOP (SECS)	TOTAL MAX BRK (G)	TOTAL QUEUE CAPACITY (VEH/CLK)	TOTAL FUEL CONSUM (GAL/HR)	TOTAL PHASE LENGTH (SECS)	TOTAL LINK NO.			
DOWN	1	101	644	1950P	151M	337.60	98.27	17.27	71.35	98.62	378.0	51		
DOWN	2	304	841	2075	71	376.56	12.62	1.70	8.7	167.8	1922	6		
DOWN	3	307	1358	2150P	108M	240.57	256.76	2.90	27.44	50.53	2922	17		
UP	1	110	3086	MAX = 151M	954.55	147.65	21.67	99.22	121.09	141.3	1127.2	3722	455.01	PI = 92.2
UP	2	206	550	2250P	103M	230.77	17.19	3.60	4.64	10.12	71.8	511.94	9822	25
UP	3	305	854	2150P	98M	258.20	11.12	3.43	3.80	3.80	16.0	815.8	6022	21
UP	4	305	1352	MAX = 103M	585.01	41.13	12.51	12.18	24.68	45.5	1536.6	7322	151.50	PI = 32.8

Fig 4.15 Optimal solution using phase sequence 2,1,3

(Check Iteration)

ITERATION : 4 (to test the algorithm)

Input Cycle Length: 115 seconds

Resulting Sequence: 19,1,3

Resulting PI Value: 339.35

Best Cycle Length Over Range: 125 seconds

Resulting PI Value: 337.84 (greater than iteration 3)

Reference: Table 4.6, Fig 4.16, Fig 4.17

Table 4.6 Resulting PI's for cycle length of 115 sec

Phase Sequence	Node			System Wide
	1	2	3	
1,1,1	165	28	168.7	361.69
2,2,2	162.2	33.2	165	360.42
3,3,3	166.2	35	150.7	351.89
4,4,4	163.5	29.2	151.3	343.96
5,5,5	165.1	29.9	150.4	345.37
6,6,6	161.1	31.1	148.5	340.63
7,6,1	167.2	32	168.2	367.45
8,1,2	166.6	27.5	168.6	362.68
9,2,3	170	33.5	149.6	353.13
10,3,4	172.6	32.4	152	357
11,4,5	164	29.1	151.1	344.15
12,5,6	166.4	32.4	151.4	350.17
13,6,1	172.9	31.2	165.5	369.61
14,5,2	165	31.6	163.9	360.6
15,4,3	168.7	29.9	148.8	346.39
16,3,4	164	35	155	354.01
17,2,5	162.7	36.8	150	349.45
18,6,1	162.8	30.6	166.6	359.98
19,5,2	161.1	32.7	165	358.71
20,1,6	170.7	28.5	151.3	350.44
21,2,1	161.7	33.5	168.2	363.34
22,3,2	161.9	33.9	165.4	361.12
23,4,3	166.9	28.7	148.1	343.72
24,5,4	170.6	30.3	151	351.92

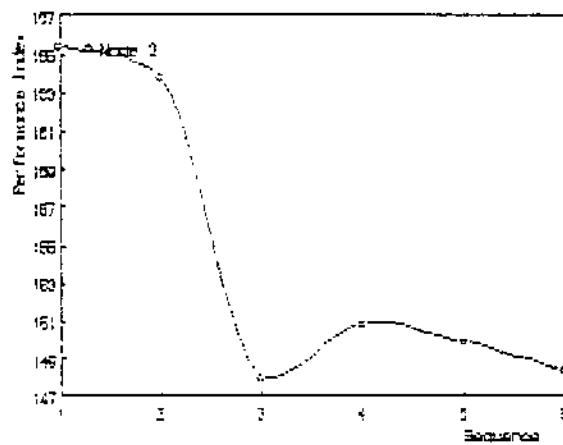
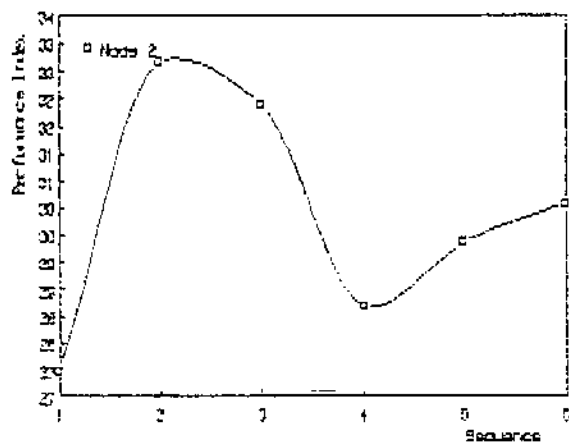
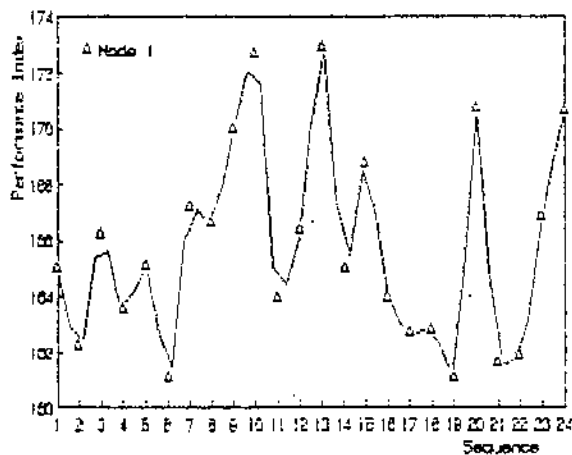


Fig 4.16 PI values versus phase sequences for each node (115 sec)

Phase Sequence	System Wide PI
19,1,3	339.35

DATE OF RUN: 12/26/90 START TIME OF RUN: 15:35:10

BEST CYCLE LENGTH = 125 SEC.

CYCLE EVALUATION USING PHASE SEQUENCE 19,1,2

CYCLE EVALUATION SUMMARY PERFORMANCE									
CYCLE LENGTH (SEC)	STEP (STEP)	AVERAGE DELAY (SEC/VEH)	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	SATURATED LINKS	NUMBER	UNIFORM DELAY (SEC/VEH)	PERFORMANCE INDEX	LINK NO.
95	1	179.12	1704.2	351.0	22	22	1671.1	352.2	101
100	3	177.12	1665.1	350.6	22	22	1659.6	350.6	102
105	5	175.25	1627.5	347.0	22	22	1627.0	347.0	103
110	7	173.38	1590.0	343.4	22	22	1590.0	343.4	104
115	9	171.51	1552.5	339.8	22	22	1552.5	339.8	105
120	11	169.64	1515.0	336.2	22	22	1515.0	336.2	106
125	13	167.77	1477.5	332.6	22	22	1477.5	332.6	107
130	15	165.90	1440.0	329.0	22	22	1440.0	329.0	108
135	17	164.03	1402.5	325.4	22	22	1402.5	325.4	109
140	19	162.16	1365.0	321.8	22	22	1365.0	321.8	110
145	21	160.29	1327.5	318.2	22	22	1327.5	318.2	111
150	23	158.42	1290.0	314.6	22	22	1290.0	314.6	112
155	25	156.55	1252.5	311.0	22	22	1252.5	311.0	113
160	27	154.68	1215.0	307.4	22	22	1215.0	307.4	114
165	29	152.81	1177.5	303.8	22	22	1177.5	303.8	115
170	31	150.94	1140.0	300.2	22	22	1140.0	300.2	116
175	33	149.07	1102.5	296.6	22	22	1102.5	296.6	117
180	35	147.20	1065.0	293.0	22	22	1065.0	293.0	118
185	37	145.33	1027.5	289.4	22	22	1027.5	289.4	119
190	39	143.46	990.0	285.8	22	22	990.0	285.8	120
195	41	141.59	952.5	282.2	22	22	952.5	282.2	121
200	43	139.72	915.0	278.6	22	22	915.0	278.6	122
205	45	137.85	877.5	275.0	22	22	877.5	275.0	123
210	47	135.98	840.0	271.4	22	22	840.0	271.4	124
215	49	134.11	802.5	267.8	22	22	802.5	267.8	125
220	51	132.24	765.0	264.2	22	22	765.0	264.2	126
225	53	130.37	727.5	260.6	22	22	727.5	260.6	127
230	55	128.50	690.0	257.0	22	22	690.0	257.0	128
235	57	126.63	652.5	253.4	22	22	652.5	253.4	129
240	59	124.76	615.0	249.8	22	22	615.0	249.8	130
245	61	122.89	577.5	246.2	22	22	577.5	246.2	131
250	63	121.02	540.0	242.6	22	22	540.0	242.6	132
255	65	119.15	502.5	239.0	22	22	502.5	239.0	133
260	67	117.28	465.0	235.4	22	22	465.0	235.4	134
265	69	115.41	427.5	231.8	22	22	427.5	231.8	135
270	71	113.54	390.0	228.2	22	22	390.0	228.2	136
275	73	111.67	352.5	224.6	22	22	352.5	224.6	137
280	75	109.80	315.0	221.0	22	22	315.0	221.0	138
285	77	107.93	277.5	217.4	22	22	277.5	217.4	139
290	79	106.06	240.0	213.8	22	22	240.0	213.8	140
295	81	104.19	202.5	210.2	22	22	202.5	210.2	141
300	83	102.32	165.0	206.6	22	22	165.0	206.6	142
305	85	100.45	127.5	203.0	22	22	127.5	203.0	143
310	87	98.58	90.0	199.4	22	22	90.0	199.4	144
315	89	96.71	52.5	195.8	22	22	52.5	195.8	145
320	91	94.84	15.0	192.2	22	22	15.0	192.2	146
325	93	92.97	-22.5	188.6	22	22	-22.5	188.6	147
330	95	91.10	-60.0	185.0	22	22	-60.0	185.0	148
335	97	89.23	-97.5	181.4	22	22	-97.5	181.4	149
340	99	87.36	-135.0	177.8	22	22	-135.0	177.8	150
345	101	85.49	-172.5	174.2	22	22	-172.5	174.2	151
350	103	83.62	-210.0	170.6	22	22	-210.0	170.6	152
355	105	81.75	-247.5	167.0	22	22	-247.5	167.0	153
360	107	79.88	-285.0	163.4	22	22	-285.0	163.4	154
365	109	78.01	-322.5	159.8	22	22	-322.5	159.8	155
370	111	76.14	-360.0	156.2	22	22	-360.0	156.2	156
375	113	74.27	-397.5	152.6	22	22	-397.5	152.6	157
380	115	72.40	-435.0	149.0	22	22	-435.0	149.0	158
385	117	70.53	-472.5	145.4	22	22	-472.5	145.4	159
390	119	68.66	-510.0	141.8	22	22	-510.0	141.8	160
395	121	66.79	-547.5	138.2	22	22	-547.5	138.2	161
400	123	64.92	-585.0	134.6	22	22	-585.0	134.6	162
405	125	63.05	-622.5	131.0	22	22	-622.5	131.0	163
410	127	61.18	-660.0	127.4	22	22	-660.0	127.4	164
415	129	59.31	-697.5	123.8	22	22	-697.5	123.8	165
420	131	57.44	-735.0	120.2	22	22	-735.0	120.2	166
425	133	55.57	-772.5	116.6	22	22	-772.5	116.6	167
430	135	53.70	-810.0	113.0	22	22	-810.0	113.0	168
435	137	51.83	-847.5	109.4	22	22	-847.5	109.4	169
440	139	50.00	-885.0	105.8	22	22	-885.0	105.8	170
445	141	48.13	-922.5	102.2	22	22	-922.5	102.2	171
450	143	46.26	-960.0	98.6	22	22	-960.0	98.6	172
455	145	44.39	-997.5	95.0	22	22	-997.5	95.0	173
460	147	42.52	-1035.0	91.4	22	22	-1035.0	91.4	174
465	149	40.65	-1072.5	87.8	22	22	-1072.5	87.8	175
470	151	38.78	-1110.0	84.2	22	22	-1110.0	84.2	176
475	153	36.91	-1147.5	80.6	22	22	-1147.5	80.6	177
480	155	35.04	-1185.0	77.0	22	22	-1185.0	77.0	178
485	157	33.17	-1222.5	73.4	22	22	-1222.5	73.4	179
490	159	31.30	-1260.0	69.8	22	22	-1260.0	69.8	180
495	161	29.43	-1297.5	66.2	22	22	-1297.5	66.2	181
500	163	27.56	-1335.0	62.6	22	22	-1335.0	62.6	182
505	165	25.69	-1372.5	59.0	22	22	-1372.5	59.0	183
510	167	23.82	-1410.0	55.4	22	22	-1410.0	55.4	184
515	169	21.95	-1447.5	51.8	22	22	-1447.5	51.8	185
520	171	20.08	-1485.0	48.2	22	22	-1485.0	48.2	186
525	173	18.21	-1522.5	44.6	22	22	-1522.5	44.6	187
530	175	16.34	-1560.0	41.0	22	22	-1560.0	41.0	188
535	177	14.47	-1597.5	37.4	22	22	-1597.5	37.4	189
540	179	12.60	-1635.0	33.8	22	22	-1635.0	33.8	190
545	181	10.73	-1672.5	30.2	22	22	-1672.5	30.2	191
550	183	8.86	-1710.0	26.6	22	22	-1710.0	26.6	192
555	185	7.00	-1747.5	23.0	22	22	-1747.5	23.0	193
560	187	5.13	-1785.0	19.4	22	22	-1785.0	19.4	194
565	189	3.26	-1822.5	15.8	22	22	-1822.5	15.8	195
570	191	1.39	-1860.0	12.2	22	22	-1860.0	12.2	196
575	193	-0.48	-1897.5	8.6	22	22	-1897.5	8.6	197
580	195	-2.35	-1935.0	5.0	22	22	-1935.0	5.0	198
585	197	-4.22	-1972.5	1.4	22	22	-1972.5	1.4	199
590	199	-6.09	-2010.0	-2.2	22	22	-2010.0	-2.2	200
595	201	-7.96	-2047.5	-5.8	22	22	-2047.5	-5.8	201
600	203	-9.83	-2085.0	-9.4	22	22	-2085.0	-9.4	202
605	205	-11.70	-2122.5	-13.0	22	22	-2122.5	-13.0	203
610	207	-13.57	-2160.0	-16.6	22	22	-2160.0	-16.6	204
615	209	-15.44	-2197.5	-20.2	22	22	-2197.5	-20.2	205
620	211	-17.31	-2235.0	-23.8	22	22	-2235.0	-23.8	206
625	213	-19.18	-2272.5	-27.4	22	22	-2272.5	-27.4	207
630	215	-21.05	-2310.0	-31.0	22	22	-2310.0	-31.0	208
635	217	-22.92	-2347.5	-34.6	22	22	-2347.5	-34.6	209
640	219	-24.79	-2385.0	-38.2	22	22	-2385.0	-38.2	210
645	221	-26.66	-2422.5	-41.8	22	22	-2422.5	-41.8	211
650	223	-28.53	-2460.0	-45.4	22	22	-2460.0	-45.4	212
655	225	-30.40	-2497.5	-49.0	22	22	-2497.5	-49.0	213
660	227	-32.27	-2535.0	-52.6	22	22	-2535.0	-52.6	214
665	229	-34.14	-2572.5	-56.2	22	22	-2572.5	-56.2	215
670	231	-36.0							

(Check Iteration)

ITERATION : 5 (to test the algorithm)

Input Cycle Length: 110 seconds

Resulting Sequence: 19,5,6

Resulting PI Value: 345.57

Best Cycle Length Over Range: 125 seconds

Resulting PI Value: 344.82 (greater than iteration 3)

Reference: Table 4.7, Fig 4.18, Fig 4.19

Table 4.7 Resulting PI's for cycle length of 110 sec

Phase Sequence	Node			System Wide
	1	2	3	
1,1,1	163.6	27.8	164.2	355.50
2,2,2	161.8	30.7	169.3	361.75
3,3,3	163.2	33.8	152.4	349.29
4,4,4	163.4	29.0	154.0	346.45
5,5,5	166.9	27.4	151.6	345.93
6,6,6	162.1	28.3	149.5	339.92
7,6,1	167.9	30.0	166.9	364.67
8,1,2	165.9	27.5	166.5	359.88
9,2,3	171.2	31.3	152.0	354.57
10,3,4	167.3	33.7	154.9	355.81
11,4,5	162.8	28.8	153.5	345.11
12,5,6	164.5	30.9	151.0	346.46
13,6,1	173.6	29.0	162.4	365...
14,5,2	162.3	30.6	162.7	355.52
15,4,3	165.6	28.4	149.0	343.03
16,3,4	165.1	31.5	157.4	354.08
17,2,5	163.7	34.4	151.3	349.42
18,6,1	163.1	28.3	163.1	354.51
19,5,2	161.1	31.0	169.5	361.58
20,1,6	164.0	28.0	147.4	339.40
21,2,1	161.9	31.3	164.5	357.63
22,3,2	163.3	32.5	163.4	359.29
23,4,3	164.9	27.8	148.7	341.37
24,5,4	165.7	28.7	153.8	348.29

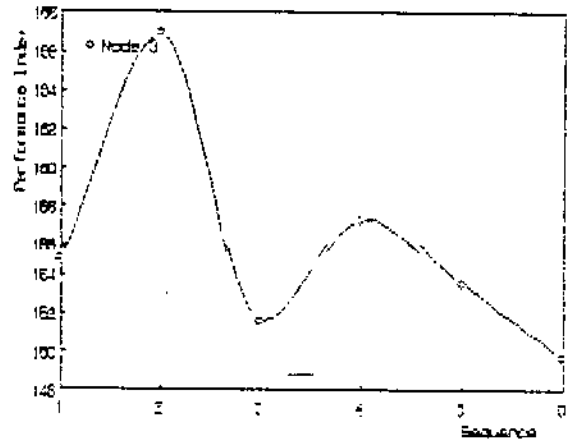
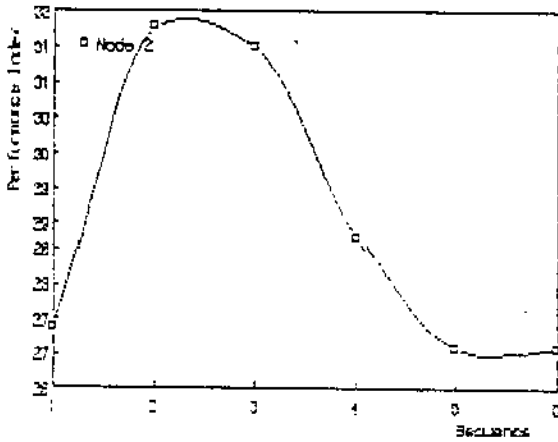
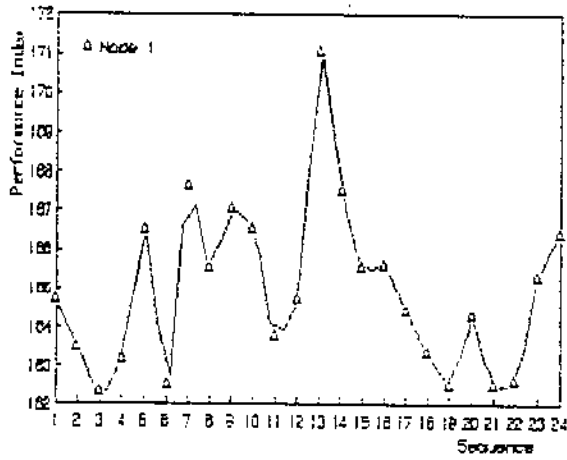


Fig. 4.18 PI values versus phase sequences for each node (110 sec)

Phase Sequence	System Wide PI
19, 5, 6	345.57

DATE OF RUN: 2.10.81 START TIME OF RUN: 5: 02.2

BEST CYCLE LENGTH = 1.35 SEC.

CYCLE EVALUATION SUMMARY PERFORMANCE										
CYCLE LENGTH (SECS)	STEP SIZE (CM)	AVERAGE DELAY (SEC)	PERCENT STOPS	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	NUMBERS SATURATED LINKS				
96	30	181.32	62	174.70	2.51	222				
98	30	179.57	62	167.70	2.51	222				
100	30	176.96	61	165.70	2.51	222				
100	35	174.20	60	164.60	2.51	222				
105	30	171.51	60	162.90	2.51	222				
110	30	171.51	60	162.90	2.51	222				
120	40	171.51	60	162.90	2.51	222				
125	42	171.49	60	162.80	2.51	222				
130	42	173.75	55	163.50	2.51	222				
PERFORMANCE WITH OPTIMAL SETTINGS										
MODE LINK NO.	FLOW (CM/HR)	FLOW (CM/HR)	FLIGHT DEGREE (C)	TOTAL TRAVEL (CM)	TIME (HR)	UNIFORM (CM/HR)	DELTA (CM/HR)	RANDOM (CM/HR)	TOTAL DELAY (CM/HR)	PERFORMANCE INDEX
1	101	1900P	1594	28.00	16.52	1.19	12.72	7.2	330.3	26
1	102	190	1015	1594	38.00	2.57	12.72	7.2	330.3	21
1	103	36	1015	1594	19.20	1.66	12.72	7.2	330.3	26
1	104	50	1015	1594	12.20	1.44	12.72	7.2	330.3	26
1	105	64	1045	1594	24.12	2.73	12.72	7.2	330.3	26
1	106	84	1950P	1614	35.80	4.61	12.72	7.2	330.3	26
1	107	248	1075	1614	18.20	2.73	12.72	7.2	330.3	26
1	108	240	2360P	1004	23.75	4.99	12.72	7.2	330.3	26
1	109	540	1105	1088	14.48	5.36	12.72	7.2	330.3	26
1	112	168	1105	1088	7.70	1.82	12.72	7.2	330.3	26
1	112	2570	MAX = 1614	312.09	241.02	43.47	171.65	215.11	301.3	718.05 PI = 162.8
2	201	850	2420	95	340.00	23.25	8.95	3.57	12.50	53
2	202	100	1500	9	40.00	0.00	0.00	0.00	0.00	20
2	203	376	1010	104	32.59	1.14	2.22	4.43	10.9	56
2	206	558	2315	988	98.79	7.80	4.97	10.52	100.8	56
2	207	256	1200	21	45.51	1.23	1.00	4.00	60.10	23
2	2024	MAX = 1044	1060.84	68.12	1060.84	22.60	15.51	39.70	45.5	23
3	301	1950P	2004	49.00	59.12	4.69	20.06	24.75	557.0	49
3	302	350	1200	21	75.00	2.14	0.00	0.00	0.00	20
3	303	324	1035	208	129.20	71.79	19.60	58.18	517.0	20
3	304	424	1035	208	129.20	71.79	19.60	58.18	517.0	20
3	305	112	3045	2434	22.20	4.16	73.80	42.04	689.9	27
3	306	56	3045	2434	16.40	3.05	16.40	16.40	269.9	27
3	307	158	2150P	1054	240.37	1.54	20.43	21.98	680.3	20
3	308	694	2150P	1054	240.37	1.54	20.43	21.98	680.3	20
3	310	96	5095	68	28.80	1.23	3.24	3.60	18.2	20
3	310	3684	MAX = 2494	1043.69	227.06	37.97	159.74	197.71	193.2	160.05 PI = 149.9
TOTAL FRAME DELAYS (CM/HR)										
3016.01	536.21	104.12	548.90	451.02	175.00	4672.94	520	1610.11	1610.11	5.02 (TOTAL)
ROUTE SUMMARY REPORT										
MODE LINK NO.	FLOW (CM/HR)	SAT. DEGREE (C)	TOTAL FLOW (CM/HR)	PERCENT STOPS	PERFORMANCE INDEX	NUMBERS SATURATED LINKS				
1	107	844	1950P	1614	15.61	79.86	95.47	407.3	220.00	55
3	304	894	2075	71	376.58	13.14	2.22	2.65	10.9	53
3	307	1358	2150P	1054	240.37	28.40	1.54	21.98	58.3	20
DOWN :	3006	MAX = 1614	954.55	19.37	100.73	120.10	140.1	1017.90	332.2	450.90 PI = 91.1
3	110	540	2250P	1088	230.04	24.72	5.96	12.34	150.0	55
3	309	854	2150P	68	90.77	15.21	7.86	12.50	60.7	27
UP :	1952	MAX = 1088	505.01	50.84	17.09	17.51	34.40	63.4	1053.50	177.46 PI = 29.6
TOTAL DISTANCE TRAVEL (CM/HR)										
1533.56	197.50	36.46	119.64	154.50	110.40	2471.10	432.3	628.37	7.80 (TOTAL)	

Fig 4.19 Optimal solution using phase sequence 19, 0, 6

(Check Iteration)

ITERATION : 6 (to test the algorithm)

Input Cycle Length: 105 seconds

Resulting Sequence: 3,5,6

Resulting PI Value: 345.23

Best Cycle Length Over Range: 115 seconds

Resulting PI Value: 343.91 (greater than iteration 3)

Reference: Table 4.8, Fig 4.20, Fig 4.21

Table 4.8 Resulting PI's for cycle length of 105 sec

Phase Sequence	Node			System Wide
	1	2	3	
1,1,1	164.7	27.5	155.2	347.37
2,2,2	163.5	31.8	167.3	362.59
3,3,3	162.3	34.2	154.0	350.50
4,4,4	163.2	29.9	157.4	350.55
5,5,5	166.5	27.1	153.7	347.37
6,6,6	162.5	27.3	150.8	340.63
7,6,1	167.6	27.9	158.1	353.57
8,1,2	165.5	27.4	170.1	362.94
9,2,3	167.0	32.2	151.7	350.86
10,3,4	166.5	31.5	157.9	355.81
11,4,5	163.8	30.1	155.9	349.83
12,5,6	164.7	29.7	153.0	347.43
13,6,1	171.0	27.1	154.9	353.05
14,5,2	167.5	27.8	167.8	363.08
15,4,3	165.5	29.0	153.9	348.42
16,3,4	165.6	32.1	160.7	358.40
17,2,5	164.4	32.1	157.3	353.68
18,6,1	163.4	27.3	155.5	346.20
19,5,2	162.5	30.7	167.0	360.17
20,1,6	164.3	28.0	149.8	342.12
21,2,1	162.5	32.3	156.9	351.76
22,3,2	162.6	32.6	168.0	363.15
23,4,3	165.3	28.8	153.6	347.67
24,5,4	166.4	27.7	158.5	352.53

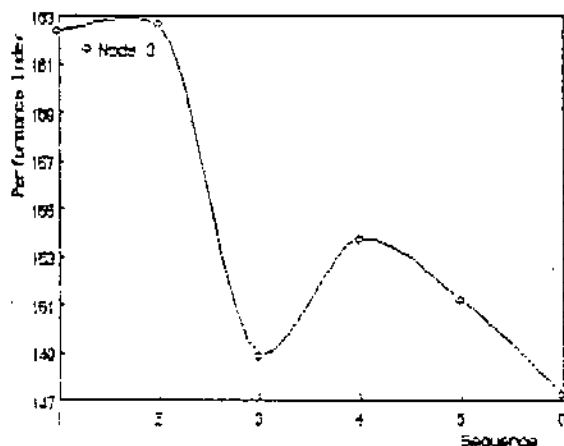
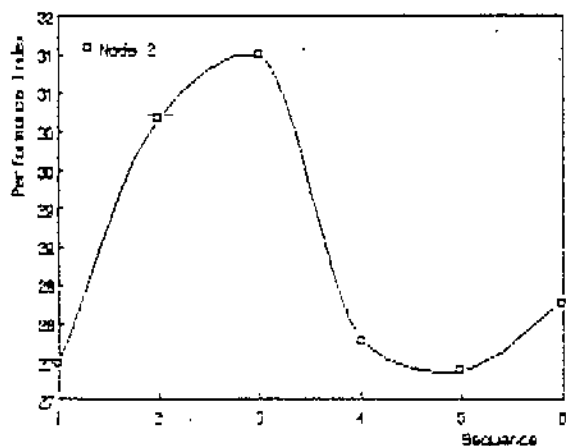
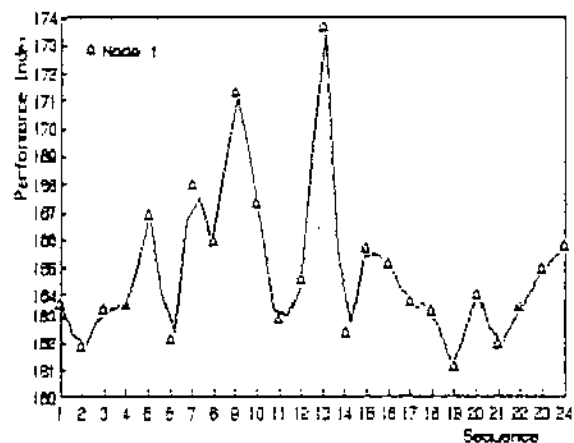


Fig 4.20 PI values versus phase sequences for each node (105 sec)

Phase Sequence	System Wide PI
3, 5, 6	345.23

DATE OF RUN: 2: 10/31 START TIME OF RUN: 6:21:52

CYCLE EVALUATION SUMMARY PERFORMANCE

CYCLE LENGTH (SEC)	AVERAGE DELAY (SEC/VEH)	PERCENT DELAY STOPS	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	NUMBER SATURATED LINKS
90	178.10	63	1677.1	354.0	22
95	179.25	64	1696.1	356.2	22
100	182.12	64	1725.4	349.7	22
105	185.66	61	1766.9	346.8	22
110	189.70	60	1812.4	344.5	22
115	194.30	60	1861.4	341.1	21
120	199.40	58	1914.1	337.1	21
125	205.00	56	1970.4	332.4	21
130	211.10	55	2030.4	327.9	21

BEST CYCLE LENGTH = 115 SEC.

LINK NO.	PERFORMANCE WITH OPTIMAL SETTINGS	TOTAL FLOW (VEH/HR)	TOTAL DELAY (HR)	UNIFORM DELAY (SEC/VEH)	AVERAGE DELAY (SEC/VEH)	UNIFORM STOPS (VEH/HR)	IRREGULAR STOPS (VEH/HR)	MAX BACK OF QUEUE CAPACITY (VEH/HR)	QUEUE CAPACITY (VEH/HR)	FUEL CONSUMPTION (GAL/HR)	FUEL PHASE LENGTH (SEC)	LINK NO.
1	101	1900P	1364	2.00	1.55	1.22	1.74	17.37	19.33	726.3	15	101
1	102	196	1304	19.46	7.24	12.74	17.37	101.9	101.9	347.0	16	102
1	103	1015	1354	13.20	7.78	1.47	5.93	7.40	12.4	23.2	17	103
1	104	66	1660P	15.8	5.93	1.47	4.93	5.61	10.4	10.9	17	104
1	105	50	1045	10.00	4.93	1.11	3.72	29.00	10.4	17.02	17	105
1	106	644	1608	57.60	31.11	18.08	23.72	170.33	10.4	69.80	17	106
1	107	318	1075	15.20	10.11	1.76	4.63	57.4	10.4	318.05	42	107
1	108	318	1075	15.20	10.11	1.76	4.63	57.4	10.4	318.05	42	108
1	109	270	1075	109.00	33.34	5.38	24.08	170.33	10.4	57.91	45	109
1	110	540	2250P	109.00	33.34	5.38	24.08	170.33	10.4	57.91	45	110
1	111	168	1105	71.57	3.60	1.08	2.88	130.86	110	1105	58	111
1	112	168	1105	71.57	3.60	1.08	2.88	130.86	110	1105	58	112
1	113	2570	912.09	242.94	43.08	173.95	217.04	1009.63	752.4	725.24	PI =	113
2	201	850	2420	904	340.00	23.50	5.62	14.10	60.1	408.403	42	201
2	202	894	2075	9	40.00	1.14	0.60	14.10	60.1	408.403	42	202
2	203	258	2310	104	160.79	12.71	1.92	2.22	7.0	368.53	44	203
2	204	258	2310	104	160.79	12.71	1.92	2.22	7.0	368.53	44	204
2	205	258	2310	104	160.79	12.71	1.92	2.22	7.0	368.53	44	205
2	206	258	2310	104	160.79	12.71	1.92	2.22	7.0	368.53	44	206
2	207	258	2310	104	160.79	12.71	1.92	2.22	7.0	368.53	44	207
2	3024	MAX = 105M	1060.64	62.59	35.99	15.99	16.68	32.66	30.9	1947.13	61	3024
3	301	150	1950P	1844	48.00	24.09	4.28	18.34	22.72	511.0	25	301
3	302	250	1200	21	75.00	21.14	4.08	18.34	22.72	511.0	25	302
3	303	464	3015	184	139.20	69.07	12.71	53.19	65.89	254.22	54	303
3	304	725	1100P	242M	43.60	22.23	5.75	23.28	39.73	301.5	22	304
3	305	154	3045	242M	21.60	13.63	1.20	16.25	13.63	16.25	19	305
3	306	154	3045	242M	21.60	13.63	1.20	16.25	13.63	16.25	19	306
3	307	1358	2150P	105M	240.37	38.77	2.22	32.55	32.55	167.57	74	307
3	308	108	3075	103M	19.12	3.06	1.12	2.40	2.52	21.11	20	308
3	309	89	2085	71	28.20	11.24	3.37	3.48	15.5	52.43	74	309
3	310	3684	MAX = 242M	1043.08	226.18	34.35	152.48	196.83	152.5	1873.53	51	310

TOTAL DISTANCE TRAVELED (VEH-MIN)	TOTAL TRAVEL TIME (VEH-HR)	TOTAL FUEL CONSUMPTION (GAL)	TOTAL DELAY (HR)	TOTAL UNIFORM DELAY (HR)	TOTAL IRREGULAR DELAY (HR)	TOTAL STOP TIME (HR)	OPERATING COST (\$/VEH)	PERFORMANCE INDEX	SPEED (MPH)	LINK NO.			
3016.01	521.72	93.42	353.13	44.53	173.26	5608.53	602	1639.65	2130.31	5.67	<TOTALS>		
CRUISING SUMMARY REPORT - THE TSD ORIENTATION OMBROUND ON THE PHASE IS DESTROYING													
1	107	844	1950P	150M	327.60	104.22	16.81	77.77	94.57	403.4	53.42	62	107
2	204	884	3075	70	376.59	12.71	1.82	4.40	2.22	9.0	268.53	44	204
3	307	1358	2150P	105M	240.37	38.77	2.22	30.13	32.55	65.8	767.57	74	307
DOWN :													
1	110	540	2250P	105M	109.00	33.34	5.38	24.08	170.33	10.4	164.24	PI =	110
2	206	854	2180P	71	258.20	11.00	3.30	2.38	3.68	18.9	52.43	74	206
3	309	894	2180P	71	258.20	11.00	3.30	2.38	3.68	18.9	52.43	74	309
UP :													
1	112	168	1105	58	595.01	40.43	11.79	12.20	23.99	44.2	1455.00	PI =	112
2	207	894	2180P	71	258.20	11.00	3.30	2.38	3.68	18.9	52.43	74	207
3	310	150	1950P	1844	48.00	24.09	4.28	18.34	22.72	511.0	25	310	

Fig 4.21 Optimal solution Using phase 10

4.4.2 Results of Research:

Results of algorithm iterations are shown in Table 4.9. This table summarizes different steps of the algorithm that has been developed in order to get a good solution.

Table 4.9 Summary of iterations done to reach solution

Iteration	Input Cycle Length	Resulting		Output Cycle Length	PI
		PI	Sequence		
1	100	346.93	19,5,1	120	349.14
2	120	341.53	6,4,3	125	342.84
3	125	339.53	2,1,3	125	337.22
Ckeck, 4	115	339.35	19,1,3	125	337.84
Ckeck, 5	110	343.57	19,5,6	125	344.82
Ckeck, 6	105	345.23	3,5,6	115	343.91

Table 4.9 is reproduced in a plot-form as shown in Fig 4.22. The convergence of algorithm was at 125 seconds cycle length. At that length, the resulting performance index PI was the minimum among the other values. Also, the resulting cycle length was the same as the input cycle length (125 seconds).

A summary of results of this research are shown in Table 4.10. The summary shows all the PI values sequences that had been found and tested. This table is plotted as shown in Fig 4.23. The curve that represents phase sequence 2,1,3 has the least PI values among all other phase sequences tested.

Improvement in the system has been calculated considering different parameters of the system as performance index, fuel

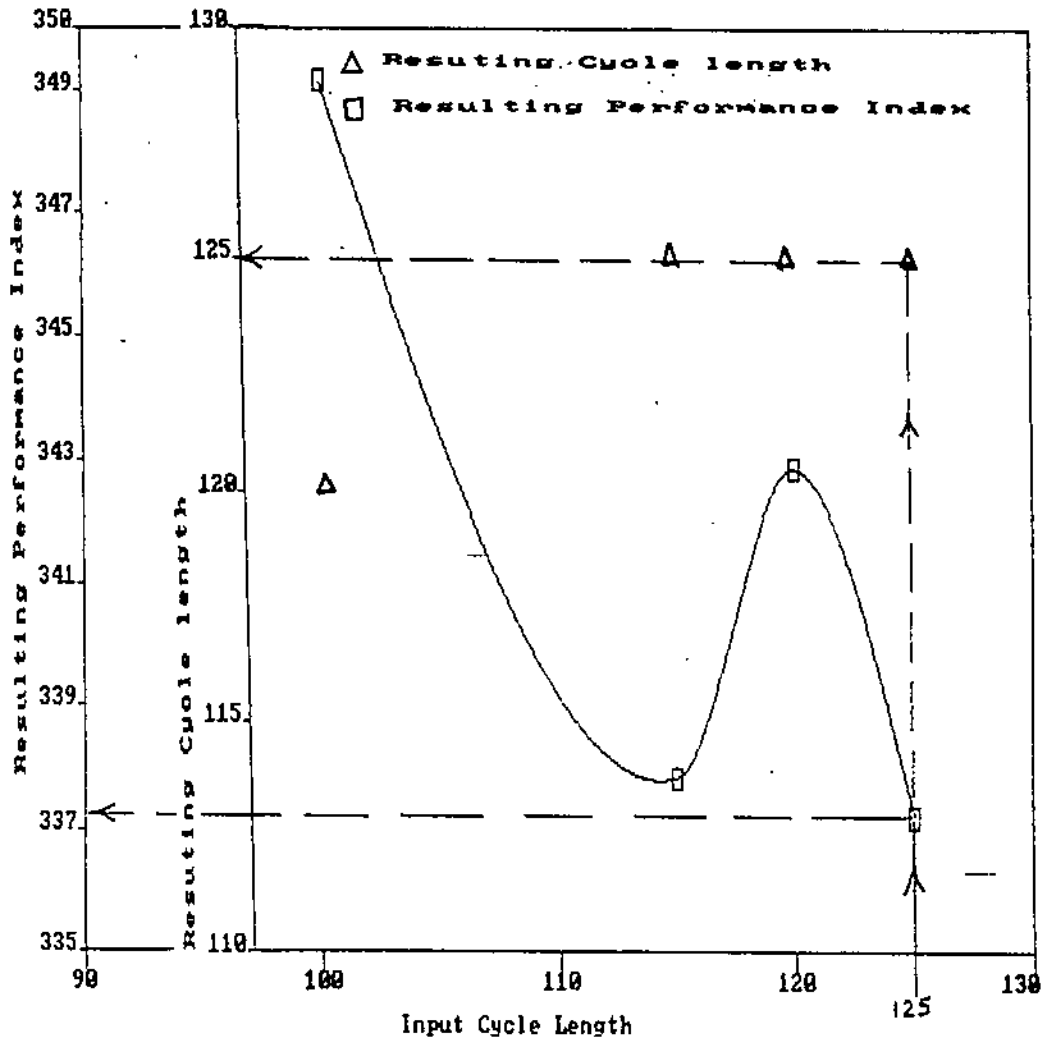


Fig 4.22 Summary of iterations done to reach solution

consumption, total delay, average delay, operating cost, and total travel time. The comparison was between the installed setting and phase sequence, and the recommended solution that was found (phase sequence 2,1,3). This comparison and the improvement are shown in Table 4.11.

Table 4.10 Summary of Results (Performance Index Values)

Column Number		1	2	3	4	5	6	7	Remarks	
Sequence	Run Type	Cycle Length	Node			System		Route		
			1	2	3	Wide	Down	Up		Total
1,1,1	Sim	100	176.2	36	175.6	387.7	170	48.9	218.82	Installed S.T.P & Phase Sequence *
1,1,1	Opt	100	164.6	28.2	156	348.83	126	29.2	155.27	Installed S.T.P & Phase Sequence
19,5,1	Opt	120	161.4	33.2	154.6	349.14	122.7	27.5	150.25	Range 90-130 sec
6,4,3	Opt	125	164.6	32.1	146.2	342.84	99.5	38.3	137.84	Range 90-130 sec
19,1,3	Opt	125	163	27.9	147	337.84	102.4	22.7	125.09	Range 90-130 sec
2,1,3	Opt	125	162.6	28.7	145.9	337.22	92.2	22.8	114.9	Range 90-130 sec

* S.T.P Signal Timing Plan

Summary of Results

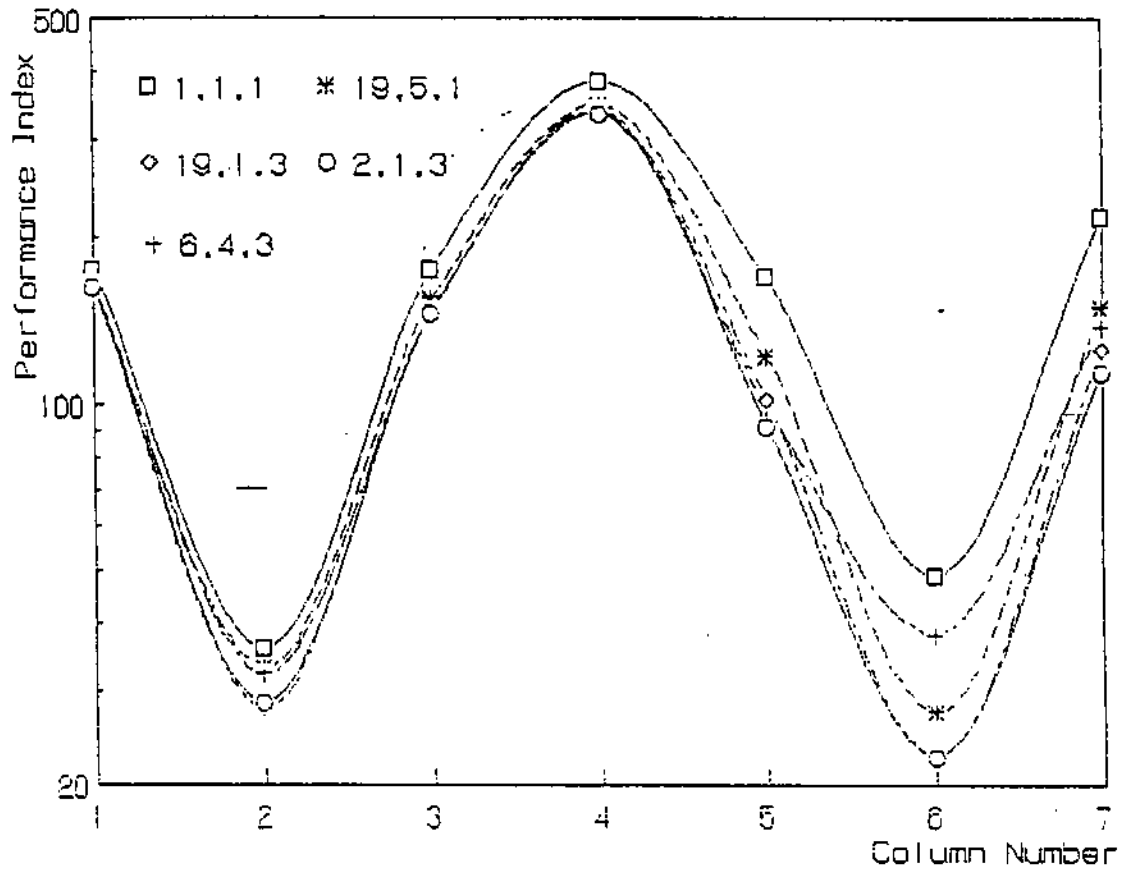


Fig. 4.23 Plot for every sequence developed by algorithm

Table 4.11 Improvement in System (Prince Shaker Street)

Parameter		Installed Setting	Recomm. Solution	% Improv.	
Performance Index	Node	1	176.2	162.6	7.72
		2	36	28.7	20.28
		3	175.6	145.9	16.91
	S.W.		387.7	337.22	13.02
	Route	Up	170	92.2	45.76
		Down	48.9	22.8	53.37
		Tot.	218.82	114.9	47.49
Fuel Consumption (Li/Hr)	Node	1	769.4	718.14	6.66
		2	254.89	227.41	10.78
		3	781.13	668.8	14.38
	S.W.		1805.42	1614.34	10.58
	Route	Up	749.55	455.01	39.30
		Down	250.31	151.5	39.48
		Tot.	999.86	779.62	22.03
Total Delay (Veh-H/H)	S.W.		504.87	439.97	12.85
	Route		285.39	145.77	48.92
Average Delay (Sec/H)	S.W		195.9	170.71	12.86
	Route		203.93	104.17	48.92
Operating Cost	S.W		2335.82	2095.22	10.30
	Route		1260.32	779.62	38.14
Total Travel (Veh-H/H)	S.W		590.06	525.15	11.00
	Route		328.4	188.78	42.52

4.5 Conclusions:

In the matter of time needed to reach the solution, i.e. the optimum cycle length, it can be seen clearly from Table 4.9 that the best performance index PI was reached after three iterations. The number of computer runs per iteration was 24 plus one run to make a cycle evaluation. This makes the total number of runs needed to reach the solution equal to 75. The check iteration also needed 25 computer runs. This adds up to a total of 100 computer runs needed for the solution.

On the other hand, in order to find the best solution using the method described in TRANSYT, the number of runs needed are 864 plus one cycle evaluation, which adds up to a total of 865 computer runs.

As it was expected, the developed algorithm shows a rapid convergence. In the case of Prince Shaker Street we dealt with, the convergence took about 12% of the time needed for using the method of TRANSYT-7F (100 runs using algorithm versus 865 runs using method of TRANSYT-7F).

In the matter of improvement in the system, it can be seen clearly from the summary of results (Table 4.10) that the best phase sequence (2,1,3) that resulted has the minimum system and route performance index (PI). Also, and as shown in Table(4.11), the recommended solution has improved the system by 6.6% in fuel consumption at node 1 and 14.4% at node 3. Furthermore, the system has been improved in the total and in the average delay by about 49%. Also, the total travel has been improved by a very good percentage in the sense that it

has increased by about 43% on the main street. Based on these results, the developed algorithm has been shown to be a good tool to be applied in order to reach a good solution with a high confidence level.

Concerning the best cycle length found, there are some factors that affect the selection of cycle length greater than 120 seconds. Among these factors are the existence of more than four approaches for the intersection, more than four phases for the timing plan, and high traffic volumes which cause high congestion at the intersection. Because of these reasons, the author recommends the installation of 115 second cycle length since it ranked second in PI values (table 4.9).

Chapter Five

Summary and Recommendations for Future Research

5.1 Summary:

The objective of this thesis was to Set an Effecient Signal Sequence and Timing for Interconnected Traffic Signals.

This problem was solved by developing an algorithm that was implemented on TRANSYT-7F. That algorithm had resulted in an optimal or near optimal solution with a high confidence level.

The developed algorithm showed a very good time saving in the computer run time. In the case we dealt with, the reduction in time was about 80% when using a PC-AT (without math-coprocessor).

The recommended solution of the phase sequences and signal timing plans for the three intersections studied showed significant improvements. These improvements in the different parameters were summarized in Table 4.11.

Delay, which was the major parameter in the study that we attempted to minimize, had been reduced by about 48% in the main street. Also, fuel consumption was decreased by about 22% for the same route. Overall, the recommended solution has proved to introduce a significant improvement.

5.2 Recommendations for Future Research:

-- In coducting the research for this thesis, some ideas were contemplated but, due to time limitations, could not be tried. Among these are:

- 1) Left-turn movements are allowed at Wahbi Tamari. (node 1)

and Flying Carpet (node 2) intersections. But, these movements are protected. In other words, they have separate phase. They can only move on the green arrow (they have their own right-of-way). A study could be conducted on the effect of unprotected left-turn movements, which has no exclusive right-of way and, must only rely on gaps in the opposing traffic to find how this solution can affect delay.

- 2) In this study, no constructional changes were assumed. In other words, for example, no approach widening was done. So, a study could be made in order to find the effect of approach widening on delay and other traffic parameters and, how this change could affect the behaviour of the flow of traffic.

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Appendices

Appendix A: Glossary

Appendix B: Webster's Formula, Program calculating delay

Appendix C: Traffic Data at Each Intersection

Appendix D: Solution of Wahbi Tamari's intersection Using
Webster's Model

Appendix E: Input Data to TRANSYT-7F

Appendix F: Complete Sample Output

Bound: The direction at which the traffic is coming from.

Capacity: Maximum number of vehicles that can pass over a given section of a lane or roadway during a given time period, under prevailing roadway and traffic conditions.

Clearance Interval: The interval from the end of the yellow period associated with one phase to the beginning of a conflicting phase.

Cycle Length: The time required for one complete sequence of signal indications.

Degree of Saturation: The ratio of the flow to the maximum possible flow under the given settings of the signals.

Delay: Time lost while traffic is impeded by some element over which the driver has no control, such as traffic signal.

External Link: A link entering the network, having no upstream input in the network.

Flow: The volume of traffic, normally in vehicles per hour (vph).

Fuel Consumption: The estimate of the amount of fuel consumed by all vehicles in a network in liters.

Link: The unidirectional roadway between two signalized locations.

Lost Time: The unproductive time during the cycle for moving vehicles.

Node: The representation of an intersection of two or more streets.

Offset: In a signal system, the time difference in seconds between system time base and the start of a specified interval.

Peak Hour Factor (PHF): The ratio of vehicles entering the intersection during the peak hour to four times the number of vehicles entering during the peak 15-minutes period.

Peak Period: The period of day when traffic demands are typically the highest.

Performance Index: The optimization objective function of TRANSYT-7F, a linear combination of delay (veh-hr) and stops (veh-sec) or total operating cost.

Phase: A portion of a signal cycle during which the right-of-way is made to given traffic movements.

Phase Sequence: The order in which the traffic movements are given the right-of-way in a signal cycle.

Queue Length: The number of vehicles which are stopped or moving in a line where the movement of each vehicle is constrained by that of the lead vehicle.

Saturation Flow: The flow in vehicles per hour which would be obtained if there was a continuous queue of vehicles, and they were given a 100 percent green time.

Traffic Volume: The actual passage of traffic past a

particular point of a roadway during a given period of time. Measured in vehicles per hour.

APPENDIX B

Webster's Formula

(Program calculates delay)

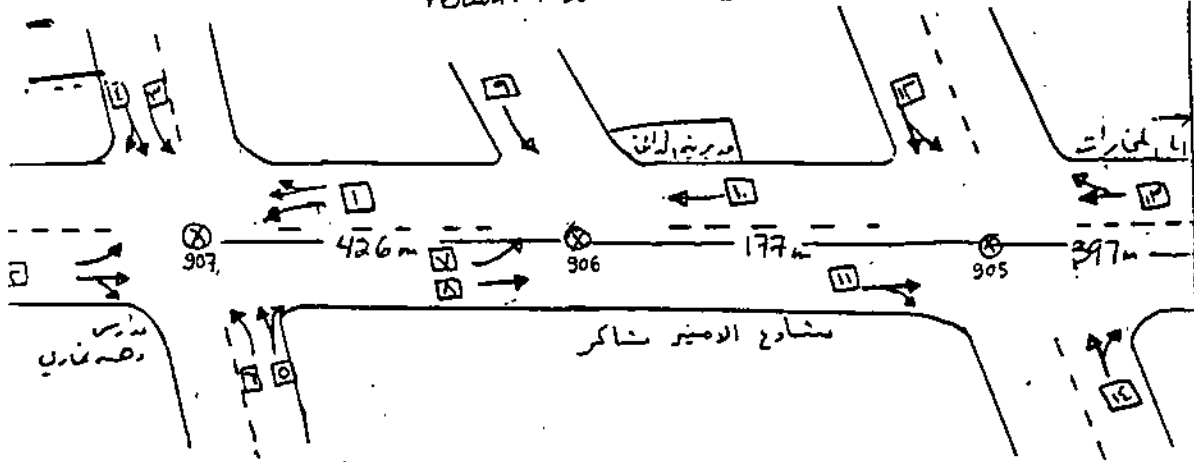
```

10 '*****
30 'This program calculates the DELAY using WEBSTER's method
50 'that was represented in Road Research Technical Paper 39
70 'This method calculates the Average Delay per Vehicle on a
90 'particular intersection arm.
110 '*****
130 INPUT "Lambda =",L
150 INPUT "Degree of Saturation 'x' =",X
170 INPUT "Flow 'q' =",Q
190 INPUT "Cycle Length 'c' =",CY
210 MX = 1-X
230 MLAM = 1-L
250 DEN = (1-L*X)
270 A = (CY*(MLAM2))/(2*DEN)
290 B = (X2)/(2*Q*MX)
310 TL = 2+5*L
330 CQ = CY/Q2
350 C = .65*(CQ.3333)*(XTL)
370 DELAY = A+B-C
390 PRINT "A= ",A: PRINT "B= ",B: PRINT "C= ",C
410 PRINT "Delay =",DELAY

```

TRAFFIC COUNIS:

Period: 7:30-9:30



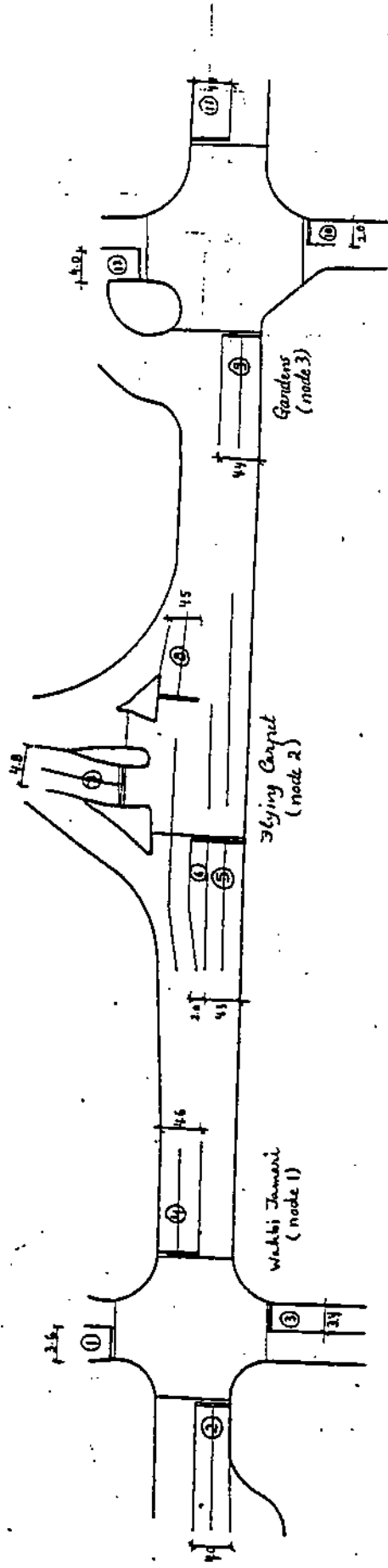
MOVEMENT TIME PERIOD	↖ ↗	↘ ↙	3	4	5	6	7	8	9	10	11	12	13	14	Total
7.00 - 7.15															
7.15 - 7.30															
7.30 - 7.45	120 40	233 60	27	78	23	62	91	220	203	146	343	114	201	80	
7.45 - 8.00	116 46	206 125	26	71	28	64	97	222	212	133	378	172	236	117	
8.00 - 8.15	171 38	177 84	22	56	30	68	83	204	213	100	355	140	239	62	
8.15 - 8.30	99 7	211 75	18	47	15	31	89	208	191	96	326	91	201	48	
8.30 - 8.45	129 12	198 55	16	32	14	15	85	168	184	128	325	88	155	40	
8.45 - 9.00	149 15	184 45	11	44	13	16	42	101	158	149	253	83	169	35	
9.00 - 9.15	145 13	167 70	10	21	9	10	66	130	119	46	282	93	203	33	
9.15 - 9.30	184 10	198 50	15	27	17	19	71	166	120	101	226	79	178	36	
9.30 - 9.45															
9.45 - 10.00															
Sub total															
TOTAL															

Intersection : 905, 906, 907

Date : 29/5/1989

Day : Tuesday

Weather Conditions : Sunny



Wahbi Tamari Intersection

PERIOD	1	2	3	4
7:30 - 7:45	100	295	85	160
7:45 - 8:00	97	331	92	162
8:00 - 8:15	78	281	98	209
8:15 - 8:30	65	286	46	106
8:30 - 8:45	48	253	29	141
8:45 - 9:00	55	225	29	164
9:00 - 9:15	31	263	19	158
9:15 - 9:30	42	242	36	196
TOTALS	516	2176	434	1296

Flying Carpet Intersection

PERIOD	5	6	7	8
7:30 - 7:45	220	91	203	146
7:45 - 8:00	222	97	212	133
8:00 - 8:15	204	83	213	100
8:15 - 8:30	208	89	191	96
8:30 - 8:45	168	85	184	128
8:45 - 9:00	101	42	158	149
9:00 - 9:15	130	66	119	96
9:15 - 9:30	166	71	120	101
TOTALS	1419	624	1400	949

Gardens Intersection

PERIOD	9	10	11	12
7:30 - 7:45	343	80	201	114
7:45 - 8:00	378	117	236	172
8:00 - 8:15	355	62	239	140
8:15 - 8:30	326	48	201	91
8:30 - 8:45	325	40	155	88
8:45 - 9:00	253	35	169	83
9:00 - 9:15	282	33	203	93
9:15 - 9:30	226	36	178	79
TOTALS	2488	451	1582	860

APPENDIX D
Solution of Wahbi Tamari Intersection
Using Webster's Equation

Wahbi Tamari's Intersection

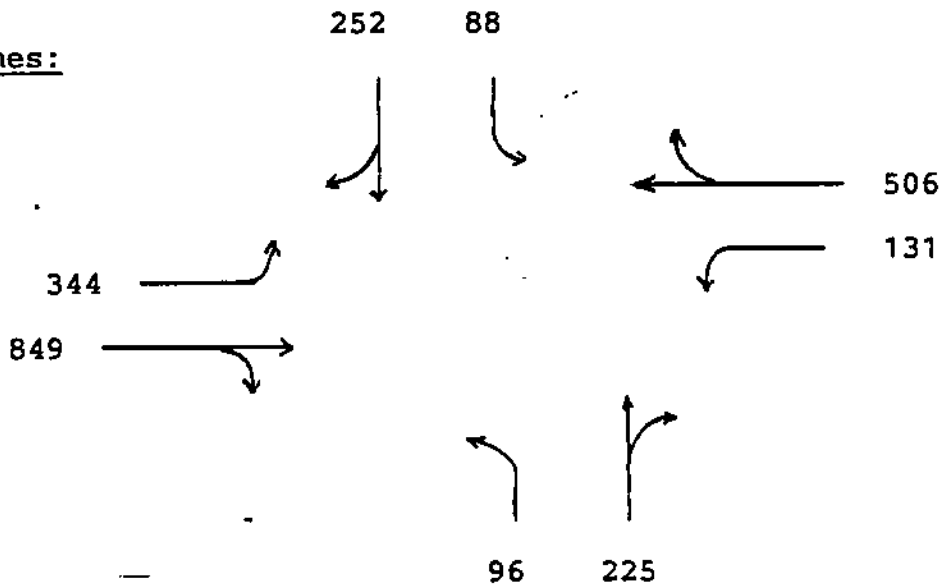
Traffic flow data for each approach in the a.m. peak

TIME	N B		S B		E B		W B		Tot.	Cum Total
	↳	↓	↶	↷	↵	↶	↷	↵		
7:30 - 7:45	22	78	23	62	40	120	60	235	640	2491
7:45 - 8:00	26	71	28	64	46	116	125	206	682	2322
8:00 - 8:15	22	56	30	68	38	171	84	197	666	2113
8:15 - 8:30	18	47	15	31	7	99	75	211	503	1918
8:30 - 8:45	16	32	14	15	12	129	55	198	471	1931
8:45 - 9:00	11	49	13	16	15	149	45	180	473	
9:00 - 9:15	10	21	9	10	13	145	70	193	471	
9:15 - 9:30	15	27	17	19	10	186	50	192	516	

As it can be seen from table, the maximum cummulative volume corresponds to the period from 7:30-8:30. Though, this period will be considered in computations.

TIME	N B		S B		E B		W B		TOTAL
	↳	↓	↶	↷	↵	↶	↷	↵	
7:30 - 7:45	22	78	23	62	40	120	60	235	640
7:45 - 8:00	26	71	28	64	46	116	125	206	682
8:00 - 8:15	22	56	30	68	38	171	84	197	666
8:15 - 8:30	18	47	15	31	7	99	75	211	503
TOTAL	88	252	96	225	131	506	344	849	2491

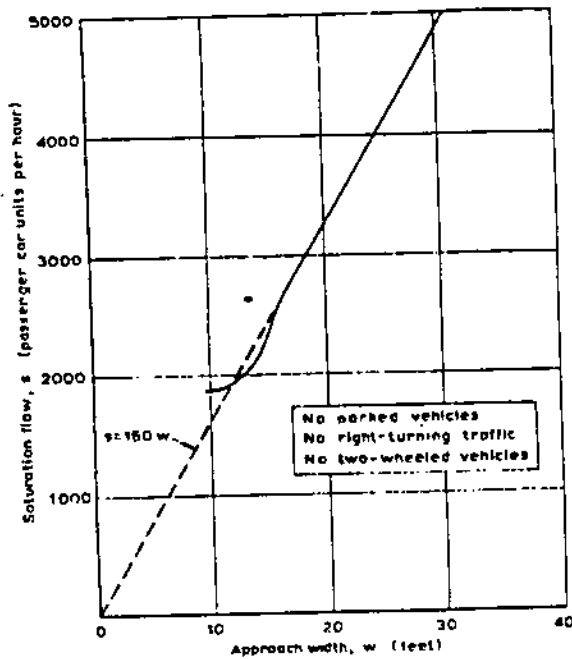
Volumes:



Approach	Saturation Flow
East Bound	2250
West Bound	1950
North Bound	1900
South Bound	1880

$$\begin{aligned}
 \text{PHF} &= \frac{\text{Total flow in 1 Hr}}{4 \text{ (Max flow of 15 min)}} = \frac{2491}{4 \times 682} \\
 &= 0.913
 \end{aligned}$$

VOLUME ADJUSTMENT WORKSHEET										
①	②	③	④	⑤	⑥	⑦	⑧	⑨	⑩	⑪
Appr.	Mvt.	MVL Volume (vph)	Peak Hour Factor PHF	Flow Rate v_p (vph) $\frac{v}{P}$	Lane Group	Flow rate in Lane Group v_L (vph)	Number of Lanes N	Lane Utilization Factor U Table 9-4	Adj. Flow v (vph) $\frac{v}{U}$	Prop. of LT or RT P_L or P_R
EB	LT	131	0.91	146	↙	708	2	1.05	744	
	TH	506	0.91	562	↔					
	RT									
WB	LT	344	0.91	382	↗	1325	2	1.05	1391	
	TH	849	0.91	943	↘					
	RT									
NB	LT	88	0.91	98	↕	378	1	1.0	378	
	TH	252	0.91	280						
	RT									
SB	LT	96	0.91	107	↕	357	1.0	357		
	TH	225	0.91	250						
	RT									



Effect of approach width on saturation flow

Optimum Signal Time Phasing:

	<u>N</u>	<u>S</u>	<u>E</u>	<u>W</u>
q	378	357	744	1391
S	1900	1880	2250	1950
y=q/S	0.199	0.189	0.33	0.713

$$Y = 0.199 + 0.189 + 0.330 + 0.713$$
$$= 1.431$$

In this case, since $Y = \sum y > 1.0$ then, use the maximum recommended cycle length = 120 seconds.

Splitting Effective Green Times:

$$g_i = \frac{y_i}{Y} (C_0 - L)$$

$$g_N = \frac{0.199}{1.431} (120 - 12) = 15.0$$

$$g_S = 0.189 * 75.472 = 14.3$$

$$g_E = 0.330 * 75.472 = 24.9$$

$$g_W = 0.713 * 75.472 = 53.8$$

Then, actual green times (Refer to figure on next page)

$$g_N = 15 \text{ sec}$$

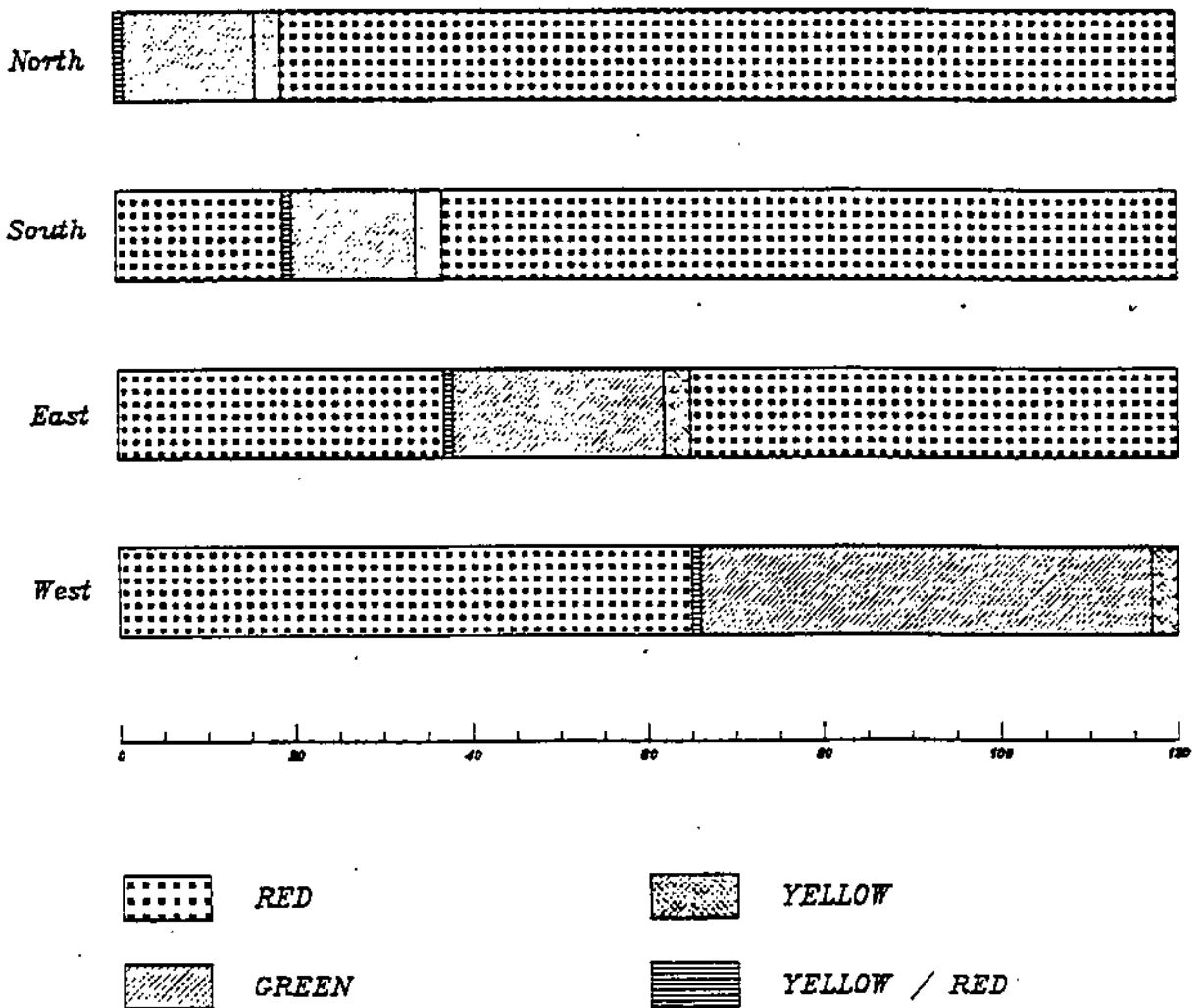
$$g_B = 14 \text{ sec}$$

$$g_E = 24 \text{ sec}$$

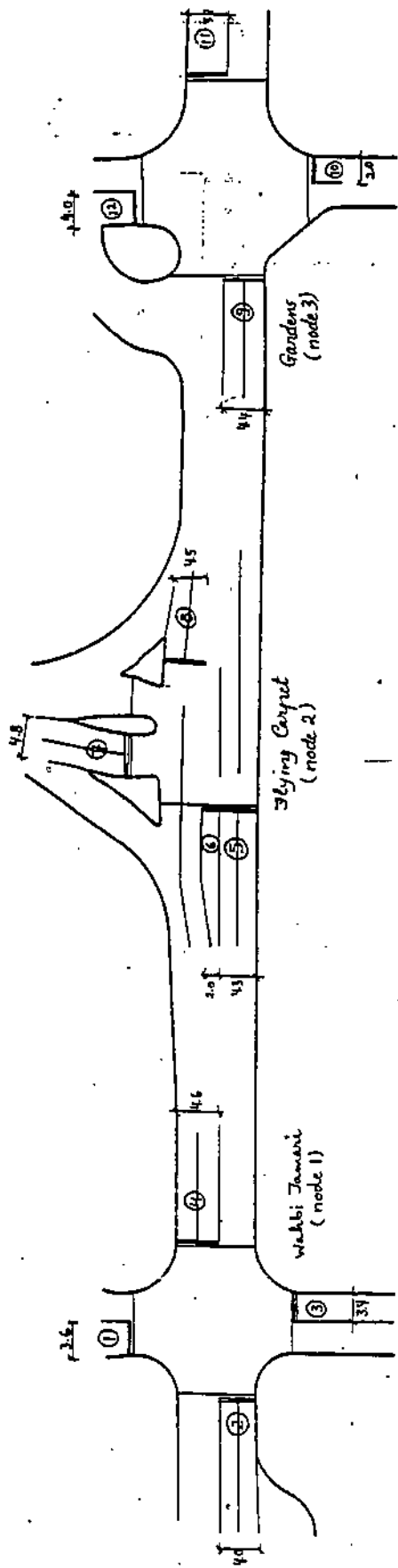
$$g_W = 51 \text{ sec.}$$

Phase Diagram

(Wahbi Tamari Intersection)



Phase diagram of Wahbi Tamari Intersection
in the a.m. peak hour



TRANSYT-7F
NODE/LINK INVENTORY WORKSHEET

CITY Amman NETWORK Prince Shaker str.

SYSTEM _____

CONDITION(S) _____ PERIOD _____

DEVELOPED BY _____ DATE _____

INVENTORY

INTERSECTION	NODE NO.	LINK NO.	LINK LENGTH	SAT. FLOW	COMMENTS/SPECIAL ACTIONS
Gardens	3	301	300	1950	External / Primary
		302	300	1200	Permitted
		303	300		External / Secondary
		304	600	1100	External / Primary
		305	600		" / Secondary
		306	600		" "
		307	177	2150	Primary
		308	177		Secondary
		309	300	2150	External / Primary
		310	300		" / Secondary

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TRANSYT-7F

DATA COLLECTION SHEET - PRETIMED SIGNAL - TIMING PLAN

CITY Amman NETWORK Prince Shaker Str.

INTERSECTION Wahbi Tamari NODE 1

CONTROLLER _____

COLLECTED BY _____ SOURCE _____ DATE _____

INTERVAL		DIAL NUMBER									PHASES		
		1			2			3					
NAME	NO.	SEC	%	PIN	SEC	%	PIN	SEC	%	PIN	DIAGRAM	NO.	MIN
Actual green	1	12										1	17 Sec
Yellow/Red	2	1											
Amber	3	3											
ALL/Red	4	1											
Actual Green	5	22										2	27 Sec
Yellow/Red	6	1											
Amber	7	3											
ALL/Red	8	1											
Actual Green	9	13										3	18 Sec
Yellow/Red	10	1											
Amber	11	3											
ALL/Red	12	1											
Actual Green	13	33										4	38 Sec
Yellow/Red	14	1											
Amber	15	3											
ALL/Red	16	1											
CYCLE LENGTHS		100 Sec.									COMMENTS		
OFFSETS	1												
	2												
	3												
TIMES/DIAL													

SHEET ___ OF ___

TRANSYT-7F

DATA COLLECTION SHEET - PRETIMED SIGNAL - TIMING PLAN

CITY Amman NETWORK Prince Sheker St.
 INTERSECTION Flying Carpet NODE 2
 CONTROLLER _____
 COLLECTED BY _____ SOURCE _____ DATE _____

INTERVAL		DIAL NUMBER									PHASES		
		1			2			3					
NAME	NO.	SEC	%	PIN	SEC	%	PIN	SEC	%	PIN	DIAGRAM	NO.	MIN
Actual Green	1	28									← →	1	33 Sec
Yellow/Red	2	1											
Amber	3	3											
All Red	4	1											
Actual Green	5	23									↗ →	2	28 Sec
Yellow/Red	6	1											
Amber	7	3											
All Red	8	1											
Actual Green	9	34									↘	3	39 Sec
Yellow/Red	10	1											
Amber	11	3											
All Red	12	1											
CYCLE LENGTHS		100 Sec									COMMENTS		
OFFSETS		1											
		2											
		3											
TIMES/DIAL											SHEET ___ OF ___		

TRANSYT-7F

DATA COLLECTION SHEET - PRETIMED SIGNAL - TIMING PLAN

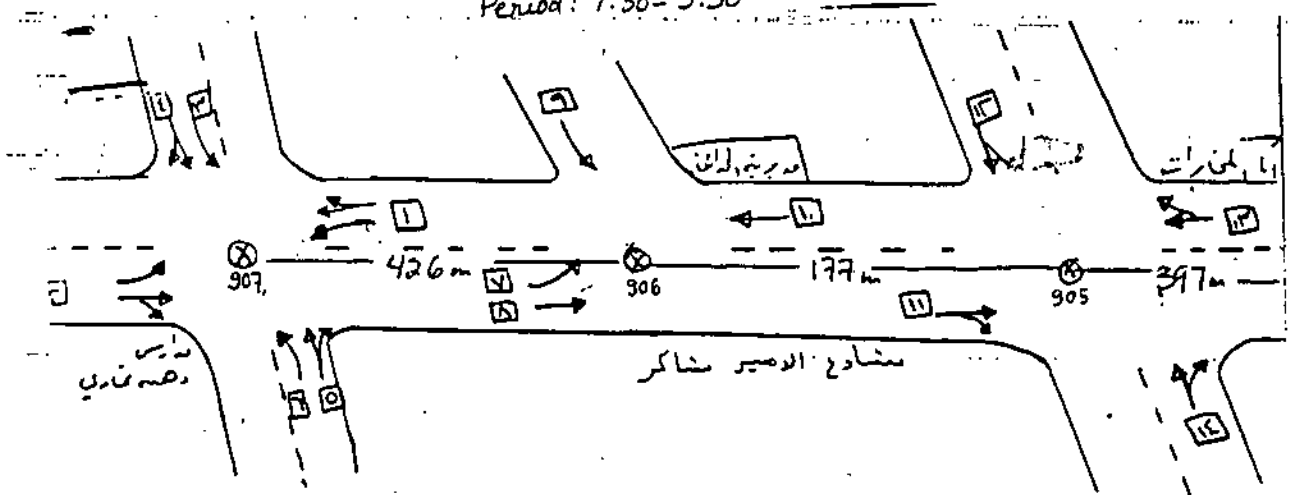
CITY Amman NETWORK Prince Shaker st.
 INTERSECTION Gardens NODE 3
 CONTROLLER _____
 COLLECTED BY _____ SOURCE _____ DATE _____

INTERVAL		DIAL NUMBER									PHASES		
		1			2			3					
NAME	NO.	SEC	%	PIN	SEC	%	PIN	SEC	%	PIN	DIAGRAM	NO.	MIN
Actual Gr.		43										1	48 sec
Yellow/Red		1											
Amber		3											
All/Red		1											
Actual Gr.		23										2	28 sec
Yellow/Red		1											
Amber		3											
All/Red		1											
Actual Gr.		19										3	24 sec
Yellow/Red		1											
Amber		3											
All/Red		1											
CYCLE LENGTHS		100 sec									COMMENTS		
OFFSETS	1												
	2												
	3												
TIMES/DIAL													

SHEET ___ OF ___

TRAFFIC COUNTS:

Period: 7:30-9:30



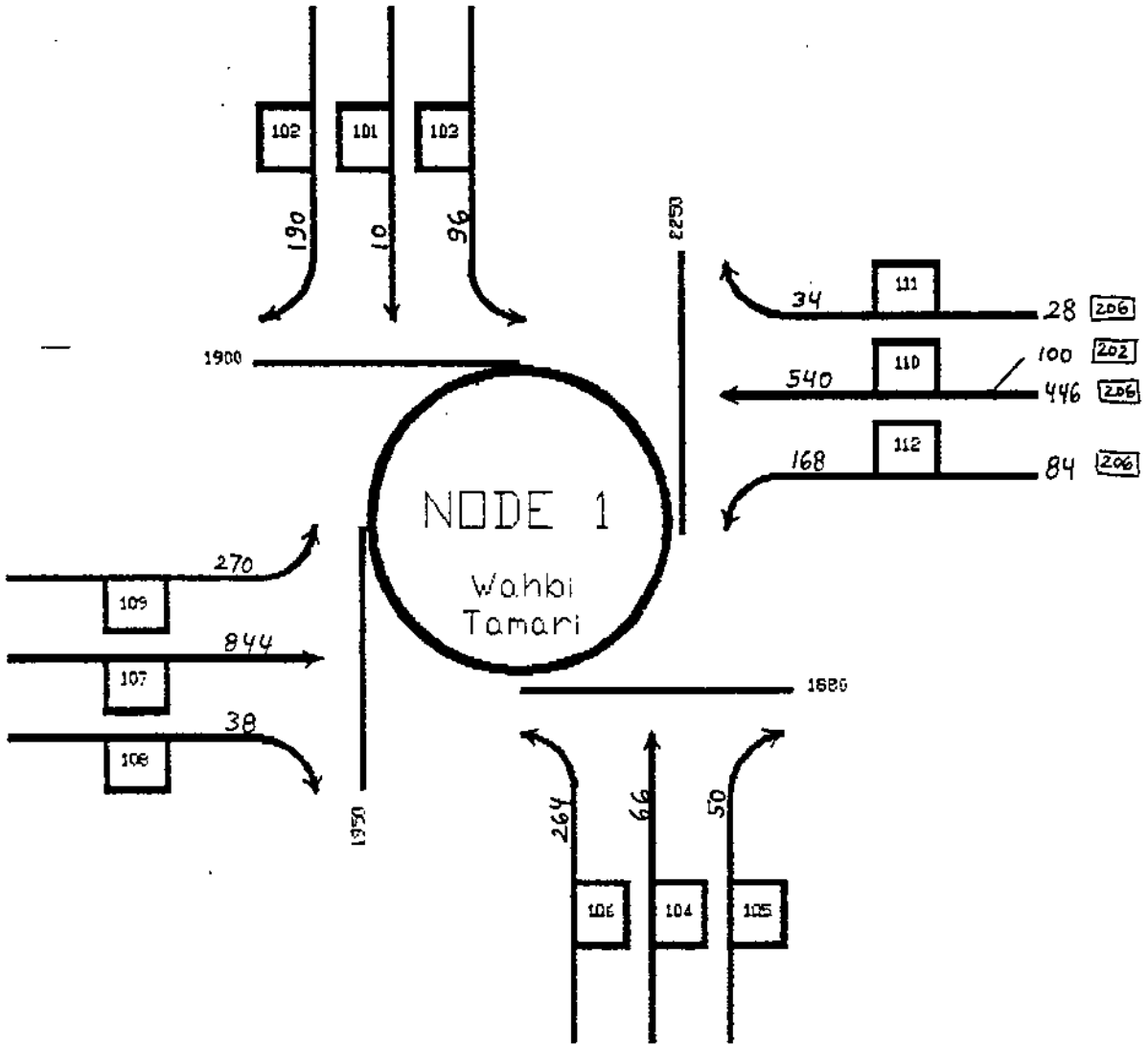
MOVEMENT TIME PERIOD	↖	↗	3	4	5	6	7	8	9	10	11	12	13	14	Total
7.00 - 7.15															
7.15 - 7.30															
7.30 - 7.45	120 40 235	60	22	78	23	62	91	220	203	146	343	114	201	80	
7.45 - 8.00	116 46 206	125	26	71	28	64	97	222	212	133	378	172	236	117	
8.00 - 8.15	171 38 197	84	22	56	30	68	83	204	213	100	355	140	239	62	
8.15 - 8.30	99 7 211	75	18	47	15	31	89	208	191	96	326	91	201	48	
8.30 - 8.45	129 12 198	55	16	32	14	15	85	168	164	128	325	88	155	40	
8.45 - 9.00	149 15 186	45	11	44	13	16	42	101	158	149	253	83	169	35	
9.00 - 9.15	145 13 197	70	10	21	9	10	66	130	119	96	282	93	203	33	
9.15 - 9.30	188 10 191	50	15	27	17	19	71	166	120	101	226	79	178	36	
9.30 - 9.45															
9.45 - 10.00															
Sub total															
TOTAL															

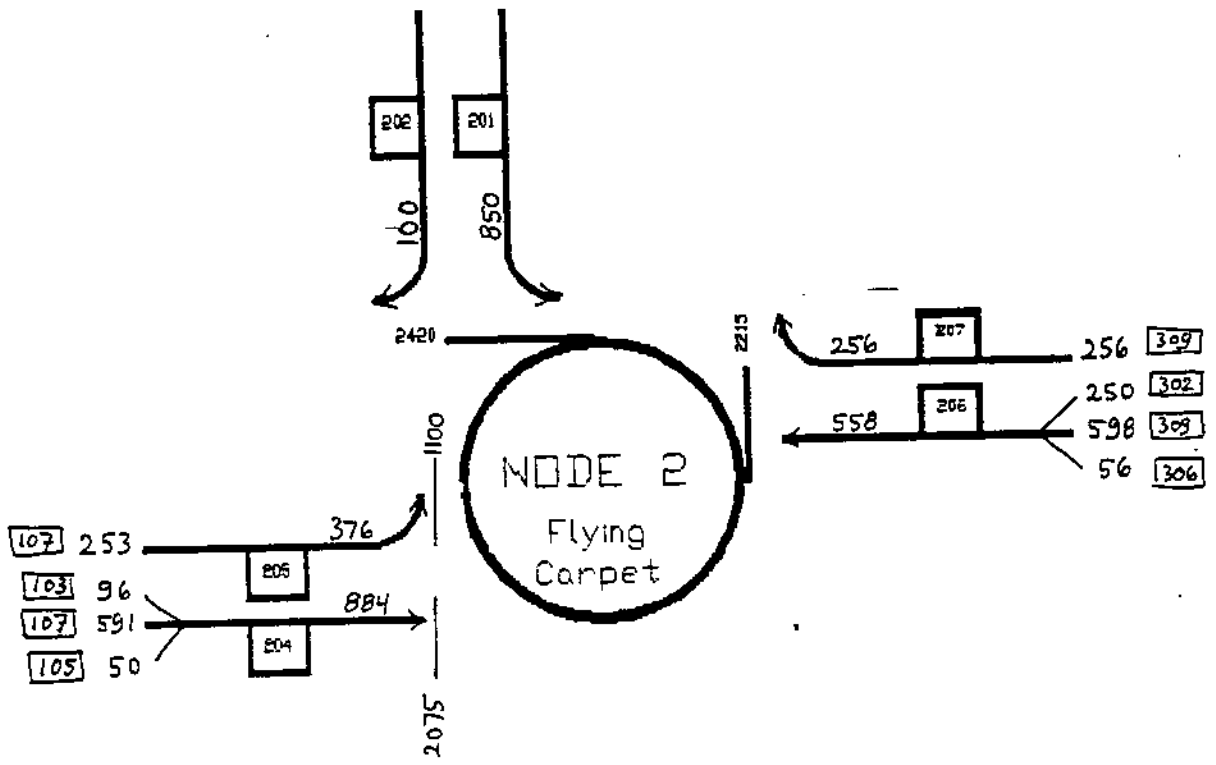
Intersection: 905, 906, 907

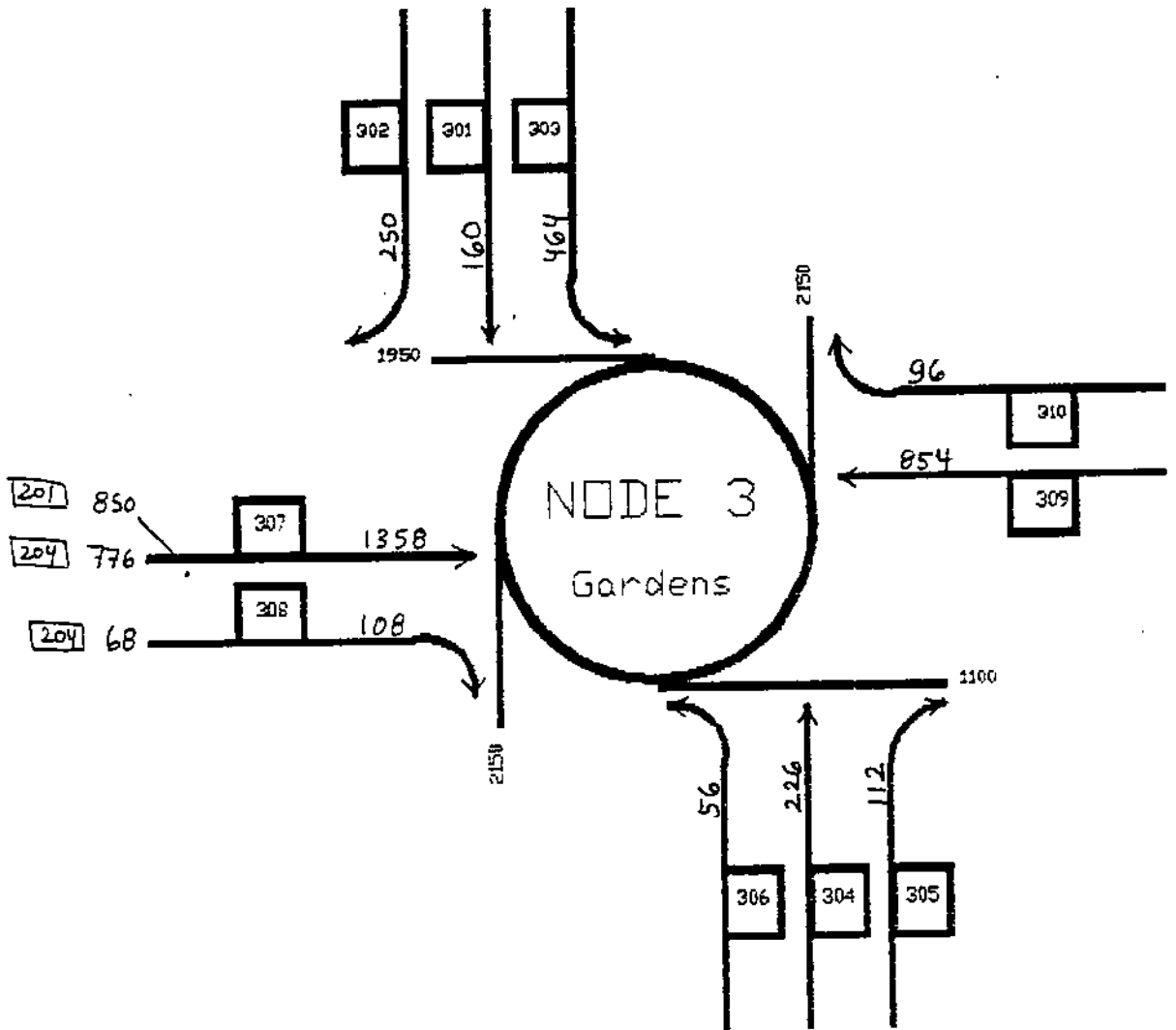
Date: 29/5/1989

Day: Tuesday

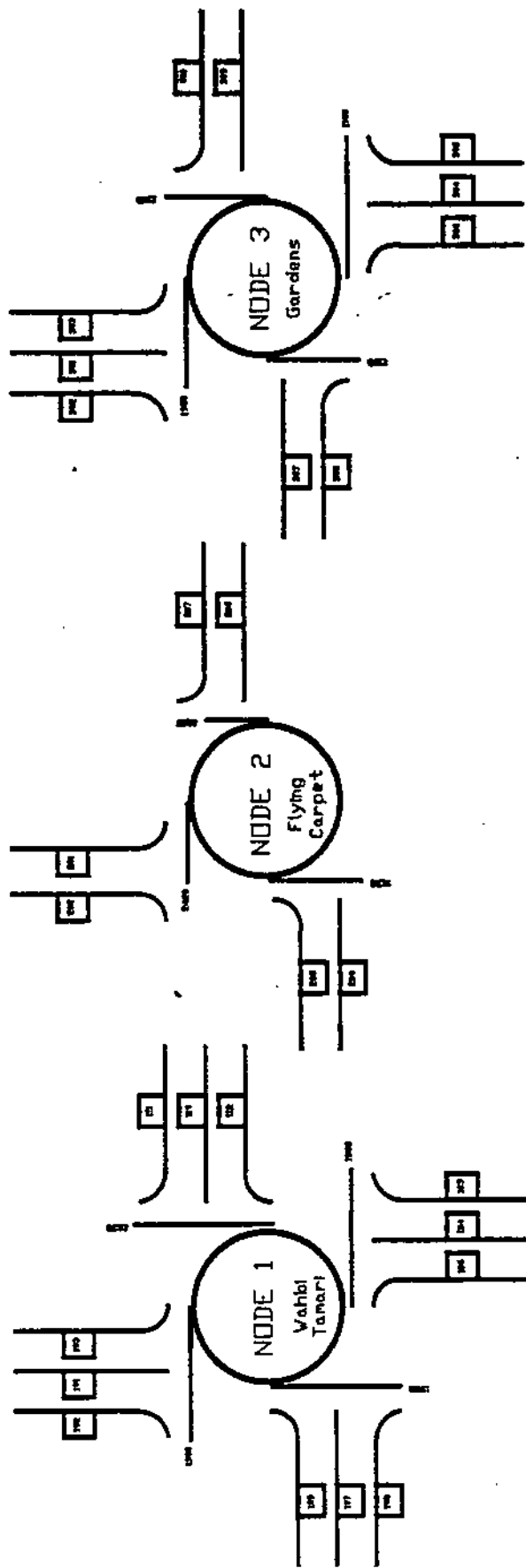
Weather Conditions: Sunny







Prince Shaker Street



Schematic Node/Link Diagram

TRANSYT-7F
DATA COLLECTION SHEET - TOTAL VOLUME COUNT STUDY

CITY Amman NETWORK Prince Shaker St.

LOCATION Walbi Jamari

NODES IN INFLUENCE AREA 1

COLLECTED BY _____

COMPLETED BY _____ DATE _____

COMMENTS _____

TIME PERIOD	DAY% DAY/DATE OF COUNTS					WEEK TOTAL	AVERAGE	DESIGN PERIOD AND HOURS
	MON.	TUES.	WED.	THURS.	FRI.			
<i>North</i> 7:30-7:45		100						1/2 Hr Peak
7:45-8:00		97						
8:00-8:15		78						
8:15-8:30		65						
8:30-8:45		48						
8:45-9:00		55						
9:00-9:15		31						
9:15-9:30		42						
<i>South</i> 7:30-7:45		153						1/2 Hr Peak
7:45-8:00		161						
8:00-8:15		151						
8:15-8:30		120						
8:30-8:45		100						
8:45-9:00		58						
9:00-9:15		76						
9:15-9:30		90						

TRANSYT-7F
DATA COLLECTION SHEET - TOTAL VOLUME COUNT STUDY

CITY Amman NETWORK Prince Shaker St.
 LOCATION Wahbi Jamari
 NODES IN INFLUENCE AREA 1
 COLLECTED BY _____
 COMPLETED BY _____ DATE _____
 COMMENTS _____

TIME PERIOD	DAY% DAY/DATE OF COUNTS					WEEK TOTAL	AVERAGE	DESIGN PERIOD AND HOURS
	MON.	TUES.	WED.	THURS.	FRI.			
7:30-7:45		160						↑ 1/2 Hr Peak ↓
7:45-8:00		162						
8:00-8:15		209						
8:15-8:30		106						
8:30-8:45		141						
8:45-9:00		164						
9:00-9:15		158						
9:15-9:30		196						
								↑ 1/2 Hr Peak ↓
7:30-7:45		295						
7:45-8:00		331						
8:00-8:15		281						
8:15-8:30		286						
8:30-8:45		253						
8:45-9:00		225						
9:00-9:15		263						
9:15-9:30		244						

TRANSYT-7F
DATA COLLECTION SHEET - TOTAL VOLUME COUNT STUDY

CITY Amman NETWORK Prince Shaker St.

LOCATION Flying Carpet

NODES IN INFLUENCE AREA 1

COLLECTED BY _____

COMPLETED BY _____ DATE _____

COMMENTS _____

TIME PERIOD	DAY% DAY/DATE OF COUNTS					WEEK TOTAL	AVERAGE	DESIGN PERIOD AND HOURS
	MON.	TUES.	WED.	THURS.	FRI.			
7:30-7:45		203						1/2 Hr Peak
7:45-8:00		212						
8:00-8:15		213						
8:15-8:30		191						1/2 Hr Peak
8:30-8:45		184						
8:45-9:00		158						
9:00-9:15		119						
9:15-9:30		120						
7:30-7:45		146						
7:45-8:00		133						1/2 Hr Peak
8:00-8:15		100						
8:15-8:30		96						
8:30-8:45		128						1/2 Hr Peak
8:45-9:00		149						
9:00-9:15		96						
9:15-9:30		101						
7:30-7:45		311						
7:45-8:00		319						
8:00-8:15		287						1/2 Hr Peak
8:15-8:30		297						
8:30-8:45		253						
8:45-9:00		143						
9:00-9:15		196						
9:15-9:30		237						

North

East

West

TRANSYT-7F
DATA COLLECTION SHEET - TOTAL VOLUME COUNT STUDY

CITY Amman NETWORK Prince Shaker St.

LOCATION Gardens

NODES IN INFLUENCE AREA 1

COLLECTED BY _____

COMPLETED BY _____ DATE _____

COMMENTS _____

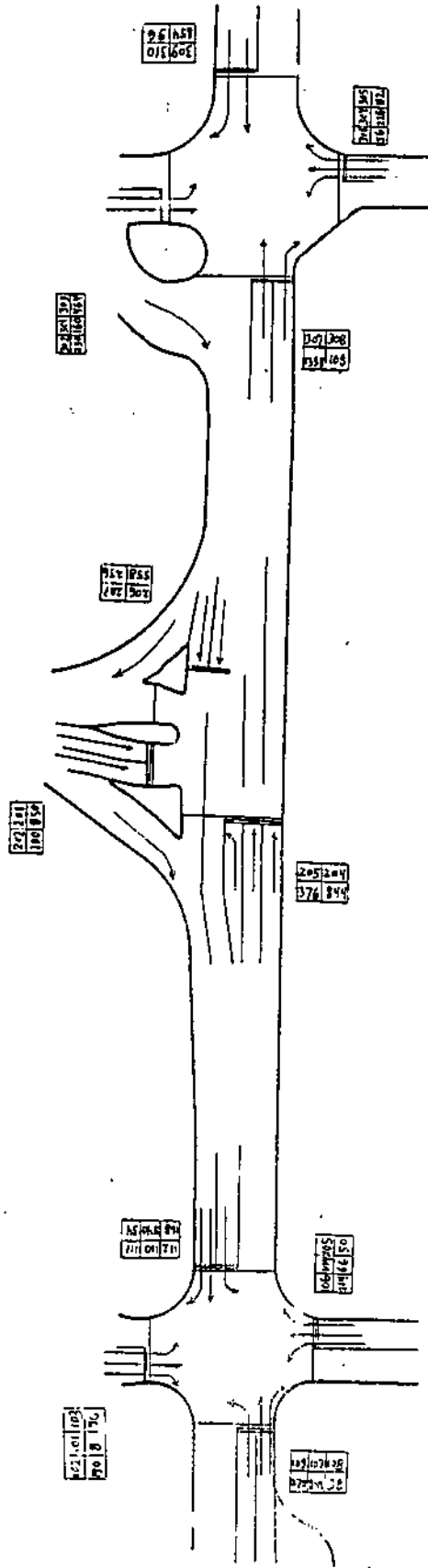
TIME PERIOD	DAY% DAY/DATE OF COUNTS					WEEK TOTAL	AVERAGE	DESIGN PERIOD AND HOURS
	MON.	TUES.	WED.	THURS.	FRI.			
7:30-7:45		114						1/2 Hr Peak
7:45-8:00		172						
8:00-8:15		140						
8:15-8:30		91						
8:30-8:45		88						
8:45-9:00		83						
9:00-9:15		93						1/2 Hr Peak
9:15-9:30		79						
7:30-7:45		80						
7:45-8:00		117						
8:00-8:15		62						
8:15-8:30		48						
8:30-8:45		40						1/2 Hr Peak
8:45-9:00		35						
9:00-9:15		33						
9:15-9:30		36						
7:30-7:45		343		201				
7:45-8:00		378		236				
8:00-8:15		355		239				1/2 Hr Peak
8:15-8:30		326		201				
8:30-8:45		325		155				
8:45-9:00		253		169				
9:00-9:15		282		203				
9:15-9:30		226		178				

North

South

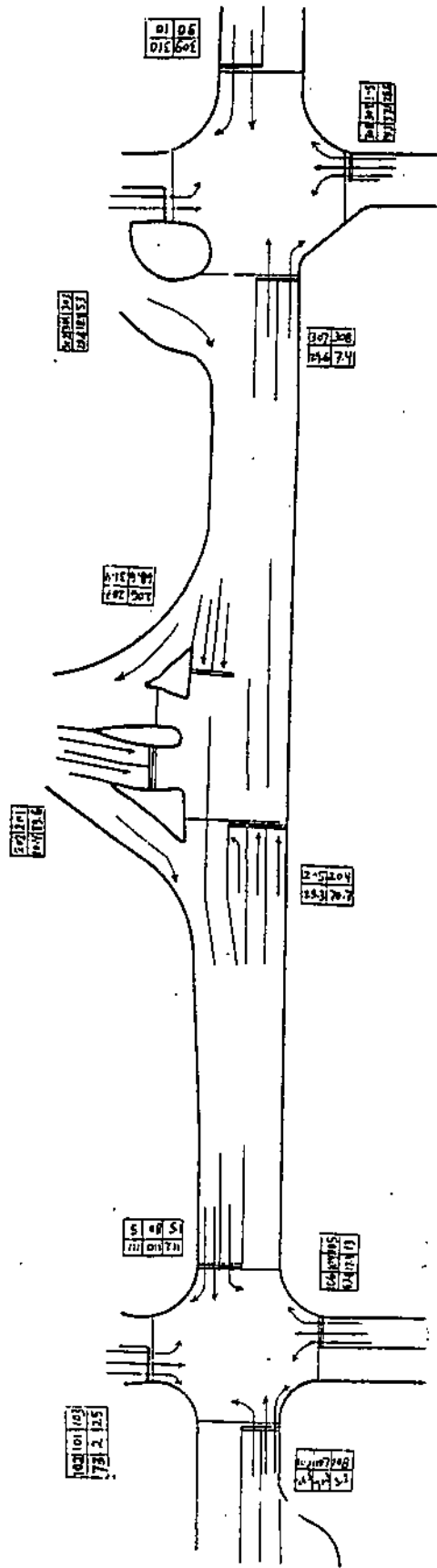
East-West

Total Volumes and Turning Movements
Design Hourly Volumes (DHV)



Total Flow By Link and By Movement (percentages)

Period 8:00 - 8:15
Sunday Sep 9, 1990



TRANSYT-7F

DATA COLLECTION SHEET - TURNING MOVEMENT COUNTS

CITY Amman NETWORK Prince Shaker St.
 INTERSECTION Wahbi Tamari NODE NO. 1 PERIOD _____
 COLLECTED BY _____ DATE _____ COMMENT/WEATHER _____

TIME PERIOD	A AVE.												1 ST									
	NORTHBOUND						SOUTHBOUND						EASTBOUND					WESTBOUND				
	LEFT	THRU	RT	RTOR	TOT.	LEFT	THRU	RT	RTOR	TOT.	LEFT	THRU	RT	RTOR	TOT.	LEFT	THRU	RT	RTOR	TOT.	GRAND TOTAL	
7:30 - 7:45	22	2	76		100	62	13	10		85	40	113	7		160	60	225	10		295	640	
- 8:00	26	2	69		97	64	16	12		92	46	109	7		162	125	197	9		331	682	
- 8:15	22	2	54		78	68	17	13		98	38	161	10		209	84	188	9		281	666	
- 8:30	18	1	46		65	31	9	6		46	7	93	6		106	75	202	9		286	503	
PEAK 30 MIN	48	4	145		197	132	33	25		190	84	270	17		371	185	422	19		626		

TRANSYT-7F

DATA COLLECTION SHEET - TURNING MOVEMENT COUNTS

CITY Amman NETWORK Prince Shaker St
 INTERSECTION Flying Carpet NODE NO. 2 PERIOD _____
 COLLECTED BY _____ DATE _____ COMMENT/WEATHER _____

TIME PERIOD	A AVE.												GRAND TOTAL							
	NORTHBOUND				SOUTHBOUND				EASTBOUND					WESTBOUND						
	LEFT	THRU	PERM	TOT.	LEFT	THRU	RTOG	RTOR	TOT.	LEFT	THRU	RTOG		RTOR	TOT.	LEFT	THRU	RTOG	RTOR	TOT.
7:30 - 7:45	203		24	203											91	220			311	660
- 8:00	212		25	212											97	222			319	664
- 8:15	213		25	213											83	204			287	600
- 8:30	191		22	191											89	208			297	584
PEAK 30 MIN	425			425											188	442			630	

TRANSYT-7F

DATA COLLECTION SHEET - TURNING MOVEMENT COUNTS

CITY Amman NETWORK Prince Shaker St
 INTERSECTION Gardens NODE NO. 3 PERIOD _____
 COLLECTED BY _____ DATE _____ COMMENT/WEATHER _____

TIME PERIOD	A AVE.												GRAND TOTAL						
	NORTHBOUND						SOUTHBOUND							1ST					
	LEFT	THRU	RT	TOT.	LEFT	THRU	RT	TOT.	LEFT	THRU	RT	TOT.		LEFT	THRU	RT	TOT.		
7:30 - 7:45	85	29	46	114	11	46	23	80	181	20	201	318	25	343	738				
- 8:00	128	44	69	172	17	67	33	117	212	24	236	350	28	378	903				
- 8:15	104	36	56	140	9	35	18	62	215	24	239	329	26	355	196				
- 8:30	68	23	36	91	7	27	14	48	181	20	201	302	24	326	666				
PEAK 30 MIN	232	80	125	312	28	113	56	197	427	48	475	679	54	733					

TRANSYT - 7F
DATA REDUCTION WORKSHEET - TOTAL VOLUMES AND TURNING MOVEMENTS

CITY Amman NETWORK Prince Shaker St.
 INTERSECTION Wabbi Tamari NODE 1
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

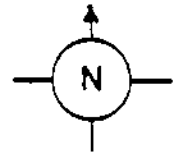
KEY

Peak 1/2-hour Volume

*Design Hourly Volume (DHV)

VEHICLES

145	4	48
190	8	96



19	422	185
38	844	270



168	540	34
84	270	17

264	66	50
132	33	25

TRANSYT - 7F
 DATA REDUCTION WORKSHEET - TOTAL VOLUMES AND TURNING MOVEMENTS

CITY _____ NETWORK _____
 INTERSECTION Gardens NODE 3
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

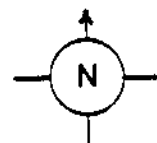
KEY

Peak 1/2-hour Volume

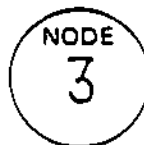
*Design Hourly Volume (DHV)

VEHICLES

125	80	232
250	160	464



54	679
108	1358

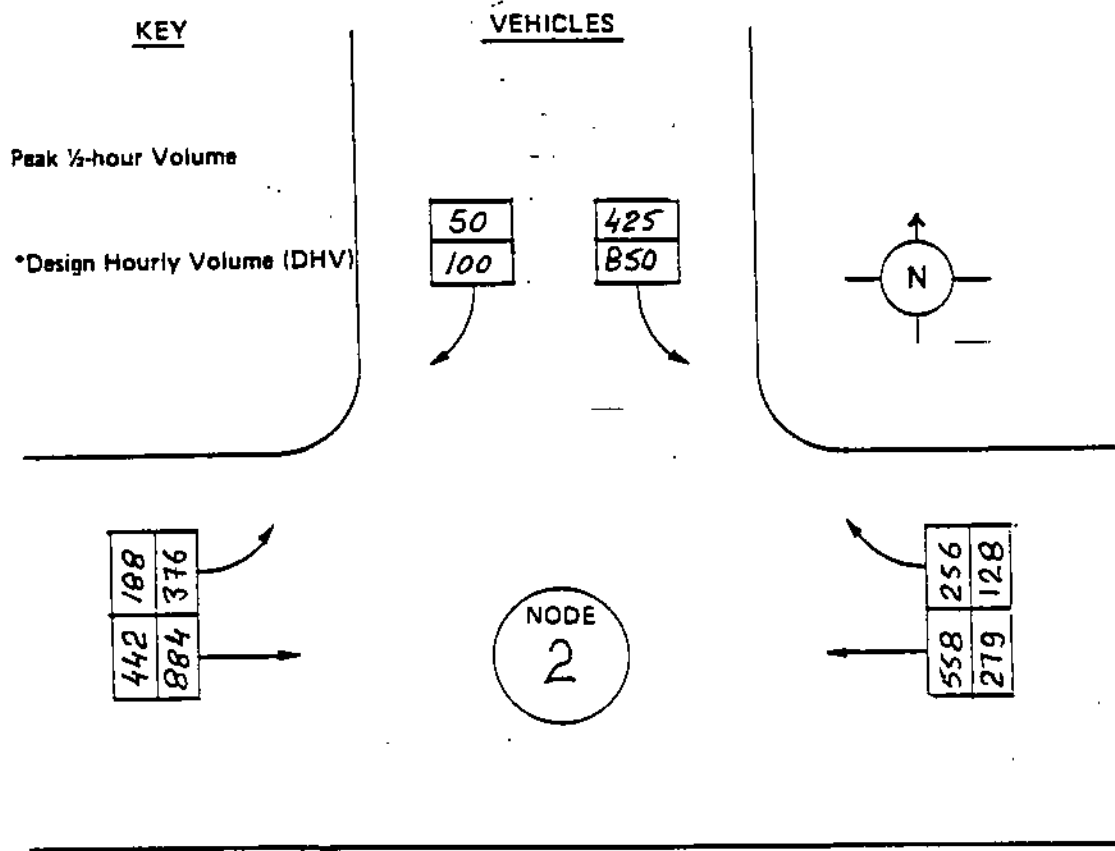


854	96
427	48

56	226	112
28	113	56

TRANSYT - 7F
 DATA REDUCTION WORKSHEET - TOTAL VOLUMES AND TURNING MOVEMENTS

CITY _____ NETWORK _____
 INTERSECTION Flying Carpet NODE 2
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____



DATA REDUCTION WORKSHEET - TOTAL VOLUMES AND TURNING MOVEMENTS

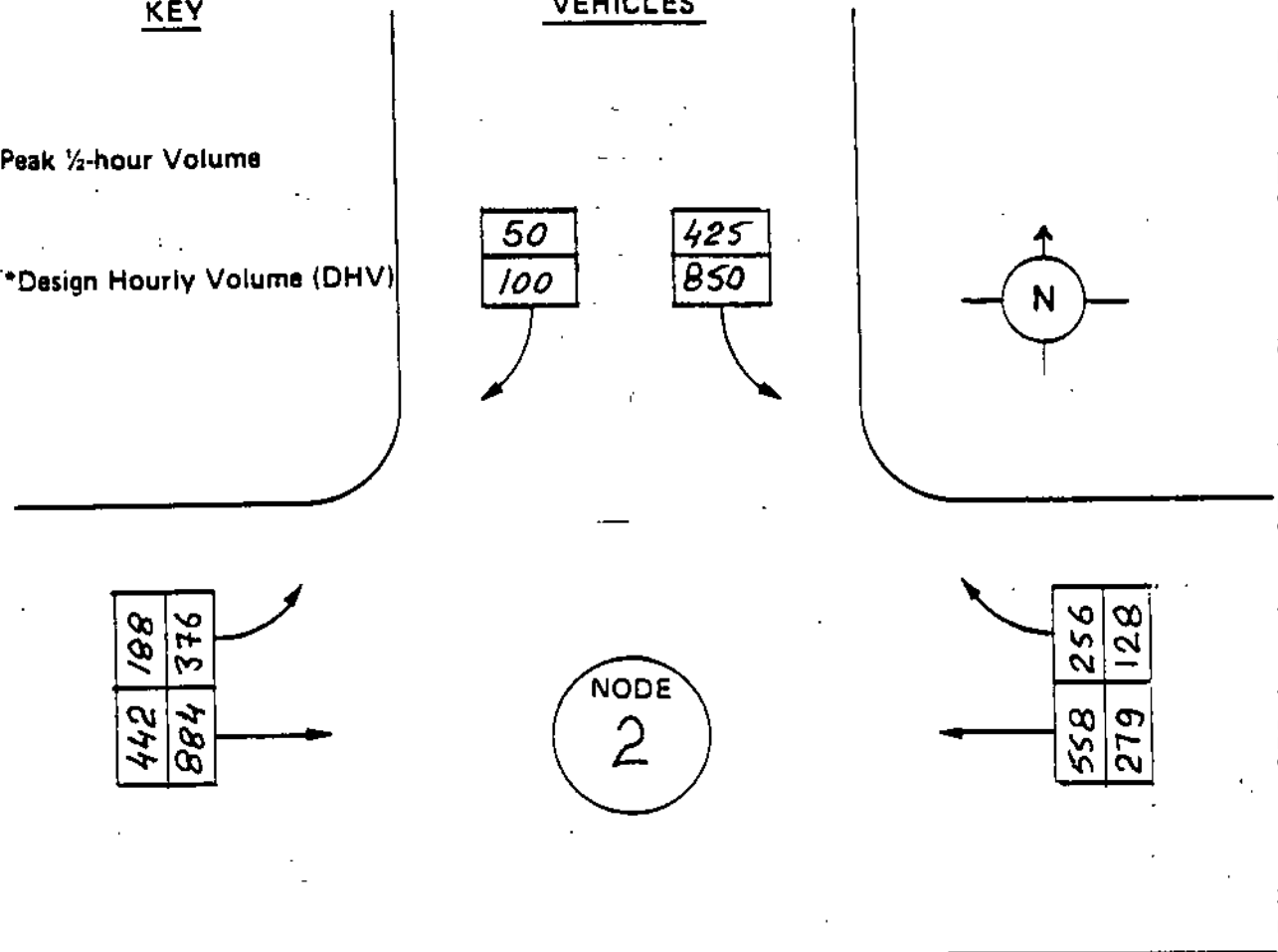
CITY _____ NETWORK _____
 INTERSECTION Flying Carpet NODE 2
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

KEY

Peak 1/2-hour Volume

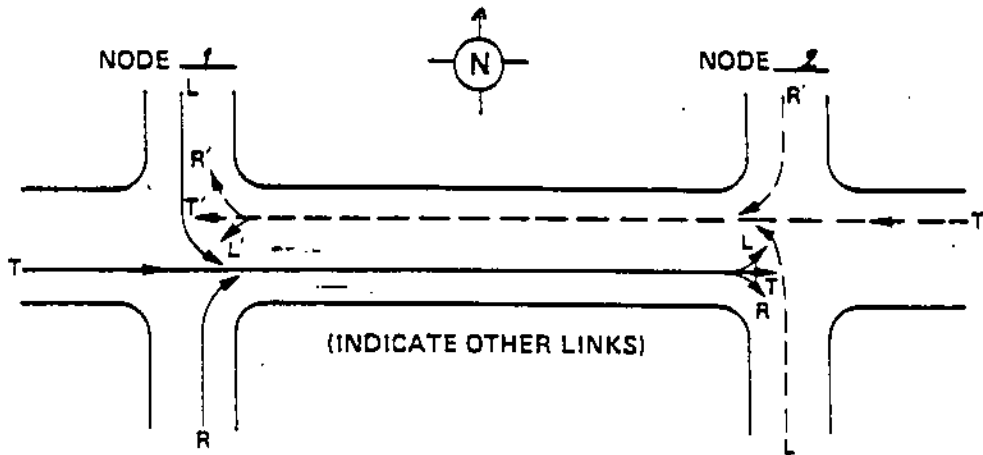
*Design Hourly Volume (DHV)

VEHICLES



TRANSYT - 7F
DATA COLLECTION SHEET - LINK-TO-LINK SAMPLES

CITY _____ NETWORK _____
 STREET _____ PERIOD _____
 LEFT INTERSECTION wahbi Tamari NODE NO. 1
 RIGHT INTERSECTION Flying Carpet NODE NO. 2
 COLLECTED BY _____ DATE _____ WEATHER _____
 COMMENT _____



LEFT TO RIGHT
TO NODE 2

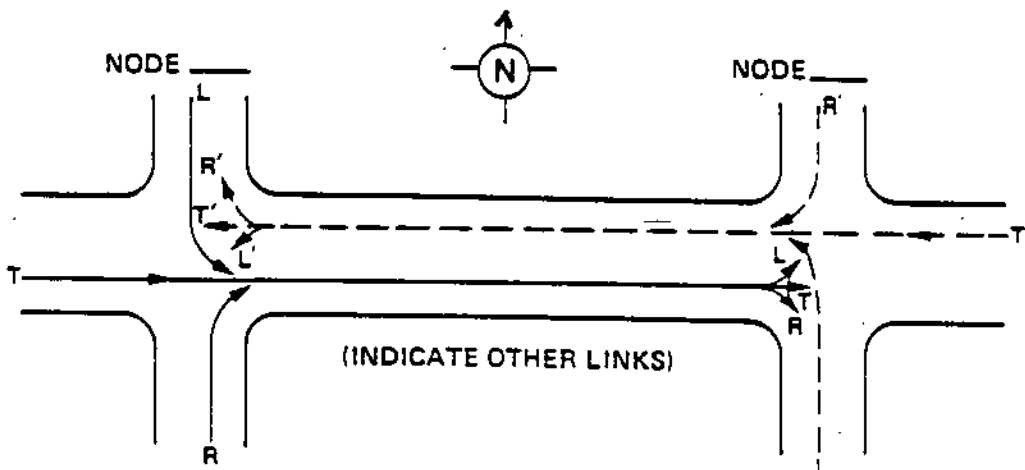
		L	T	R	TOTAL
FROM NODE <u>1</u>	L		96		96
			100%		
	T	254	590		844
		30%	70%		
R		50		50	
			100%		

RIGHT TO LEFT
TO NODE 1

		L'	T'	R'	TOTAL
FROM NODE <u>2</u>	L'		100		100
			100%		
	T'	84	446	29	559
		15%	80%	5%	
R'					

TRANSYT - 7F
DATA COLLECTION SHEET - LINK-TO-LINK SAMPLES

CITY Amman NETWORK Prince Shaker St.
 STREET _____ PERIOD _____
 LEFT INTERSECTION Flying Carpet NODE NO. 2
 RIGHT INTERSECTION gardens NODE NO. 3
 COLLECTED BY _____ DATE _____ WEATHER _____
 COMMENT _____



LEFT TO RIGHT
TO NODE 3

		L	T	R	TOTAL
FROM NODE <u>2</u>	L		850		850
			100%		
	T		776	68	844
			92%	8%	
R					

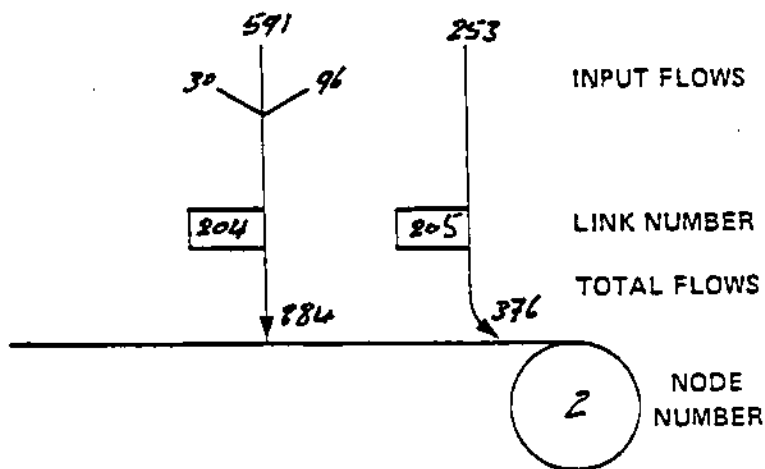
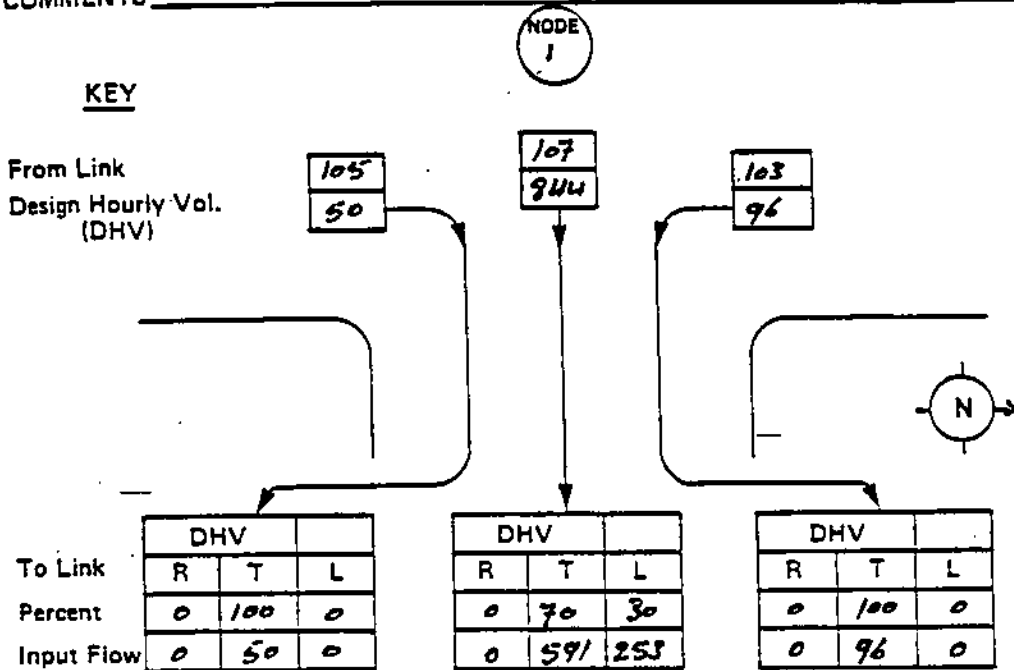
RIGHT TO LEFT
TO NODE 2

		L'	T'	R'	TOTAL
FROM NODE <u>3</u>	L'		250		250
			100%		
	T'		598	256	854
			70%	30%	
R'					

TRANSYT - 7F
DATA REDUCTION WORKSHEET - LINK INPUTS

CITY Amman NETWORK Prince shaker st.
 FROM INTERSECTION Wabbi Tamari NODE 1
 TO INTERSECTION Flying Carpet NODE 2
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

KEY



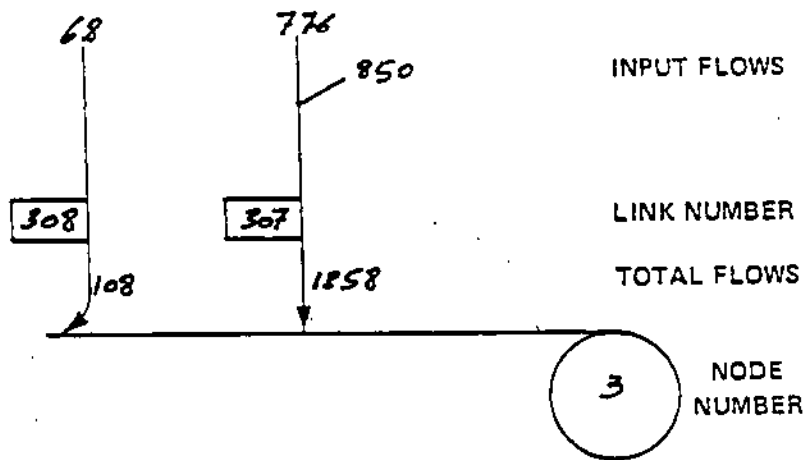
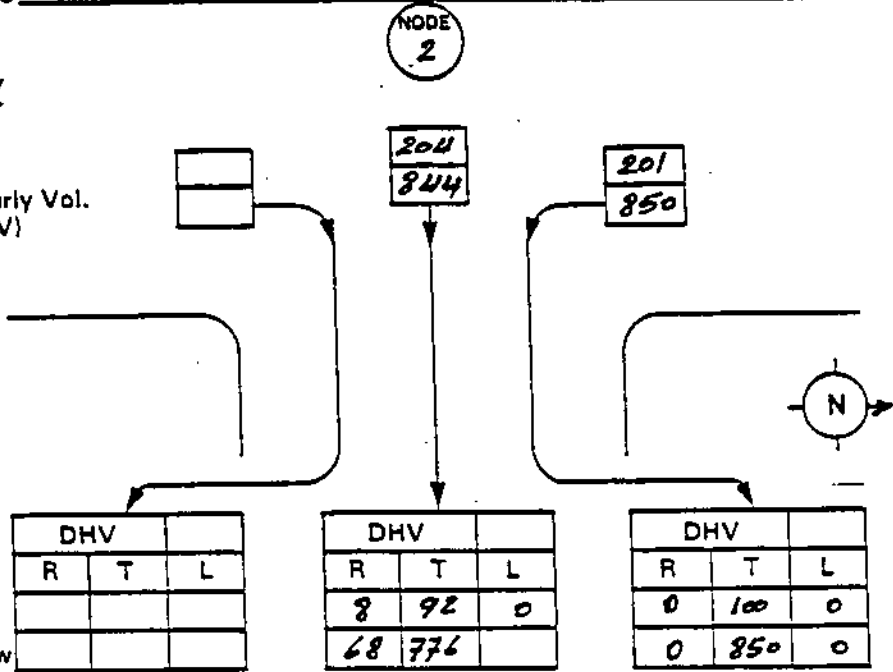
TRANSYT - 7F
DATA REDUCTION WORKSHEET - LINK INPUTS

CITY Amman NETWORK Prince shaker st
 FROM INTERSECTION Flying Carpet NODE 2
 TO INTERSECTION Gardens NODE 3
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

KEY

From Link
Design Hourly Vol.
(DHV)

To Link
Percent
Input Flow



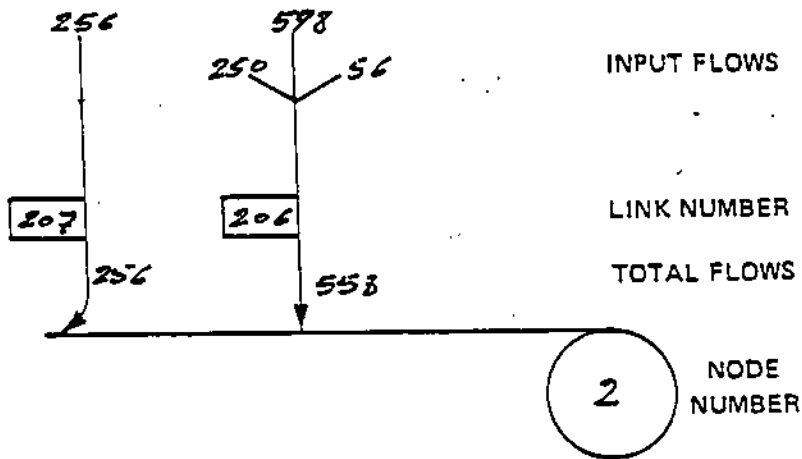
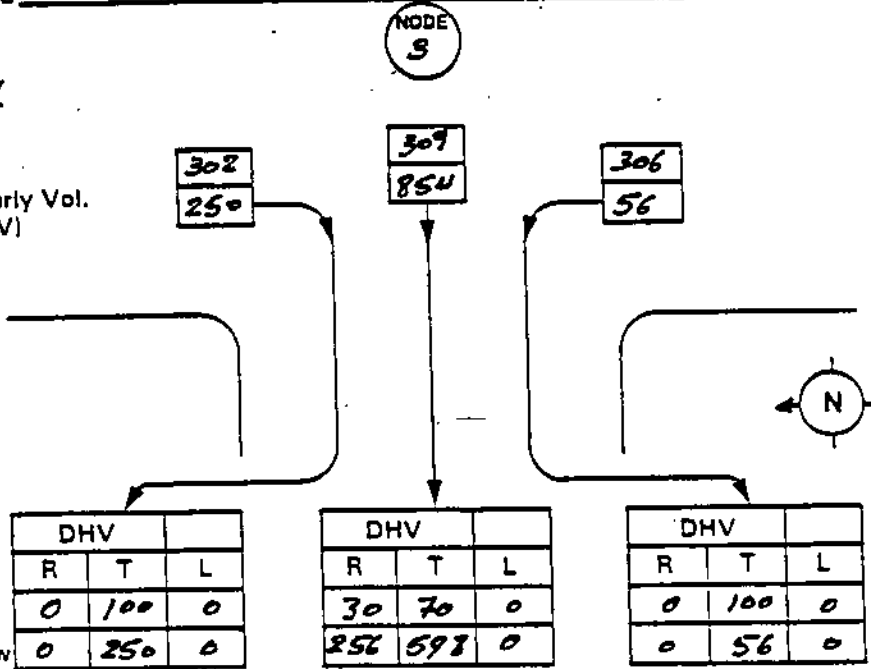
TRANSYT - 7F
DATA REDUCTION WORKSHEET - LINK INPUTS

CITY Amman NETWORK Prince shaker st.
 FROM INTERSECTION Gardens NODE 9
 TO INTERSECTION Flying Carpet NODE 2
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

KEY

From Link
Design Hourly Vol.
(DHV)

To Link
Percent
Input Flow



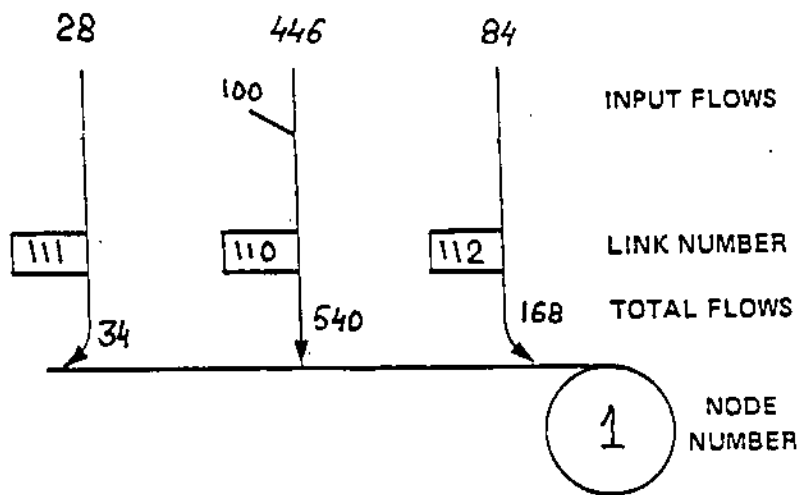
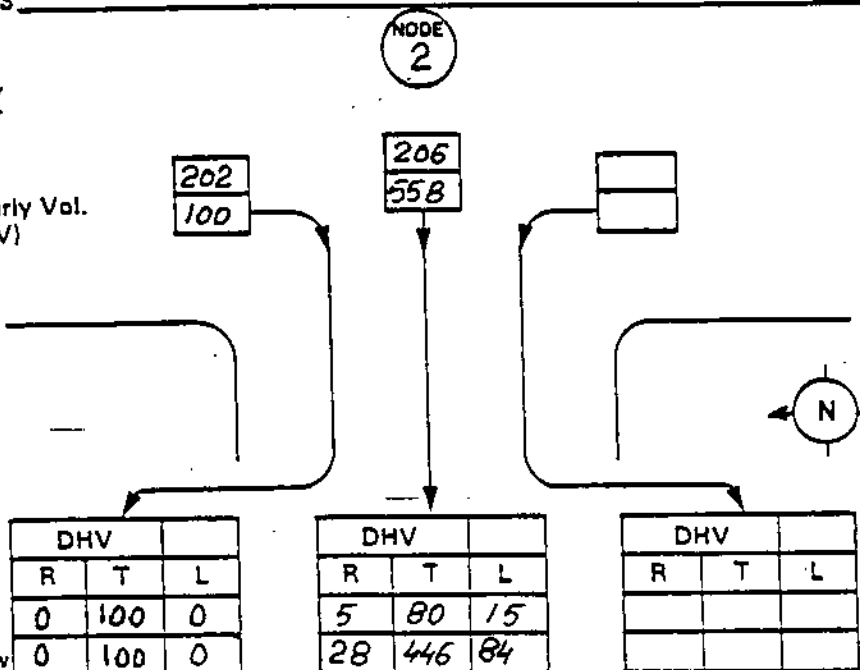
TRANSYT - 7F
DATA REDUCTION WORKSHEET - LINK INPUTS

CITY Amman NETWORK Prince Shaker st.
 FROM INTERSECTION Flying Carpet NODE 2
 TO INTERSECTION Wabbi Tamari NODE 1
 COMPLETED BY _____ DATE _____
 REFERENCES _____ PERIOD _____
 COMMENTS _____

KEY

































From Link
Design Hourly Vol.
(DHV)

To Link
Percent
Input Flow



















Phase sequences:

















Node 1

1	4	7	10
 12 1 3 1	 12 1 3 1	 22 1 3 1	 22 1 3 1
 22 1 3 1	 13 1 3 1	 12 1 3 1	 33 1 3 1
 13 1 3 1	 33 1 3 1	 13 1 3 1	 13 1 3 1
 33 1 3 1	 22 1 3 1	 33 1 3 1	 12 1 3 1
2	5	8	11
 12 1 3 1	 12 1 3 1	 22 1 3 1	 22 1 3 1
 22 1 3 1	 13 1 3 1	 12 1 3 1	 13 1 3 1
 33 1 3 1	 22 1 3 1	 33 1 3 1	 33 1 3 1
 13 1 3 1	 33 1 3 1	 13 1 3 1	 12 1 3 1

3	↓	12 1 3 1	6	↓	12 1 3 1	9	←	22 1 3 1	12	←	22 1 3 1
	→	33 1 3 1		→	33 1 3 1		→	33 1 3 1		↑	13 1 3 1
	←	22 1 3 1		↑	13 1 3 1		↓	12 1 3 1		↓	12 1 3 1
	↑	13 1 3 1		←	22 1 3 1		↑	13 1 3 1		→	33 1 3 1

13	→	33 1 3 1	16	↑	13 1 3 1	19	↑	13 1 3 1	22	↑	13 1 3 1
	←	22 1 3 1		←	22 1 3 1		←	22 1 3 1		↓	12 1 3 1
	↓	12 1 3 1		↓	12 1 3 1		→	33 1 3 1		→	33 1 3 1
	↑	13 1 3 1		→	33 1 3 1		↓	12 1 3 1		←	22 1 3 1

14		17		20		23	
	33 1 3 1		13 1 3 1		13 1 3 1		13 1 3 1
	13 1 3 1		12 1 3 1		33 1 3 1		33 1 3 1
	22 1 3 1		22 1 3 1		22 1 3 1		12 1 3 1
	12 1 3 1		33 1 3 1		12 1 3 1		22 1 3 1

15		18		21		24	
	33 1 3 1		33 1 3 1		33 1 3 1		33 1 3 1
	13 1 3 1		12 1 3 1		12 1 3 1		22 1 3 1
	12 1 3 1		22 1 3 1		13 1 3 1		13 1 3 1
	22 1 3 1		13 1 3 1		22 1 3 1		12 1 3 1

Node 2

1		2		3		4		5		6	
	28 1 3 1		23 1 3 1		23 1 3 1		28 1 3 1		34 1 3 1		34 1 3 1
	23 1 3 1		34 1 3 1		28 1 3 1		34 1 3 1		23 1 3 1		28 1 3 1
	34 1 3 1		28 1 3 1		34 1 3 1		23 1 3 1		28 1 3 1		23 1 3 1

Node 3

1		2		3		4		5		6	
	43 1 3 1		43 1 3 1		23 1 3 1		23 1 3 1		19 1 3 1		19 1 3 1
	23 1 3 1		19 1 3 1		43 1 3 1		19 1 3 1		23 1 3 1		43 1 3 1
	19 1 3 1		23 1 3 1		19 1 3 1		43 1 3 1		43 1 3 1		23 1 3 1

APPENDIX F

COMPLETE SAMPLE OUTPUT

1 TRANSVT - 7F -- TRAFFIC SIGNAL SYSTEM OPTIMIZATION PROGRAM

VERSION 3.0

RELEASE 6 OCTOBER 1980

SPONSORED BY:
FEDERAL HIGHWAY ADMINISTRATION
OFFICE OF TRAFFIC OPERATIONS

DEVELOPED BY:
TRANSPORT AND ROAD RESEARCH LABORATORY
UNITED KINGDOM AND
TRANSPORTATION RESEARCH CENTER
UNIVERSITY OF FLORIDA

DATE OF RUN: 12/26/80 START TIME OF RUN: 13:11:13

INPUT DATA REPORT FOR RUN 1

FIELDS: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

LINE NO. TITLE RUN TITLE CARD

1) PRINCE SHAKER STREET

NETWORK CONTROL CARD

LINE NO.	CARD TYPE	MIN CYCLE	MAX CYCLE INCR.	CYCLE	SEC/STEP	SEC/STEP	STEP	LOSS	GREEN	STOP	EXTEN.	PENALTY	LEVEL	OUTPUT	INITIAL	PERIOD	SEC(0)	SPD(0)	ENGL(0)	PINCH
																LENGTH	PERC(0)	TIME(0)	METRC(0)	DECK
2)	1	90	125	5	3	1	3	3	-1	0	0	0	0	0	0	30	0	0	1	0

*** 106 *** WARNING *
THE SEC/STEPS FACTOR IN FIELD 6 IS TOO SMALL FOR CYCLE LENGTHS ABOVE 80 SECONDS. IT WILL BE INCREASED TO ALLOW A MAXIMUM OF 60 STEPS/CYCLE.

*** 107 *** WARNING *
A STOP PENALTY OF "-1" WILL RESULT IN AUTOMATIC CALCULATION OF THE PI TO MINIMIZE FUEL CONSUMPTION. LINK SPECIFIC DELAY OR STOP WEIGHTS ON CARD TYPE 37 & 38 WILL STILL BE APPLIED, HOWEVER.

*** 114 *** WARNING *
INITIAL TIMING FLAG SET TO "1" FOR CYCLE RANGE EVALUATION.

LINE CARD TYPE LIST OF NODES TO BE OPTIMIZED

3)	2	1	2	3	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
----	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

LINE CARD TYPE FIRST SET..... SECOND SET..... THIRD SET.....

ITRANSVT-7F: PRINCE SHAWER STREET

FIELD:	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
1)	7	107	108	109	0	0	110	111	112	0	0	101	102	103	0	0
5)	7	104	105	106	0	0	307	308	309	0	0	309	310	0	0	0
6)	7	301	303	0	0	0	304	305	306	0	0	0	0	0	0	0

LINE NO.	CARD TYPE	MASTER SYSTEM YELLOW	DEFAULTS ALL-RED	SYSTEM SPEED	EXTERNAL SPEED	ORIENT- DESIRED	VEHICLE ORIENT- DESIRED	2-OF SAT	2-CYC	HEIGHT	INFLAT RATE	FUEL COST	VEHICLE OCC.	
7)	10	0	4	1	1800	35	50	0	0	0	0	75	100	0

--- PROGRAM NOTE --- NON-DEFAULT INPUT UNITS HERE SPECIFIED AS FOLLOWS:

* ENGLISH/METRIC UNITS IN METRIC

INTERSECTION 1

LINE NO.	CARD TYPE	NO.	MODE	OFFSET/ YLD-PT.	REF INT	INT1	INT2	INT3	INT4	INT5	INT6	INT7	INT8	INT9	INT10	INT11	DOUBLE CYCLE
8)	14	1	1	0	1	12	1	3	1	22	1	3	1	33	1	3	0

CONTROLLER TIMING DATA

LINE NO.	CARD TYPE	NO.	MODE	INTERVAL DURATION	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
9)	18	1	1	13	1	3	1	0	0	0	0	0	0	0	0	0	0	0	0	0

CONTROLLER TIMING DATA (CONTINUED)

LINE NO.	CARD TYPE	NO.	MODE	INTERVAL DURATION	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
10)	21	1	1	14	1	4	1	101	102	103	104	105	106	107	108	109	110	111	112	113

PHASE TIMING DATA

LINE NO.	CARD TYPE	NO.	MODE	START INTVL	VARIAL. INTVL	YELLOW INTVL	ALL-RED INTVL	MINIM. SECS.	LINKS MOVING IN THIS PHASE	PHASE TYPE
11)	22	1	1	5	13	14	15	16	17	18

LINK DATA

LINE NO.	CARD TYPE	LINK NO.	LINK LENGTH	SAT. FLOW	TOTAL VOL.	MID-BLK. VOL.	FIRST INPUT LINK VOL.	SECOND INPUT LINK VOL.	THIRD INPUT LINK VOL.	QUEUE CAP.
12)	23	1	3	10	12	13	14	15	16	17

TRANSVY-7F: FRINCE SHAKER STREET

FIELDS: 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16

CONTROLLER TIMING DATA (CONTINUED)

LINE NO.	CARD TYPE	MODE NO.	INT12	INT13	INT14	INT15	INT16	INT17	INT18	INT19	INT20	INT21	INT22	INT23	INT24	INT25
380	1A	3	1	0	0	0	0	0	0	0	0	0	0	0	0	0

LINE NO.	CARD TYPE	MODE NO.	START INTVL	VARIABLE INTVL	YELLOW INTVL	ALL-RED INTVL	MINI-SECS.	PHASE TIMING DATA			PHASE TYPE					
								LINKS MOVING IN THIS PHASE	NO.	SPD/TT						
393	21	3	1	1	2	4	21	301	302	303	0	0	0	0	0	0
402	22	3	5	5	6	8	34	307	308	309	310	302	0	0	0	0
411	23	3	9	9	10	12	19	304	305	306	302	0	0	0	0	0

LINE NO.	CARD TYPE	LINK NO.	LINK LENGTH	SAT. FLOW	TOTAL VAL.	MID-BLK. VOL.	LINK DATA		SECOND INPUT LINK NO.	SECOND INPUT VOL.	SECOND INPUT SPD/TT	THIRD INPUT LINK NO.	THIRD INPUT VOL.	THIRD INPUT SPD/TT	QUEUE CAP.
							FIRST INPUT LINK NO.	FIRST INPUT VOL.							
420	28	301	300	1950	150	0	0	0	0	35	0	0	0	0	0
430	28	302	300	1200	250	0	0	0	0	35	0	0	0	0	0
440	28	303	300	0	464	0	0	0	0	35	0	0	0	0	0
450	28	304	600	1100	225	0	0	0	0	35	0	0	0	0	0
460	28	305	600	0	112	0	0	0	0	35	0	0	0	0	0
470	28	306	600	0	56	0	0	0	0	35	0	0	0	0	0
480	28	307	177	2150	1358	0	204	776	201	850	40	0	0	0	0
490	28	308	177	0	108	0	204	68	0	0	0	0	0	0	0
500	28	309	300	2150	854	0	0	0	0	35	0	0	0	0	0
510	28	310	300	0	96	0	0	0	0	35	0	0	0	0	0

RUN CARD

LINE NO.	CARD TYPE	PI TYPE	NO.	VAL.	NO.	VAL.	NO.	VAL.	NO.	VAL.	NO.	VAL.	NO.	VAL.	NO.	VAL.
520	53	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0

PROGRAM NOTE --- A CARD TYPE 53 CAUSES RUN TO BE OPTIMIZED USING THE DEFAULT QUICK OPTIMIZATION STEP SIZES. IF CARD TYPE 4 HAS INPUT, IT IS IGNORED.

THE ABOVE WILL BE PROCESSED AFTER THE "BEST" CYCLE LENGTH HAS BEEN SELECTED.

PROGRAM NOTE --- NO ERRORS DETECTED. TRANSVY-7F PERFORMS FINAL PROCESSING. IF ERRORS ARE DETECTED, FURTHER PROCESSING IS SUSPENDED.

PROGRAM NOTE --- THERE ARE A TOTAL OF 3 MODES AND 28 LINKS, INCLUDING BOTTLENECKS, IF ANY, IN THIS RUN.

PROGRAM NOTE --- THERE WERE A TOTAL OF 3 WARNING MESSAGES ISSUED IN THE ABOVE REPORT.

 CYCLE EVALUATION SUMMARY PERFORMANCE

CYCLE LENGTH (SEC)	STEP SIZE (STEPS)	AVERAGE DELAY (SEC/VEH)	PERCENT STOP(S) (%)	FUEL CONSUMPTION (GAL/HR)	PERFORMANCE INDEX	NUMBER SATURATED LINKS
90	30	181.94	63	1704.4	361.0	22
95	32	177.83	62	1673.5	352.9	22
100	33	177.22	60	1666.0	351.1	22
105	35	173.61	54	1635.1	342.7	21
110	37	172.85	55	1630.5	341.5	21
115	38	172.05	53	1622.1	339.3	22
120	40	171.88	54	1622.1	339.3	21
125	42	170.65	54	1613.4	337.0	21

BEST CYCLE LENGTH = 125 SEC. CYCLE SENSITIVITY = 2.4 %

--- PROGRAM NOTE --- TRANSYT-7F OPTIMIZES THE SYSTEM USING THE BEST CYCLE LENGTH AND HILL-CLIMB STEP SIZES AS INDICATED BY CARD TYPE 53.

<PERFORMANCE WITH OPTIMAL SETTINGS>

MODE LINK NO.	FLOW (VEH/H)	SAT (VEH/H)	DEGREE OF SAT	TOTAL TRAVEL TIME (VEH-H/HD)	TOTAL DELAY (VEH-H/HD)	AVERAGE DELAY (SEC/VEH)	UNIFORM STOPS (VEH/H)	MAX BACK OF QUEUE (VEH)	QUEUE CAPACITY (VEH/LK)	FUEL CONSUM (L/H)	PHASE LENGTH (SEC)	LINK NO.				
1	101	10	1900P	150*	2.00	1.11	1.05	378.8	6.7C 672D	25	3.34	15	101			
1	102	130	1015	150*	38.00	21.08	19.99	378.8	126.8C 672D	101	61.09	15	102			
1	103	96	1015	150*	19.20	10.65	10.30	378.8	64.1C 672D	101	30.87	15	103			
1	104	66	1690P	168*	13.20	8.66	8.29	452.1	39.2C 592D	20	24.89	17	104			
1	105	50	1015	168*	10.00	6.56	6.28	452.1	29.7C 592D	104	18.86	17	105			
1	106	264	1045	168*	52.80	34.66	33.15	452.1	156.7C 592D	104	99.57	17	106			
1	107	844	1950P	151*	37.60	99.27	88.62	378.0	560.0C 662D	66 >	33C 269.84	51	107			
1	109	38	1075	151*	15.20	4.42	3.99	378.0	25.2C 662D	107	13.05	51	109			
1	110	270	1075	151*	108.00	31.44	28.35	378.0	179.2C 662D	107	92.72	51	110			
1	111	540	2250P	103*	230.04	17.19	10.77	71.8	511.9C 952D	25	61.37	42	111			
1	112	34	1105	103*	14.16	1.06	1.00	58.8	31.6C 952D	110	3.78	42	112			
1	112	168	1105	103*	71.57	5.27	3.23	59.1	159.2C 952D	110	18.75	42	112			
1	1	2370	MAX = 168*	912.09	240.38	43.13	171.28	300.4	1890.2C 742D	718.14	PI = 162.6					
2	201	850	2420	95*	340.00	22.20	8.91	3.57	12.48	52.9	790.8C 932D	29	53	81.57	48	201
2	202	100	1200	8	40.00	1.14	0.00	0.00	0.00	0.00	0.00	0	53	4.50	125	202
2	204	864	2075	71	376.58	12.62	1.70	0.43	2.13	8.7	167.2C 192D	6	56	49.77	77	204
2	205	376	1100	104*	160.18	12.47	1.03	6.87	7.89	75.5	134.3C 362D	6	56	41.38	43	205
2	206	558	2215	96*	38.77	12.82	5.48	4.64	10.12	65.3	510.9C 922D	18	23	45.10	34	206
2	207	256	1200	21	45.31	1.29	0.00	0.00	0.00	0.00	0.00	0	23	5.10	125	207
2	2	3024	MAX = 104*	1060.84	62.55	37.11	15.51	32.63	38.8	1603.2C 532D	227.41	PI = 28.7				
3	301	160	1350P	182*	48.00	23.23	3.78	18.08	21.86	491.9	88.0C 552D	43 >	39C	66.38	24	301
3	302	250	1200	21	75.00	2.14	0.00	0.00	0.00	0.00	0.00	0	39	8.44	125	302
3	303	464	3015	182*	139.20	57.37	10.97	52.42	63.40	491.9	255.2C 552D	301	3015	194.23	24	303
3	304	226	1100P	249*	135.60	41.31	6.55	33.88	48.43	644.0	90.9C 402D	22	79	128.35	20	304
3	305	112	3045	249*	67.20	21.96	3.25	16.79	20.04	644.0	45.0C 402D	304	3045	63.51	20	305
3	306	56	3045	249*	33.60	10.98	1.62	8.40	10.02	644.0	22.5C 402D	304	3045	31.90	20	306
3	307	1358	2150P	108*	240.37	36.76	2.90	27.44	30.34	80.4	409.0C 292D	17	23	113.41	81	307
3	308	108	3075	108*	19.12	3.11	0.38	2.18	2.57	85.5	58.0C 542D	307	3075	9.30	81	308
3	309	854	2150P	70	256.20	11.12	3.43	3.36	3.80	16.0	515.8C 602D	21	39	45.03	81	309
3	310	96	3095	70	28.80	1.25	0.39	0.04	0.43	16.0	58.0C 602D	309	3095	5.06	81	310
3	3	3684	MAX = 249*	1043.00	222.22	33.28	159.59	192.87	188.5	1533.4C 422D	668.80	PI = 145.9				

<SYSTEM WIDE TOTALS INCLUDING ALL LINKS>

TOTAL DISTANCE TRAVELED (VEH-KM/H)	TOTAL TRAVEL TIME (VEH-H/H)	TOTAL UNIFORM DELAY (VEH-H/H)	TOTAL RANDOM DELAY (VEH-H/H)	TOTAL DELAY (VEH-H/H)	AVERAGE DELAY (SEC/VEH)	TOTAL UNIFORM STOPS (VEH/H-2)	TOTAL FUEL CONSUM (L/H)	OPERATING COST	PERFORMANCE INDEX	SPEED (KM/H)
3016.01	525.15	93.58	346.30	439.87	170.71	5026.00	1614.35	2095.22	337.22	5.74
										<TOTALS>

NOTE: PERFORMANCE INDEX IS DEFINED AS:

$$PI = DELAY + STOPS$$

NO. OF SIMULATIONS = 17 NO. OF LINKS = 266 ELAPSED TIME = 2309.0 SEC.

--- PROGRAM NOTE ---INPUT DATA REPORT FOR ROUTE REQUEST NO. 1

LINE NO.	CARD TYPE	TSD FLAG	FINE FLAG	LINE SCALE	TIME SCALE	DIST. SCALE	FFD FLAG	ROUTE SUMMARY FLAG	ROUTE FFD FLAG	ROUTE SUMMARY DATA FLAG	ROUTE ORIENT.
530	60	1	1	0	0	0	1	1	1	1	0

LINE NO. TITLE ROUTE TITLE CARD

540 THE TSD ORIENTATION DOWNWARD ON THE PAGE IS RESTORED

ROUTE LINK LIST

LINE NO.	CARD TYPE	LINK PAIRS ALTERNATING BY DIRECTION	DOWN AND UP	DOWN AND UP	DOWN AND UP	DOWN AND UP	DOWN AND UP	DOWN AND UP	DOWN AND UP								
550	61	107	110	204	206	307	309	0	0	0	0	0	0	0	0	0	0

1 PRINCE SHARER STREET

< T R A N S Y T - 7 F F L O W P R O F I L E D I A G R A M S >

ROUTE TITLE: THE 1SD ORIENTATION CORNBOND ON THE PAGE IS WESTBOUND

SYMBOL KEYS:

FLOW PROFILE SYMBOLS VERTICAL AXIS IS IN YARD.

- I : ARRIVALS WHICH QUEUE, NORMALLY ON RED ON UNOPPOSED LINKS OR DURING PERIODS OF HEAVY OPPOSING FLOW ON OPPOSED LINKS DURING THE PERMITTED PHASE(S).
- S : DEPARTURES FROM QUEUE, NORMALLY AT THE SATURATION FLOW RATE FOR "PROTECTED" LINKS, OR MAXIMUM FLOW RATE FOR PERMITTED, OPPOSED LINKS.
- O : ARRIVALS AND DEPARTURES ON GREEN, WHEN BELOW S'S OR I'S. THESE ARRIVALS JOIN THE BACK OF THE QUEUE.

TIME SCALE (VERTICAL AXIS):

- (BLANK) : PROTECTED GREEN INTERVALS OR UNOPPOSED MOVEMENTS.
- . : PERMITTED GREEN INTERVALS WITH OPPOSING TRAFFIC.
- * : RED INTERVALS.
- M : THE NUMBERS ACROSS THE BOTTOM ARE A TIME SCALE IN UNITS OF STEPS.

NOTE: THE FLOW PROFILE DIAGRAM SHOWS EFFECTIVE GREEN AND RED, NOT ACTUAL. OFFSETS ARE NOT ADJUSTED TO MASTER CONTROLLER, IF ANY.

SYMBOL KEYS:

FLOW PROFILE SYMBOLS (VERTICAL AXIS IS IN FEET).

- I : ARRIVALS WHICH QUEUE, NORMALLY ON RED OR UNOPPOSED LINKS OR DURING PERIODS OF HEAVY OPPOSING FLOW ON OPPOSED LINKS DURING THE PERMITTED PHASE'S).
- S : DEPARTURES FROM QUEUE, NORMALLY AT THE SATURATION FLOW RATE FOR "PROTECTED" LINKS, OF MAXIMUM FLOW RATE FOR PERMITTED, OPPOSED LINKS.
- O : ARRIVALS AND DEPARTURES ON GREEN. WHEN BELOW S'S OR I'S, THESE ARRIVALS JOIN THE BACK OF THE QUEUE.

TIME SCALE (VERTICAL AXIS):

- (ALARM) : PROTECTED GREEN INTERVALS OR UNOPPOSED MOVEMENTS.
- : PERMITTED GREEN INTERVALS WITH OPPOSING TRAFFIC.
- * : RED INTERVALS.
- N : THE NUMBERS ACROSS THE BOTTOM ARE A TIME SCALE IN UNITS OF STEPS.

NOTE: THE FLOW PROFILE DIAGRAM SHOWS EFFECTIVE GREEN AND RED, NOT ACTUAL. OFFSETS ARE NOT ADJUSTED TO MASTER CONTROLLER IF ANY.

<ROUTE SUMMARY REPORT>

LINK NO.	FLOW	SAT FLOW (VEH/H)	DEGREE OF SAT (VEH/H)	TOTAL TRAVEL TIME (VEH-H)	UNIFORM DELAY (VEH-H)	RANDOM DELAY (VEH-H)	AVERAGE DELAY (SEC/VEH)	UNIFORM STOPS (VEH-H)	MARK STOPS (VEH-H)	QUEUE CAPACITY (VEH)	FUEL CONSUM (L/K)	PHASE LENGTH (SEC)	LINK NO.			
1	107	944	1950P	151*	337.60	98.27	17.27	71.35	89.62	378.0	560.0(662)	66	53C 289.04	51	107	
2	204	884	2075	71	376.58	12.62	1.70	2.13	8.7	167.2(192)	6	56	49.77	77	204	
3	307	1358	2150P	108*	240.37	36.76	2.90	27.44	30.34	400.0(292)	17	23	115.41	81	307	
DOWN :																
	3066			151*	954.55	147.65	21.87	99.22	121.09	141.3	1127.2(372)		455.01	PI =	92.2	
1	110	540	2250P	103*	230.04	17.19	3.60	7.17	10.77	71.8	511.9(352)	25	56	61.37	42	110
2	206	558	2215	98*	30.77	12.82	5.48	4.64	10.12	65.3	510.9(322)	18	23	45.10	34	206
3	309	854	2150P	70	256.20	11.12	3.43	3.36	3.80	16.0	515.8(602)	21	39	45.03	81	309
UP :																
	1952			103*	505.01	41.13	12.51	12.18	24.68	45.5	1578.6(792)		151.50	PI =	22.8	

<ROUTE TOTALS>

TOTAL DISTANCE TRAVELED (VEH-KM/H)	TOTAL TRAVEL TIME (VEH-H)	TOTAL UNIFORM DELAY (VEH-H)	TOTAL RANDOM DELAY (VEH-H)	TOTAL DELAY (VEH-H)	AVERAGE DELAY (SEC/VEH)	TOTAL UNIFORM STOPS (VEH-H)	MARK STOPS (VEH-H)	OPERATING COST	PERFORMANCE INDEX	SPEED (KM/H)	TOTAL FUEL CONSUM (L/H)
1537.56	189.70	34.30	111.39	145.77	101.17	2665.8(532)	606.51	779.62	114.90	8.16	<TOTALS>

NOTE: PERFORMANCE INDEX IS DEFINED AS:

PI = DELAY + STOPS

NO. OF SIMULATIONS = 17 NO. OF LINKS = 265 ELAPSED TIME = 2392.3 SEC.

1 PRINCE SIMAR STREET

LINE CARO
NO. TYPE

563 90

--- PROGRAM NOTE --- END OF JOB!

CYCLE: 125 SECONDS, 60 STEPS PAGE 15

TERMINATION CARD

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0